

## Features

- Wide 4V to 30V Operating Input Range
- 3A Continuous Output Current
- Fixed 500KHz Switching Frequency
- No Schottky Diode Required
- Short Protection with Hiccup-Mode
- Built-in Over Current Limit
- Built-in Over Voltage Protection
- Internal Soft start
- Output Adjustable from 0.92V
- Integrated internal compensation
- Thermal Shutdown
- Available in ESOP8, SOT23 Package
- -40°C to +85°C Temperature Range

## Applications

- CCTV Camera
- Flat-Panel Television and Monitor
- Battery Charger
- Distributed Power Systems

## General Description

The HM1486 is a high frequency, synchronous, rectified, step-down, switch-mode converter with internal power MOSFETs. It offers a very compact solution to achieve a 4A peak output current over a wide input supply range, with excellent load and line regulation.

The HM1486 requires a minimal number of readily available, external components and is available in a space saving ESOP8 package.

## Typical Application Circuit

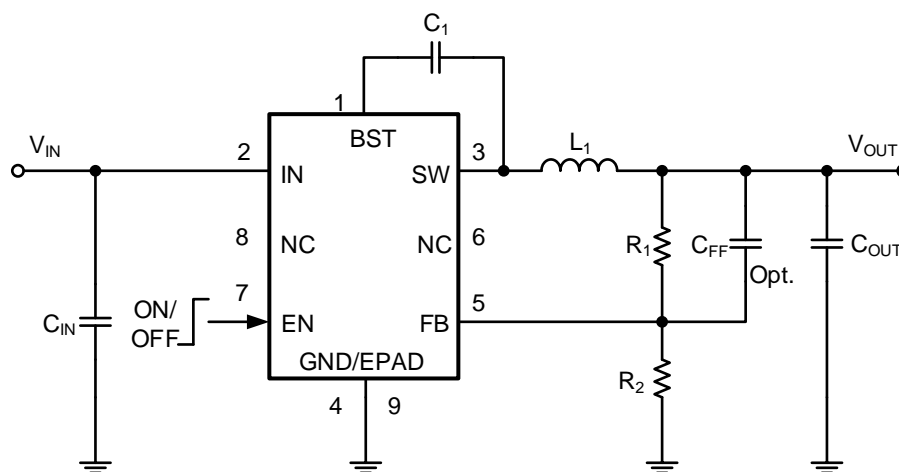
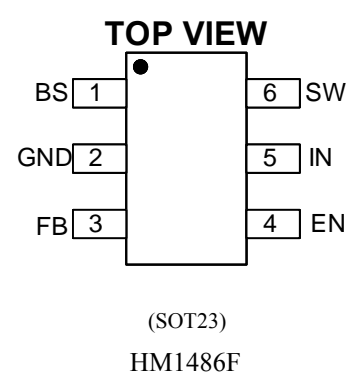
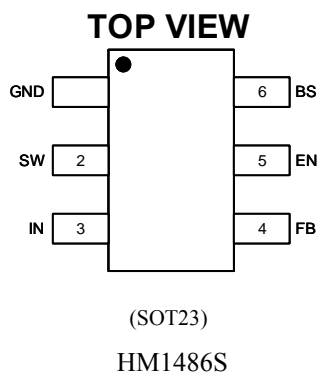
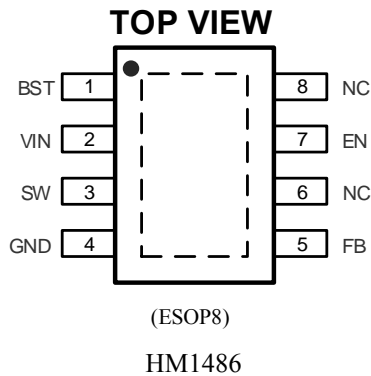


Figure 1. Basic Application Circuit

输入靠近芯片对地加电解电容与贴片电容104-105对地；  
C1用104，EN脚不用时用100K电阻上拉到输入端

## Pin Description

### Pin Configuration



系列型号	输入耐压	基准电压	频率	输出电流	封装
HM1486	30V	0.92V	500KHz	3A	ESOP8
HM1486S	30V	0.92V	600KHz	2A	SOT23-6
HM1486F	30V	0.92V	1.4MHz	1.2A	SOT23-6
HM1486D	40V	0.92V	500KHz	2.5A	ESOP8

## Pin Description

Pin	Name	Function
1	BST	Bootstrap. A capacitor connected between SW and BST pins is required to form a floating supply across the high-side switch driver.
2	VIN	Power Supply Pin
3	SW	Switching Pin
4/9	GND/EPAD	GROUND Pin
5	FB	Adjustable Version Feedback input. Connect FB to the center point of the external resistor divider
6	NC	
7	EN	Drive this pin to a logic-high to enable the IC. Drive to a logic-low to disable the IC and enter micro-power shutdown mode.
8	NC	

## Order Information

Marking	Part No.	Model	Description	Package	MOQ
HM1486	70301579	HM1486	Buck, 4-30V, 3.0A, 500KHz, VFB 0.92V, ESOP8	ESOP8	3000PCS

## Absolute Maximum Ratings

V <sub>IN</sub> , EN, Voltage .....	-0.3V to 36V	SW Voltage .....	-0.3V to (V <sub>IN</sub> +0.5V)
Operating Temperature Range .....	-40°C to +85°C	Storage Temperature Range .....	-65°C to 150°C
FB Voltages .....	-0.3 to 6V	BS Voltage .....	(V <sub>sw</sub> -0.3) to (V <sub>sw</sub> +5V)
Lead Temperature (Soldering, 10s) .....	+300°C	ESD (Machine Made) MM.....	200V
Thermal Resistance (θJA) .....	50 °C/W	ESD (Human Body Made) HMB.....	2KV
Thermal Resistance (θJC) .....	10 °C/W		

Note1: Exceeding these ratings may damage the device.

Note2: The device is not guaranteed to function outside of its operating conditions.

## Electrical Characteristics

(V<sub>IN</sub>=12V, V<sub>OUT</sub>=5V, T<sub>A</sub> = 25°C, unless otherwise noted.)

Parameter	Test Conditions	Min	Typ	Max	Unit
Input Voltage Range		4		30	V
Supply Current in Operation	V <sub>EN</sub> =3.0V, V <sub>FB</sub> =1.1V		0.4	0.6	mA
Supply Current in Shutdown	V <sub>EN</sub> =0 or EN = GND			1	μA
Regulated Feedback Voltage	T <sub>A</sub> = 25°C, 4V ≤ V <sub>IN</sub> ≤ 18V		0.92		V
High-Side Switch On-Resistance			130		mΩ
Low-Side Switch On-Resistance			100		mΩ
High-Side Switch Leakage Current	V <sub>EN</sub> =0V, V <sub>SW</sub> =12V			1	uA
Upper Switch Current Limit	Minimum Duty Cycle	4			A
Oscillation Frequency			0.50		MHz
Maximum Duty Cycle	V <sub>FB</sub> =0.92V			92	%
Minimum On-Time			80		nS
Minimum Off-Time			150		nS
Soft Start				1.2	mS
Thermal Shutdown			160		°C
Thermal Hysteresis			20		°C

Note1: 100% production test at +25°C. Specifications over the temperature range are guaranteed by design and characterization.

Note2: Dynamic supply current is higher due to the gate charge being delivered at the switching frequency.

## Functional Application Circuit

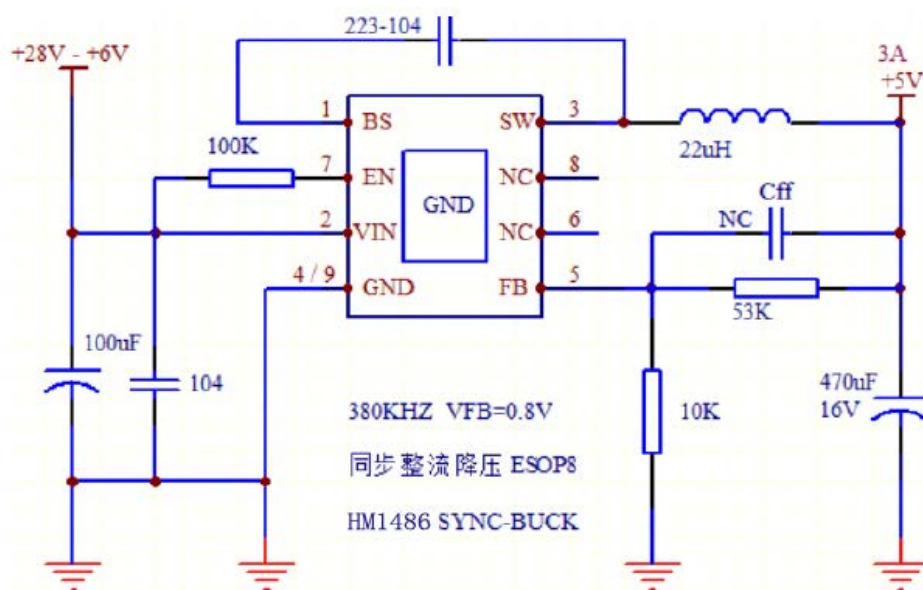


Figure 2. HM1486 Application Circuit

## Functions Description

### Internal Regulator

The HM1486 is a current mode step down DC/DC converter that provides excellent transient response with no extra external compensation components. This device contains an internal, low resistance, high voltage power MOSFET, and operates at a high 500K operating frequency to ensure a compact, high efficiency design with excellent AC and DC performance.

### Error Amplifier

The error amplifier compares the FB pin voltage with the internal FB reference (VFB) and outputs a current proportional to the difference between the two. This output current is then used to charge or discharge the internal compensation network to form the COMP voltage, which is used to control the power MOSFET current. The optimized internal compensation network minimizes the external component counts and simplifies the control loop design.

### Internal Soft-Start

The soft-start is implemented to prevent the converter output voltage from overshooting during startup. When the chip starts, the internal circuitry generates a soft-start voltage (SS) ramping up from 0V to 0.92V. When it is lower than the internal reference (REF), SS overrides REF so the error amplifier uses SS as the reference. When SS is higher than REF, REF regains control. The SS time is internally fixed to 1.2ms.

## Over Current Protection & Hiccup

The HM1486 has cycle-by-cycle over current limit when the inductor current peak value exceeds the set current limit threshold. Meanwhile, output voltage starts to drop until FB is below the Under-Voltage (UV) threshold, typically 25% below the reference. Once a UV is triggered, the HM1486 enters hiccup mode to periodically restart the part. This protection mode is especially useful when the output is dead-short to ground. The average short circuit current is greatly reduced to alleviate the thermal issue and to protect the regulator. The HM1486 exits the hiccup mode once the over current condition is removed.

## Startup and Shutdown

If both VIN and EN are higher than their appropriate thresholds, the chip starts. The reference block starts first, generating stable reference voltage and currents, and then the internal regulator is enabled. The regulator provides stable supply for the remaining circuitries. Three events can shut down the chip: EN low, VIN low and thermal shutdown. In the shutdown procedure, the signaling path is first blocked to avoid any fault triggering. The COMP voltage and the internal supply rail are then pulled down. The floating driver is not subject to this shutdown command.

## Applications Information

### Setting the Output Voltage

HM1486 require an input capacitor, an output capacitor and an inductor. These components are critical to the performance of the device. HM1486 are internally compensated and do not require external components to achieve stable operation. The output voltage can be programmed by resistor divider.

$$V_{OUT} = V_{FEEDBACK} \times \frac{R1 + R2}{R2}$$

V <sub>OUT</sub>	R1	R2	L1 <sub>MIN</sub>	L1 <sub>TYP</sub>	L1 <sub>MAX</sub>	C <sub>IN</sub>	C <sub>OUT</sub>
1V	12.5KΩ	50KΩ	2.2μH	2.2μH	4.7μH	20-47uF	20-68uF
1.05V	15.62KΩ	50KΩ	2.2μH	2.2μH	4.7μH	20-47uF	20-68uF
1.2V	25KΩ	50KΩ	2.2μH	2.2μH	4.7μH	20-47uF	20-68uF
1.5V	43.75KΩ	50KΩ	2.2μH	2.2μH	4.7μH	20-47uF	20-68uF
3.3V	156.25KΩ	50KΩ	3.3μH	3.3μH	4.7μH	20-47uF	20-68uF
5.0V	262.5KΩ	50KΩ	3.3μH	4.7μH	4.7μH	20-47uF	20-68uF

For HM1486S and HM1486F application

## Selecting the Inductor

The recommended inductor values are shown in the Application Diagram. It is important to guarantee the inductor core does not saturate during any foreseeable operational situation. The inductor should be rated to handle the peak load current plus the ripple current. Care should be taken when reviewing the different saturation current ratings that are specified by different manufacturers. Saturation current ratings are typically specified at 25°C, so ratings at maximum ambient temperature of the application should be requested from the manufacturer.

$$L = \frac{V_{out} \times (V_{in} - V_{out})}{V_{in} \times \Delta I_L \times f_{OSC}}$$

Where  $\Delta I_L$  is the inductor ripple current. Choose inductor ripple current to be approximately 30% of the maximum load current, 3A. The maximum inductor peak current is:

$$I_{L(MAX)} = I_{LOAD} + \frac{\Delta I_L}{2}$$

Under light load conditions below 100mA, larger inductance is recommended for improved efficiency.

## Selecting the Output Capacitor

Special attention should be paid when selecting these components. The DC bias of these capacitors can result in a capacitance value that falls below the minimum value given in the recommended capacitor specifications table.

The ceramic capacitor's actual capacitance can vary with temperature. The capacitor type X7R, which operates over a temperature range of -55°C to +125°C, will only vary the capacitance to within ±15%. The capacitor type X5R has a similar tolerance over a reduced temperature range of -55°C to +85°C. Many large value ceramic capacitors, larger than 1µF are manufactured with Z5U or Y5V temperature characteristics. Their capacitance can drop by more than 50% as the temperature varies from 25°C to 85°C. Therefore X5R or X7R is recommended over Z5U and Y5V in applications where the ambient temperature will change significantly above or below 25°C.

Tantalum capacitors are less desirable than ceramic for use as output capacitors because they are more expensive when comparing equivalent capacitance and voltage ratings in the 0.47µF to 44µF range. Another important consideration is that tantalum capacitors have higher ESR values than equivalent size ceramics. This means that while it may be possible to find a tantalum capacitor with an ESR value within the stable range, it would have to be larger in capacitance (which means bigger and more costly) than a ceramic capacitor with the same ESR value. It should also be noted that the ESR of a typical tantalum will increase about 2:1 as the temperature goes from 25°C down to -40°C, so some guard band must be allowed.

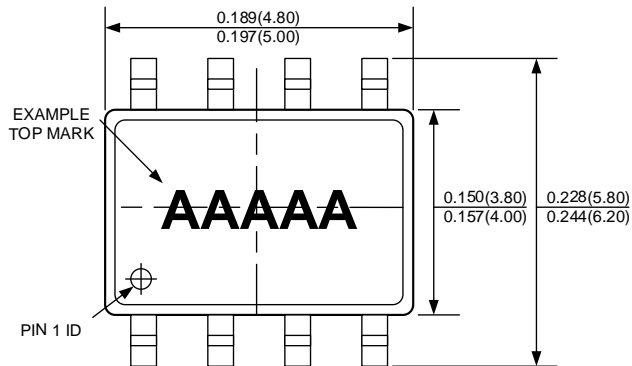
## PC Board Layout Consideration

PCB layout is very important to achieve stable operation. It is highly recommended to duplicate EVB layout for optimum performance. If change is necessary, please follow these guidelines and take Figure 4 for reference.

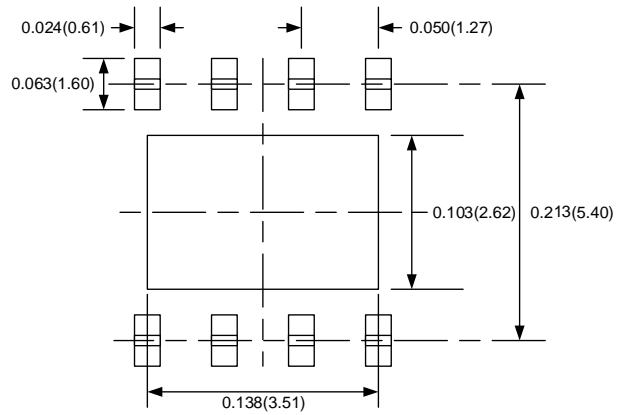
1. Keep the path of switching current short and minimize the loop area formed by Input capacitor, high-side MOSFET and low-side MOSFET.
2. Bypass ceramic capacitors are suggested to be put close to the Vin Pin.
3. Ensure all feedback connections are short and direct. Place the feedback resistors and compensation components as close to the chip as possible.
4. VOUT, SW away from sensitive analog areas such as FB.
5. Connect IN, SW, and especially GND respectively to a large copper area to cool the chip to improve thermal performance and long-term reliability.

## Package Description

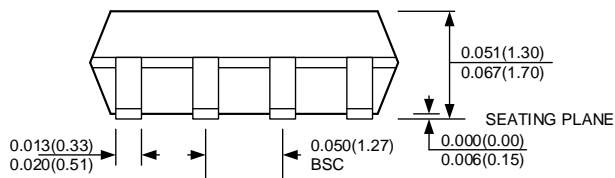
### ESOP8 (EXPOSED PAD)



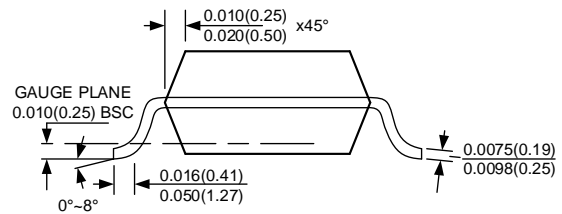
**TOP VIEW**



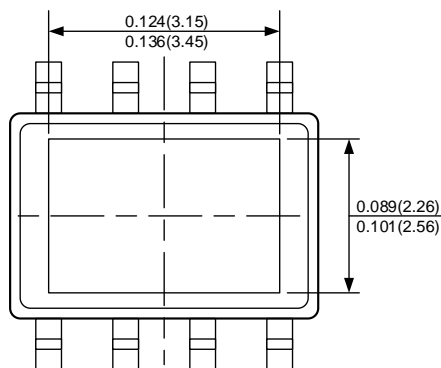
**RECOMMENDED PAD LAYOUT**



**FRONT VIEW**



**SIDE VIEW**



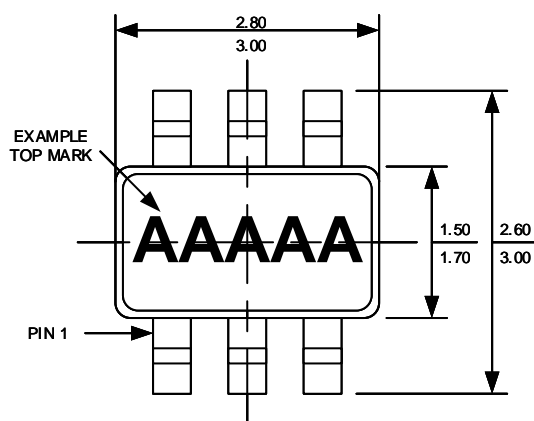
**BOTTOM VIEW**

#### NOTE:

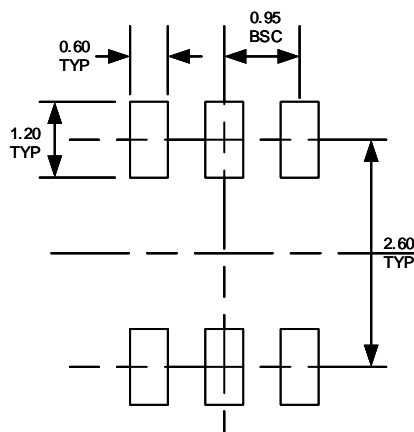
1. CONTROL DIMENSION IS IN INCHES. DIMENSION IN BRACKET IS IN MILLIMETERS.
2. PACKAGE LENGTH DOES NOT INCLUDE MOLD FLASH, PROTRUSIONS OR GATE BURRS.
3. PACKAGE WIDTH DOES NOT INCLUDE INTERLEAD FLASH OR PROTRUSIONS.
4. LEAD COPLANARITY (BOTTOM OF LEADS AFTER FORMING) SHALL BE 0.004" INCHES MAX.
5. DRAWING CONFORMS TO JEDEC MS-012, VARIATION BA.
6. DRAWING IS NOT TO SCALE.

## Package Description

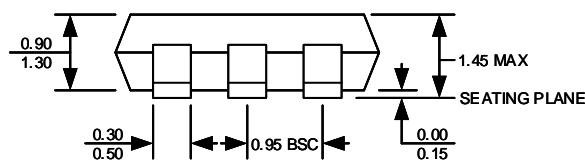
### SOT23-6



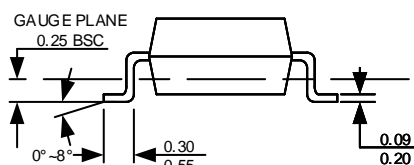
**TOP VIEW**



**RECOMMENDED PAD LAYOUT**



**FRONT VIEW**



**SIDE VIEW**