

D/A Converters Standard 8bit 2ch · 3ch Type

BH2219FVM BH2220FVM

General Description

The BH2219FVM and BH2220FVM are 8bit R-2R-type D/A converters with 2 and 3 channels, respectively. A compact package allows adjacent placement, thereby eliminating deterioration of the D/A converter due to wire pattern. Furthermore, a built-in RESET function ensures that the output voltage at all channels is Low during power up. A broad power supply voltage range (2.7V-5.5V) is available, providing design flexibility.

Features

- Compact package enabling adjacent placement
- Built-in RESET function
- High speed output response characteristics
- 3-line serial interface

Applications

DVCs, DSCs, DVDs, CD-Rs, CD-RWs

Key Specifications

Package

 $W(Typ) \times D(Typ) \times H(Max)$



Lineup

Number of channels	Input method	Data latch method	Package		Orderable Part Number
2ch	01400	LD method	MSOP8	D1 -4 0000	BH2219FVM-TR
3ch	CMOS			Reel of 3000	BH2220FVM-TR

Pin Description and Block Diagram

(BH2219FVM)

(DUZZ19L	V IVI)	
Terminal	Terminal name	Function
1	AO1	An along a start to make al
2	AO2	Analog output terminal
3	TEST MONI	Test terminal (OPEN at normal use)
4	VCC	Power source terminal
5	GND	Ground terminal
6	DI	Serial data input terminal
7	CLK	Serial clock input terminal
8	LD	Serial data load input terminal

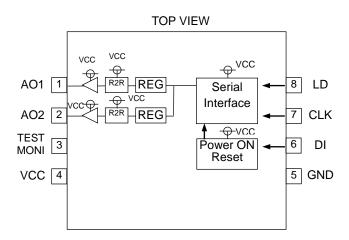


Figure 1. BH2219FVM

(BH2220FVM)

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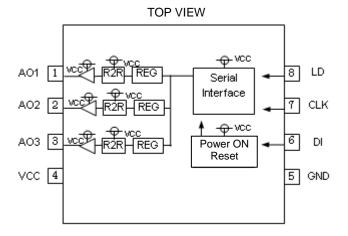


Figure 2. BH2220FVM

Absolute Maximum Ratings (Ta=25°C)

Parameter	Symbol	Limit	Unit	Remark
Power Source Voltage	Vcc	-0.3 to +7.0	V	-
Terminal Voltage	V _{IN}	-0.3 to V _{CC}	V	-
Storage Temperature Range	Tstg	-55 to +125	°C	-
Power Dissipation	Pd	0.47 (Note 1)	W	-

(Note 1) Derated at 4.7mW/C at Ta>25°C

Caution: Operating the IC over the absolute maximum ratings may damage the IC. The damage can either be a short circuit between pins or an open circuit between pins and the internal circuitry. Therefore, it is important to consider circuit protection measures, such as adding a fuse, in case the IC is operated over the absolute maximum ratings.

Recommended Operating Conditions (Ta=25°C)

oniniended operating conditions (1a=25 6)							
Dorometer	Cymhal		Limit		Linit	Remark	
Parameter	Symbol	Min	Тур	Max	Unit		
VCC Power Source Voltage	Vcc	2.7	-	5.5	V	-	
Terminal Input Voltage Range	Vin	0	-	Vcc	V	-	
Analog Output Current	Іоит	-1.0	-	+1.0	mA	-	
Action Temperature Range	Topr	-30	-	+85	°C	-	
Serial Clock Frequency	f _{SCLK}	-	1.0	10.0	MHz	-	
Limit Load Capacitance	CL	-	-	0.1	μF	-	

Electrical Characteristics

(Unless otherwise specified, Vcc=3.0V, RL=OPEN, CL=0pF, Ta=25°C)

Davamatar	Curaha al	Limit			l lmi4	0		
Parameter	Symbol	Min	Тур	Max	Unit	Conditions		
<current consumption=""></current>								
VCC System	Icc	-	0.4	0.8	mA	CLK=1MHz, 80H setting		
<logic interface=""></logic>								
L Input Voltage	V_{IL}	GND	-	0.2V _{CC}	V	-		
H Input Voltage	ViH	0.8Vcc	-	Vcc	V	-		
Input Current	I _{IN}	-10	-	+10	μA	-		
<buffer amplifier=""></buffer>								
Output Zara Saala Valtaga	Vzs1	GND	-	0.1	V	00H setting, at no load		
Output Zero Scale Voltage	Vzs2	GND	-	0.3	V	00H setting, I _{OH} =1.0mA		
Output Full Scale Voltage	V_{FS1}	Vcc-0.1	-	Vcc	V	FFH setting, at no load		
Output Full Scale Voltage	V _{FS2}	V _{CC} -0.3	-	Vcc	V	FFH setting, I _{OL} =1.0mA		
<d a="" converter="" precision=""></d>								
Differential Non Linearity Error	DNL	-1.0	-	+1.0	LSB	Input code 02H to FDH		
Integral Non Linearity Error	INL	-1.5	-	+1.5	LSB	Input code 02H to FDH		
VCC Power Source Voltage Rise Time	t_{rVCC}	100	-	-	μs	V _{CC} =0V to 2.7V		
Power ON Reset Release Voltage	V_{POR}	-	1.9	-	V	-		

Timing Chart

(Unless otherwise specified, $V_{CC} = 3.0V$, $Ta = 25^{\circ}C$)

Offices otherwise specified, VCC = 3.0 V, 1a = 23 O)						
Doromotor	Current ed		Limits		1.1:4	O and distance
Parameter	Symbol	Min	Тур	Max	Unit	Conditions
CLK L Level Time	tclkl	50	-	-	ns	-
CLK H Level Time	tclkh	50	-	-	ns	-
DI Setup Time	t _{sDI}	20	-	-	ns	-
DI Hold Time	t _{hDI}	40	-	-	ns	-
LD Setup Time	t _{sLD}	50	-	-	ns	-
LD Hold Time	t _{hLD}	50	-	-	ns	-
LD H Level Time	tLDH	50	-	-	ns	-
Output Settling Time	tout	-	-	100	μs	C _L =50pF, R _L =10kΩ

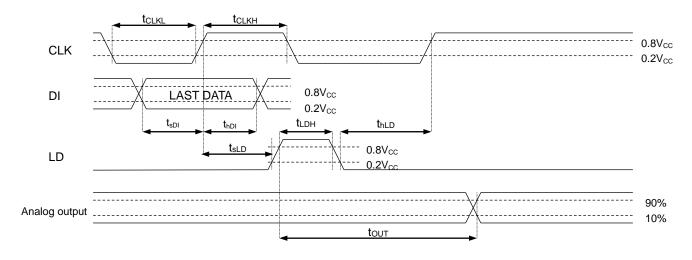


Figure 3

Typical Performance Curves

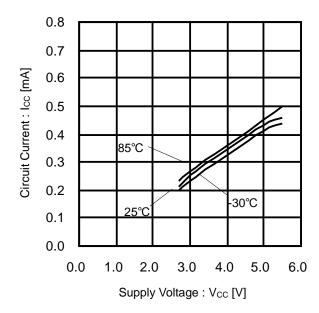


Figure 4. Circuit Current vs Supply Voltage (Active Current Consumption)

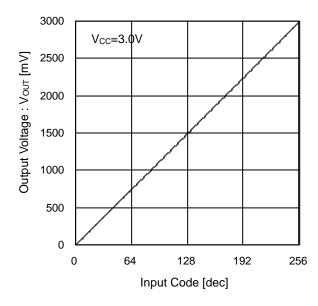


Figure 6. Output Voltage vs Input Code

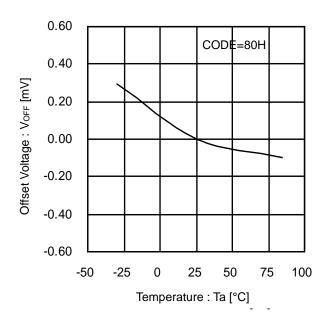


Figure 5. DC Offset Voltage vs Temperature

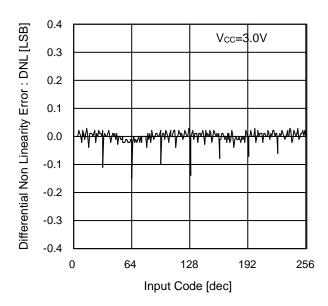


Figure 7. Differential Non Linearity Error vs Input Code

Typical Performance Curves - continued

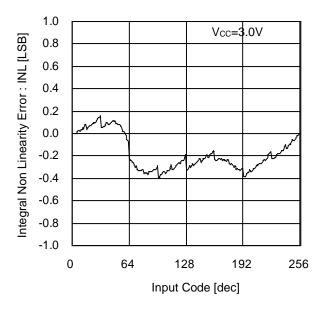


Figure 8. Integral Non Linearity Error vs Input Code

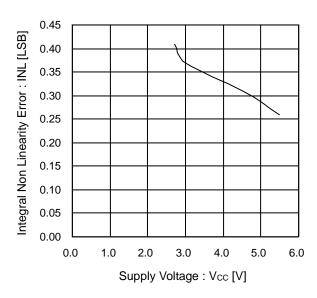


Figure 10. Integral Non Linearity Error vs Supply Voltage

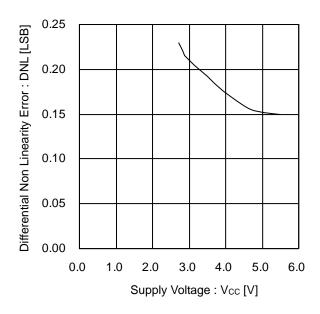


Figure 9. Differential Non Linearity Error vs Supply Voltage

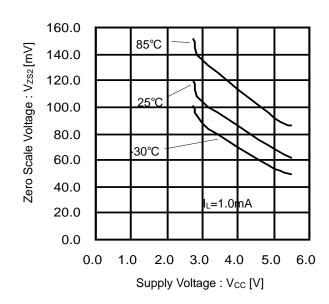


Figure 11. Output Zero Scale Voltage vs Supply Voltage

Typical Performance Curves - continued

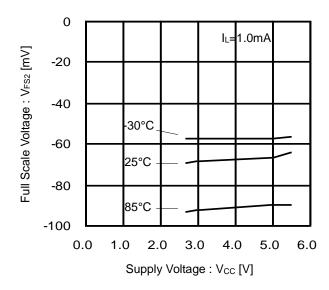


Figure 12. Output Full Scale Voltage vs Supply Voltage

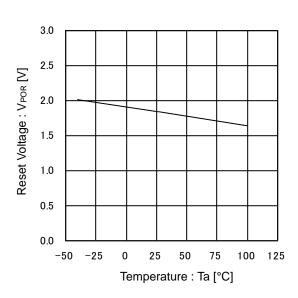


Figure 13. Reset Release Voltage vs Temperature

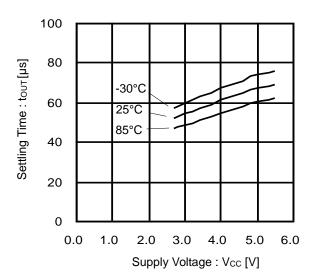


Figure 14. Settling Time vs Supply Voltage

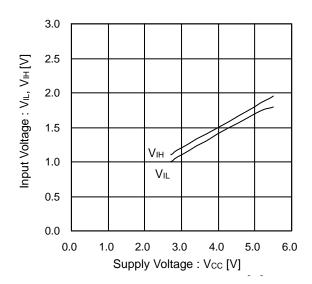


Figure 15. Input Voltage vs Supply Voltage

Application Information

Operation Description

The Serial Control Interface is 3-line serial interface 1) LD, 2) CLK and 3) DI. Every command is composed of 12 bits data sent through DI line (MSB first). DI data is read every rising edge of the CLK. That should be while LD is LOW. Last 12 bits of data are latched while LD is HIGH.

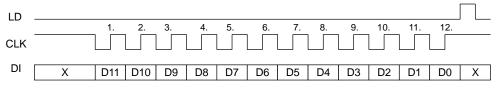


Figure 16

Data Settings

Data Cottingo								
D0	D1	D2	D3	D4	D5	D6	D7	Setting
0	0	0	0	0	0	0	0	GND
1	0	0	0	0	0	0	0	(V _{CC} -GND)/256x1
0	1	0	0	0	0	0	0	(Vcc-GND)/256x2
1	1	0	0	0	0	0	0	(Vcc-GND)/256x3
0	0	1	0	0	0	0	0	(V _{CC} -GND)/256x4
0	1	1	1	1	1	1	1	(V _{CC} -GND)/256x254
1	1	1	1	1	1	1	1	(Vcc-GND)/256x255

Channel Setting (BH2219FVM)

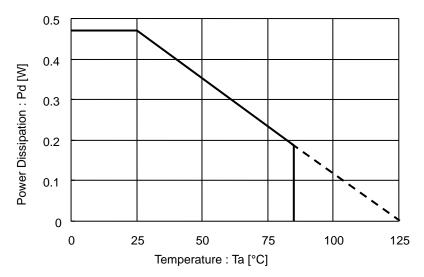
D8	D9	D10	D11	Setting
0	0	Х	Х	AO1
1	0	Х	Х	AO2
0	1	Х	Х	Not used
1	1	Х	Х	Not used

Channel setting (BH2220FVM)

D8	D9	D10	D11	Setting
0	0	Х	Х	AO1
1	0	Х	Х	AO2
0	1	Х	Х	AO3
1	1	Х	Х	Not used

Power Dissipation

· MSOP8



Board size: 70mm x 70mm x 1.6mm Material : FR4 glass epoxy board (copper foil area less than 3%)

I/O Equivalent Circuit

Terminal	Equivalent circuit	Terminal	Equivalent circuit
AO1 AO2 AO3	VCC VCC VCC GND GND	DI CLK LD	VCC VCC VCC GND GND

Operational Notes

1. Reverse Connection of Power Supply

Connecting the power supply in reverse polarity can damage the IC. Take precautions against reverse polarity when connecting the power supply, such as mounting an external diode between the power supply and the IC's power supply pins.

2. Power Supply Lines

Design the PCB layout pattern to provide low impedance supply lines. Separate the ground and supply lines of the digital and analog blocks to prevent noise in the ground and supply lines of the digital block from affecting the analog block. Furthermore, connect a capacitor to ground at all power supply pins. Consider the effect of temperature and aging on the capacitance value when using electrolytic capacitors.

3. Ground Voltage

Ensure that no pins are at a voltage below that of the ground pin at any time, even during transient condition.

4. Ground Wiring Pattern

When using both small-signal and large-current ground traces, the two ground traces should be routed separately but connected to a single ground at the reference point of the application board to avoid fluctuations in the small-signal ground caused by large currents. Also ensure that the ground traces of external components do not cause variations on the ground voltage. The ground lines must be as short and thick as possible to reduce line impedance.

5. Thermal Consideration

Should by any chance the power dissipation rating be exceeded the rise in temperature of the chip may result in deterioration of the properties of the chip. In case of exceeding this absolute maximum rating, increase the board size and copper area to prevent exceeding the Pd rating.

6. Recommended Operating Conditions

These conditions represent a range within which the expected characteristics of the IC can be approximately obtained. The electrical characteristics are guaranteed under the conditions of each parameter.

7. Inrush Current

When power is first supplied to the IC, it is possible that the internal logic may be unstable and inrush current may flow instantaneously due to the internal powering sequence and delays, especially if the IC has more than one power supply. Therefore, give special consideration to power coupling capacitance, power wiring, width of ground wiring, and routing of connections.

8. Operation Under Strong Electromagnetic Field

Operating the IC in the presence of a strong electromagnetic field may cause the IC to malfunction.

9. Testing on Application Boards

When testing the IC on an application board, connecting a capacitor directly to a low-impedance output pin may subject the IC to stress. Always discharge capacitors completely after each process or step. The IC's power supply should always be turned off completely before connecting or removing it from the test setup during the inspection process. To prevent damage from static discharge, ground the IC during assembly and use similar precautions during transport and storage.

10. Inter-pin Short and Mounting Errors

Ensure that the direction and position are correct when mounting the IC on the PCB. Incorrect mounting may result in damaging the IC. Avoid nearby pins being shorted to each other especially to ground, power supply and output pin. Inter-pin shorts could be due to many reasons such as metal particles, water droplets (in very humid environment) and unintentional solder bridge deposited in between pins during assembly to name a few.

11. Unused Input Pins

Input pins of an IC are often connected to the gate of a MOS transistor. The gate has extremely high impedance and extremely low capacitance. If left unconnected, the electric field from the outside can easily charge it. The small charge acquired in this way is enough to produce a significant effect on the conduction through the transistor and cause unexpected operation of the IC. So unless otherwise specified, unused input pins should be connected to the power supply or ground line.

Operational Notes - continued

12. Regarding the Input Pin of the IC

This monolithic IC contains P+ isolation and P substrate layers between adjacent elements in order to keep them isolated. P-N junctions are formed at the intersection of the P layers with the N layers of other elements, creating a parasitic diode or transistor. For example (refer to figure below):

When GND > Pin A and GND > Pin B, the P-N junction operates as a parasitic diode. When GND > Pin B, the P-N junction operates as a parasitic transistor.

Parasitic diodes inevitably occur in the structure of the IC. The operation of parasitic diodes can result in mutual interference among circuits, operational faults, or physical damage. Therefore, conditions that cause these diodes to operate, such as applying a voltage lower than the GND voltage to an input pin (and thus to the P substrate) should be avoided.

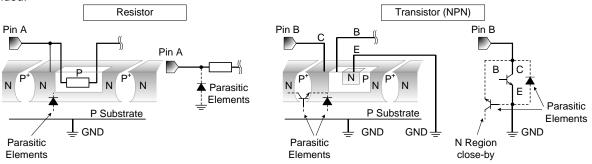
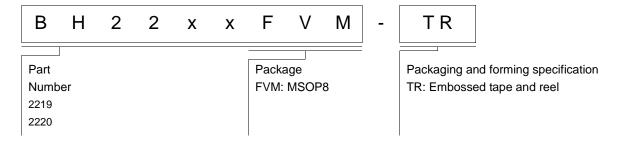


Figure 17. Example of monolithic IC structure

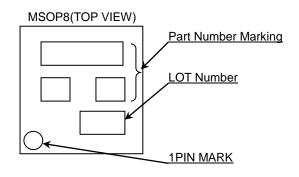
13. Reset Function

The power on reset circuit, which initializes internal settings, may malfunction during abrupt power ons. Therefore, set the time constant so as to satisfy the power source rise time.

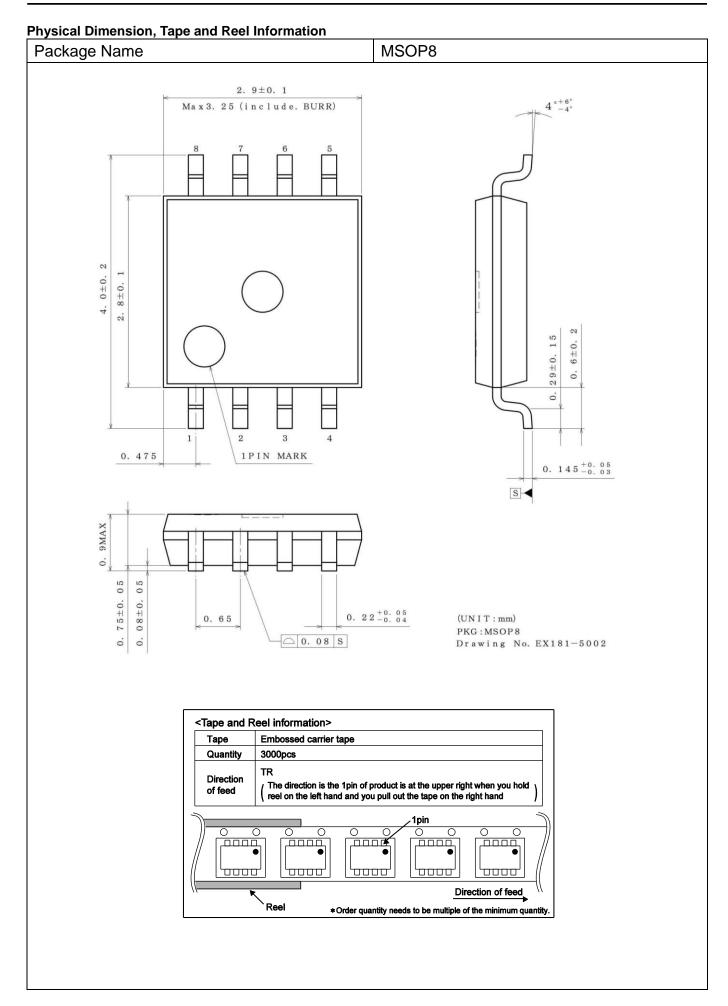
Ordering Information



Marking Diagram



Part Number	Part Number Marking
BH2219FVM-TR	H2219
BH2220FVM-TR	H2220



Revision History

Date	Revision	Changes
06.Nov.2015	001	New Release

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CLASSⅢ	CLASSIII	CLASSIIb	CLASSIII
CLASSIV	CLASSIII	CLASSⅢ	

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- 4. Use Products within the specified time after opening a humidity barrier bag. Baking is required before using Products of which storage time is exceeding the recommended storage time period.

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