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FSB50550A / FSB50550AT

Motion SPM® 5 系列

特性

- 通过 UL 第 E209204 号认证 (UL1557)
- 500 V $R_{DS(on)} = 1.4 \Omega$ (最大值) FRFET MOSFET 三相逆变器, 带有栅极驱动器和保护功能
- 内置自举二极管以简化印刷电路板布局
- 低端 MOSFET 的三个独立开源引脚用于三相电流感测
- 高电平有效接口, 可用于 3.3 / 5 V 逻辑电平, 施密特触发脉冲输入
- 针对低电磁干扰进行优化
- 内置于 HVIC 的温度感测
- 用于栅极驱动和欠压保护的 HVIC
- 绝缘等级: 1500 V_{rms} / 分钟
- 符合 RoHS 标准

应用

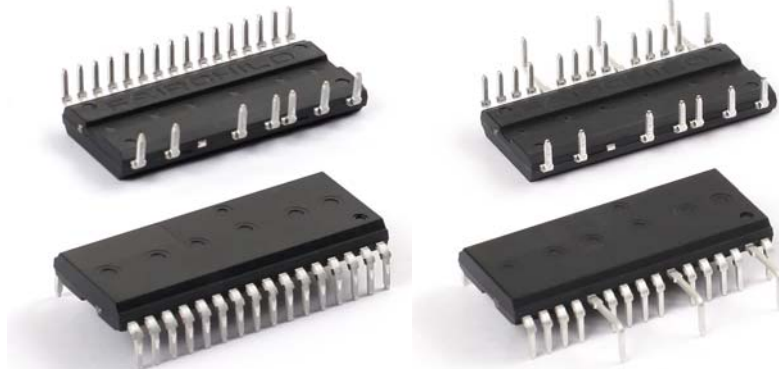
- 小功率交流电机驱动器的三相逆变器驱动

相关资料

- [RD-FSB50450A - Reference Design for Motion SPM 5 Series Ver.2](#)
- [AN-9082 - Motion SPM5 Series Thermal Performance by Contact Pressure](#)
- [AN-9080 - User's Guide for Motion SPM 5 Series V2](#)

概述

FSB50550A/AT 是一款先进的 Motion SPM® 5 模块, 为交流感应、无刷直流电机和 PMSM 电机提供非常全面的高性能逆变器输出平台。这些模块综合优化了内置 MOSFETs (FRFET® 技术) 的栅极驱动以最小化电磁干扰和能量损耗。同时也提供多重模组保护特性, 集成欠压闭锁和热量监测。内置的高速 HVIC 只需要一个单电源电压, 将逻辑电平栅极输入转化为适合驱动模块内部 MOSFET 的高电压, 高电流驱动信号。独立的开源 MOSFET 端子在每个相位均有效, 可支持大量不同种类的控制算法。



FSB50550A

FSB50550AT

封装标识与定购信息

| 器件 | 器件标识 | 封装 | 包装类型 | 数量 |
|------------|------------|-----------|------|----|
| FSB50550A | FSB50550A | SPM5P-023 | Rail | 15 |
| FSB50550AT | FSB50550AT | SPM5N-023 | Rail | 15 |

绝对最大额定值

逆变器部分 (单个 MOSFET, 除非另有说明。)

| 符号 | 参数 | 工作条件 | 额定值 | 单位 |
|--------------|----------------------|---|------|-----------|
| V_{DSS} | 单个 MOSFET 的漏极 - 源极电压 | | 500 | V |
| * $I_{D 25}$ | 单个 MOSFET 的漏极持续电流 | $T_C = 25^\circ\text{C}$ | 2.0 | A |
| * $I_{D 80}$ | 单个 MOSFET 的漏极持续电流 | $T_C = 80^\circ\text{C}$ | 1.5 | A |
| * I_{DP} | 单个 MOSFET 的漏极峰值电流 | $T_C = 25^\circ\text{C}$, $PW < 100 \mu\text{s}$ | 5 | A |
| * I_{DRMS} | 单个 MOSFET 的漏极电流有效值 | $T_C = 80^\circ\text{C}$, $F_{PWM} < 20 \text{ kHz}$ | 1.1 | A_{rms} |
| * P_D | 最大功耗 | $T_C = 25^\circ\text{C}$, 单个 MOSFET | 14.5 | W |

控制部分 (单个 HVIC, 除非另有说明。)

| 符号 | 参数 | 工作条件 | 额定值 | 单位 |
|----------|--------|-----------------------|--------------------------|----|
| V_{CC} | 控制电源电压 | 施加在 V_{CC} 和 COM 之间 | 20 | V |
| V_{BS} | 高端偏压 | 施加在 V_B 和 V_S 之间 | 20 | V |
| V_{IN} | 输入信号电压 | 施加在 V_{IN} 和 COM 之间 | $-0.3 \sim V_{CC} + 0.3$ | V |

自举二极管部分 (单个自举二极管, 除非另有说明。)

| 符号 | 参数 | 工作条件 | 额定值 | 单位 |
|-------------|-----------|--|-----|----|
| V_{RRMB} | 最大重复反向电压 | | 500 | V |
| * I_{FB} | 正向电流 | $T_C = 25^\circ\text{C}$ | 0.5 | A |
| * I_{FPB} | 正向电流 (峰值) | $T_C = 25^\circ\text{C}$, 脉冲宽度小于 1 ms | 1.5 | A |

热阻

| 符号 | 参数 | 工作条件 | 额定值 | 单位 |
|-----------------|------------|--------------------------|-----|---------------------------|
| $R_{\theta JC}$ | 结点 - 壳体的热阻 | 逆变器工作条件下的单个 MOSFET (注 1) | 8.6 | $^\circ\text{C}/\text{W}$ |

整个系统

| 符号 | 参数 | 工作条件 | 额定值 | 单位 |
|-----------|------|------------------------------|----------------|------------------|
| T_J | 工作结温 | | $-40 \sim 150$ | $^\circ\text{C}$ |
| T_{STG} | 存储温度 | | $-40 \sim 125$ | $^\circ\text{C}$ |
| V_{ISO} | 绝缘电压 | 60 Hz, 正弦波形, 1 分钟, 连接陶瓷基板到引脚 | 1500 | V_{rms} |

注:

- 关于壳体温度 (T_C) 的测量点, 参见图 4。
- 标记为 "*" 的为计算值或设计因素。

引脚描述

| 引脚号 | 引脚名 | 引脚描述 |
|-----|---------------|--------------------------|
| 1 | COM | IC 公共电源接地 |
| 2 | $V_{B(U)}$ | U 相高端 MOSFET 驱动的偏压 |
| 3 | $V_{CC(U)}$ | U 相 IC 和低端 MOSFET 驱动的偏压 |
| 4 | $IN_{(UH)}$ | U 相高端的信号输入 |
| 5 | $IN_{(UL)}$ | U 相低端的信号输入 |
| 6 | N.C | 无连接 |
| 7 | $V_{B(V)}$ | V 相高端 MOSFET 驱动的偏压 |
| 8 | $V_{CC(V)}$ | V 相 IC 和 低端 MOSFET 驱动的偏压 |
| 9 | $IN_{(VH)}$ | V 相高端的信号输入 |
| 10 | $IN_{(VL)}$ | V 相低端的信号输入 |
| 11 | V_{TS} | HVIC 温度感测输出 |
| 12 | $V_{B(W)}$ | W 相高端 MOSFET 驱动的偏压 |
| 13 | $V_{CC(W)}$ | W 相 IC 和 低端 MOSFET 驱动的偏压 |
| 14 | $IN_{(WH)}$ | W 相高端的信号输入 |
| 15 | $IN_{(WL)}$ | W 相低端的信号输入 |
| 16 | N.C | 无连接 |
| 17 | P | 直流输入正端 |
| 18 | $U, V_{S(U)}$ | 高端 MOSFET 驱动的 U 相偏压接地输出 |
| 19 | N_U | U 相的直流输入负端 |
| 20 | N_V | V 相的直流输入负端 |
| 21 | $V, V_{S(V)}$ | 高端 MOSFET 驱动的 V 相偏压接地输出 |
| 22 | N_W | W 相的直流输入负端 |
| 23 | $W, V_{S(W)}$ | 高端 MOSFET 驱动的 W 相偏压接地输出 |

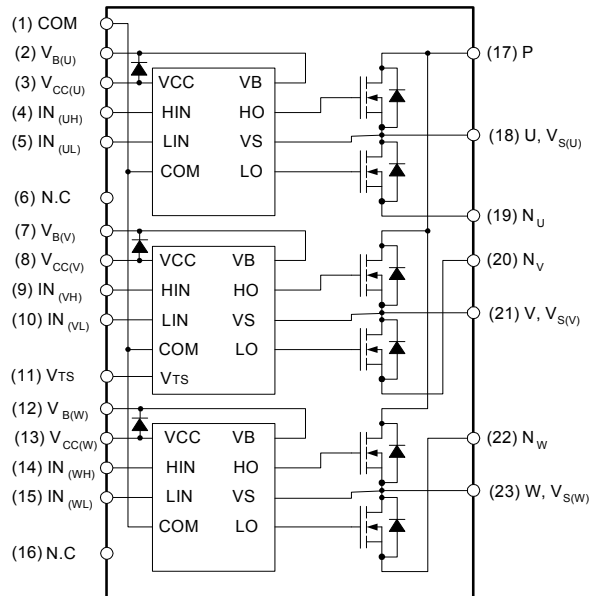


图 1. 引脚布局和内部框图（仰视图）

注：

3. 每个低端 MOSFET 的源极端子与 Motion SPM® 5 中的电源接地或偏压接地不连接。外部连接应当如图 3 所示。

电气特性 ($T_J = 25^\circ\text{C}$, $V_{CC} = V_{BS} = 15\text{V}$, 除非另有说明。)**逆变器部分** (单个 MOSFET, 除非另有说明。)

| 符号 | 参数 | 工作条件 | 最小值 | 典型值 | 最大值 | 单位 |
|--------------|----------------|---|------|-----|-----|---------------|
| BV_{DSS} | 漏极 - 源极击穿电压 | $V_{IN} = 0\text{V}$, $I_D = 1\text{mA}$ (注 1) | 500 | - | - | V |
| I_{DSS} | 零栅极电压漏极电流 | $V_{IN} = 0\text{V}$, $V_{DS} = 500\text{V}$ | - | - | 1 | mA |
| $R_{DS(on)}$ | 漏极至源极静态导通电阻 | $V_{CC} = V_{BS} = 15\text{V}$, $V_{IN} = 5\text{V}$, $I_D = 1.2\text{A}$ | - | 1.0 | 1.4 | Ω |
| V_{SD} | 漏极 - 源极二极管正向电压 | $V_{CC} = V_{BS} = 15\text{V}$, $V_{IN} = 0\text{V}$, $I_D = -1.2\text{A}$ | - | - | 1.2 | V |
| t_{ON} | 开关时间 | $V_{PN} = 300\text{V}$, $V_{CC} = V_{BS} = 15\text{V}$, $I_D = 1.2\text{A}$ $V_{IN} = 0\text{V} \leftrightarrow 5\text{V}$, 电感负载 $L = 3\text{mH}$ 高端和低端 MOSFET 开关 (注 2) | - | 600 | - | ns |
| t_{OFF} | | | - | 500 | - | ns |
| t_{rr} | | | - | 100 | - | ns |
| E_{ON} | | | - | 60 | - | μJ |
| E_{OFF} | | | - | 10 | - | μJ |
| RBSOA | 反向偏压安全工作区 | $V_{PN} = 400\text{V}$, $V_{CC} = V_{BS} = 15\text{V}$, $I_D = I_{DP}$, $V_{DS} = BV_{DSS}$, $T_J = 150^\circ\text{C}$ 高端和低端 MOSFET 开关 (注 3) | 整个区域 | | | |

控制部分 (单个 HVIC, 除非另有说明。)

| 符号 | 参数 | 工作条件 | 最小值 | 典型值 | 最大值 | 单位 |
|------------|---------------|---|-----|-----|-----|---------------|
| I_{QCC} | V_{CC} 静态电流 | $V_{CC} = 15\text{V}$, $V_{IN} = 0\text{V}$ | - | - | 200 | μA |
| I_{QBS} | V_{BS} 静态电流 | $V_{BS} = 15\text{V}$, $V_{IN} = 0\text{V}$ | - | - | 100 | μA |
| UV_{CCD} | 低端欠压保护 (图 8) | V_{CC} 欠压保护检测电平 | 7.4 | 8.0 | 9.4 | V |
| UV_{CCR} | | V_{CC} 欠压保护复位电平 | 8.0 | 8.9 | 9.8 | V |
| UV_{BSD} | 高端欠压保护 (图 9) | V_{BS} 欠压保护检测电平 | 7.4 | 8.0 | 9.4 | V |
| UV_{BSR} | | V_{BS} 欠压保护复位电平 | 8.0 | 8.9 | 9.8 | V |
| V_{TS} | HVIC 温度感测电压输出 | $V_{CC} = 15\text{V}$, $T_{HVIC} = 25^\circ\text{C}$ (注 4) | 600 | 790 | 980 | mV |
| V_{IH} | 导通阈值电压 | 逻辑高电平 | - | - | 2.9 | V |
| V_{IL} | 关断阈值电压 | 逻辑低电平 | 0.8 | - | - | V |

自举二极管部分 (单个自举二极管, 除非另有说明。)

| 符号 | 参数 | 工作条件 | 最小值 | 典型值 | 最大值 | 单位 |
|----------|--------|--|-----|-----|-----|----|
| V_{FB} | 正向电压 | $I_F = 0.1\text{A}$, $T_C = 25^\circ\text{C}$ (注 5) | - | 2.5 | - | V |
| t_{rB} | 反向恢复时间 | $I_F = 0.1\text{A}$, $T_C = 25^\circ\text{C}$ | - | 80 | - | ns |

注:

- BV_{DSS} 是 Motion SPM® 5 产品中的单个 MOSFET 的漏极和源极端子之间的绝对最大额定电压。考虑到寄生电感, V_{PN} 应远低于该值, 因此 V_{PN} 在任何情况下不得超过 BV_{DSS} 。
- t_{ON} 和 t_{OFF} 包括内部驱动 IC 的传输延迟。所列出的数值是在实验室测试条件下测得, 在实际应用中因为印刷电路板和布线的差异, 数值也会有所不同。请参阅图 6 介绍的开关时间定义, 以及图 7 中的开关测试电路。
- 每个 MOSFET 在开关工作时的峰值电流和电压也应在安全工作区 (SOA) 的范围内。请参阅图 7 中的 RBSOA 测试电路, 它与开关测试电路相同。
- V_{IS} 只能用作模块的温度感测, 但不能自动关闭 MOSFETs。
- 内置自举二极管其阻抗特性约为 15Ω 。请参阅图 2。

推荐工作条件

| 符号 | 参数 | 工作条件 | 最小值 | 典型值 | 最大值 | 单位 |
|---------------|-------------|--|------|------|----------|---------------|
| V_{PN} | 电源电压 | 施加在 P 和 N 之间 | - | 300 | 400 | V |
| V_{CC} | 控制电源电压 | 施加在 V_{CC} 和 COM 之间 | 13.5 | 15.0 | 16.5 | V |
| V_{BS} | 高端偏压 | 施加在 V_B 和 V_S 之间 | 13.5 | 15.0 | 16.5 | V |
| $V_{IN(ON)}$ | 输入导通阈值电压 | 施加在 V_{IN} 和 COM 之间 | 3.0 | - | V_{CC} | V |
| $V_{IN(OFF)}$ | 输入关断阈值电压 | | 0 | - | 0.6 | V |
| t_{dead} | 防止桥臂直通的死区时间 | $V_{CC} = V_{BS} = 13.5 \sim 16.5 \text{ V}, T_J \leq 150^\circ\text{C}$ | 1 | - | - | μs |
| f_{PWM} | PWM 开关频率 | $T_J \leq 150^\circ\text{C}$ | - | 15 | - | kHz |

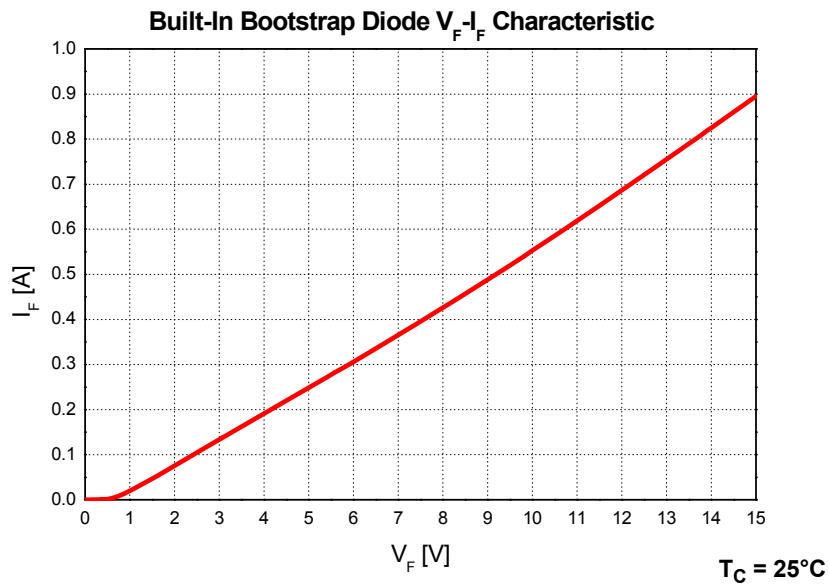


图 2. 内置自举二极管特性 (典型值)

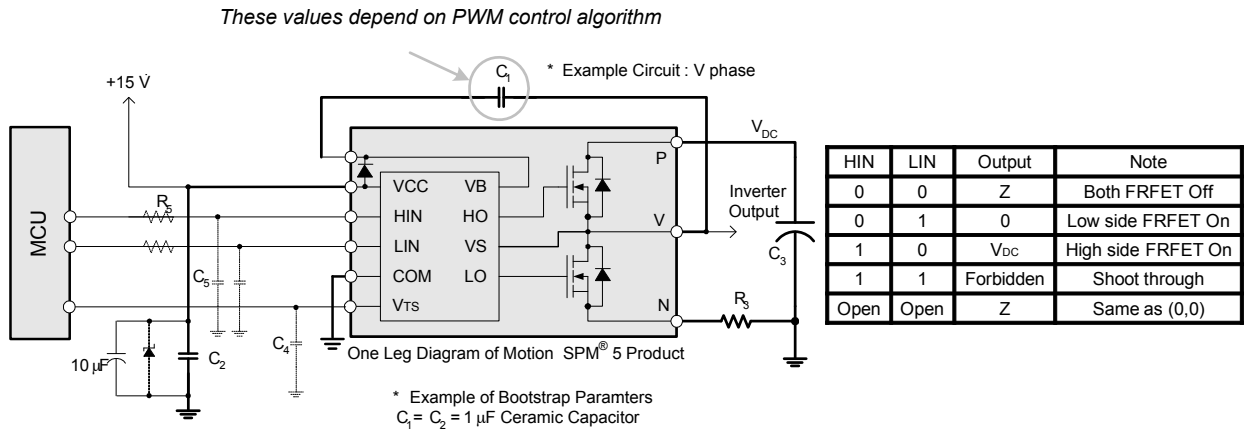


图 3. 推荐的 MCU 接口和自举电路及其参数

注:

1. 自举电路的参数取决于 PWM 算法。上述为开关频率为 15 kHz 时的参数的典型例子。
2. Motion SPM 5 产品和 MCU (虚线显示部分) 的每个输入端的 RC 耦合 (R₅ 和 C₅) 和 C₄, 可用于防止由浪涌噪声产生的错误信号。
3. 印刷电路板图形中的粗线应尽量短且粗, 以减少电路中的寄生电感, 从而导致浪涌电压的降低。旁路电容 C₁, C₂ 和 C₃ 应具有良好的高频特性, 以吸收高频纹波电流。

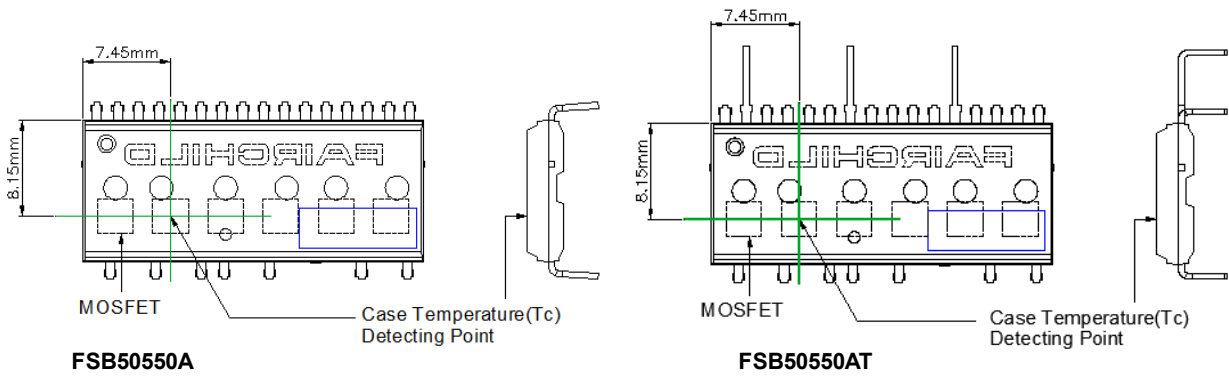


图 4. 壳体温度测量

注:

4. 将热电偶贴在 SPM 5 封装 (如果应用到, 放在 SPM 5 封装和散热片中间) 的散热片的顶部, 以获得正确的温度测量数值。

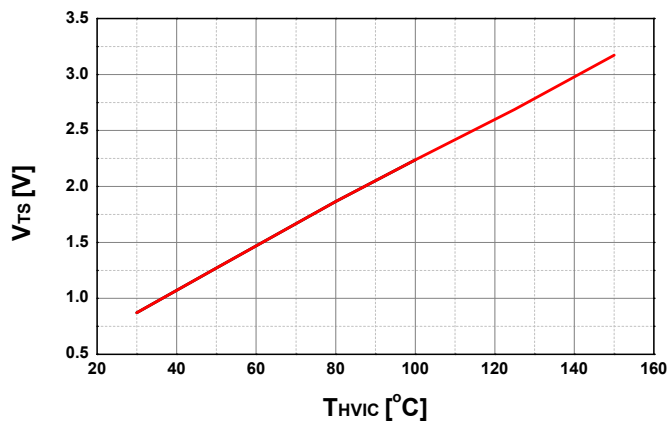


图 5. V_{TS} 的温度曲线 (典型值)

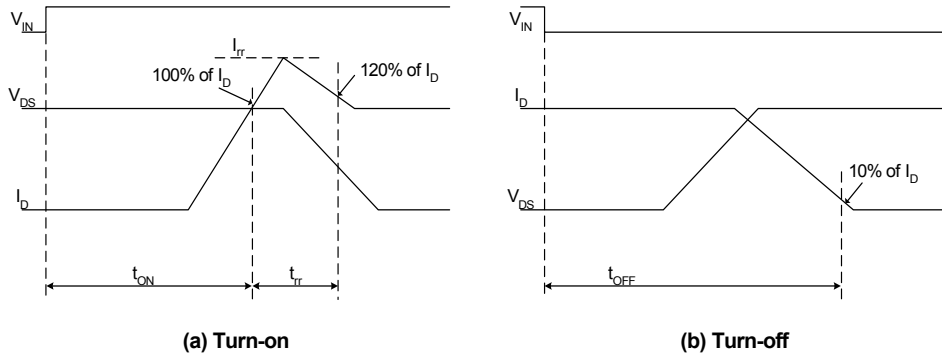


图 6. 开关时间定义

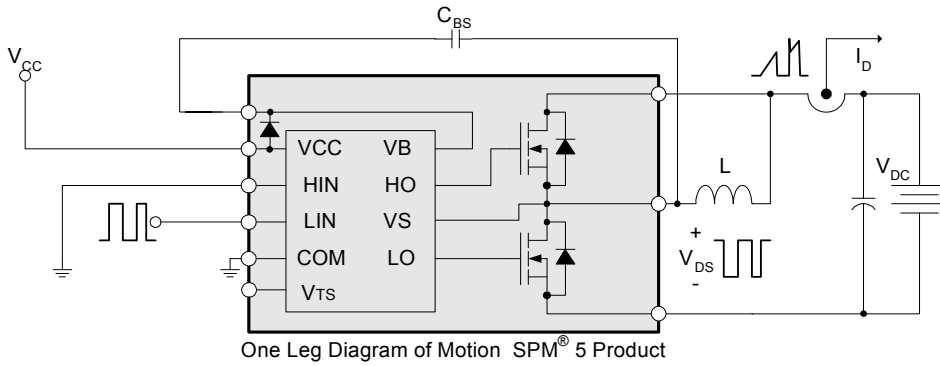


图 7. 开关和 RBSOA (单脉冲) 测试电路 (低端)

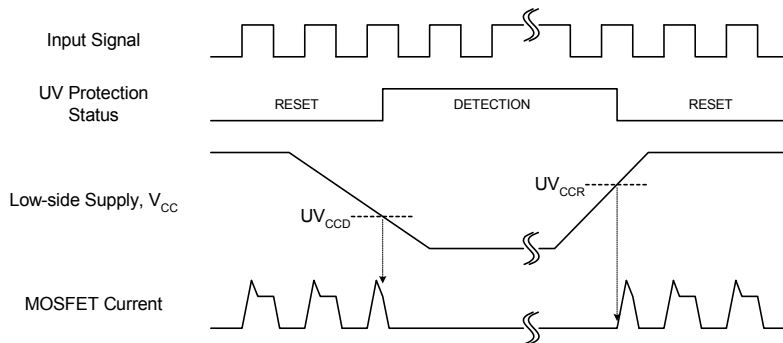


图 8. 欠压保护 (低端)

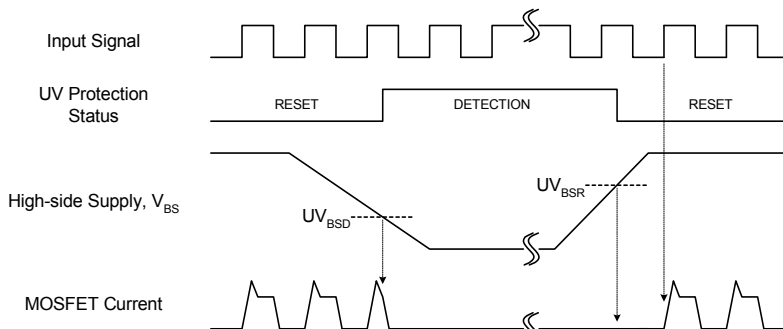


图 9. 欠压保护 (高端)

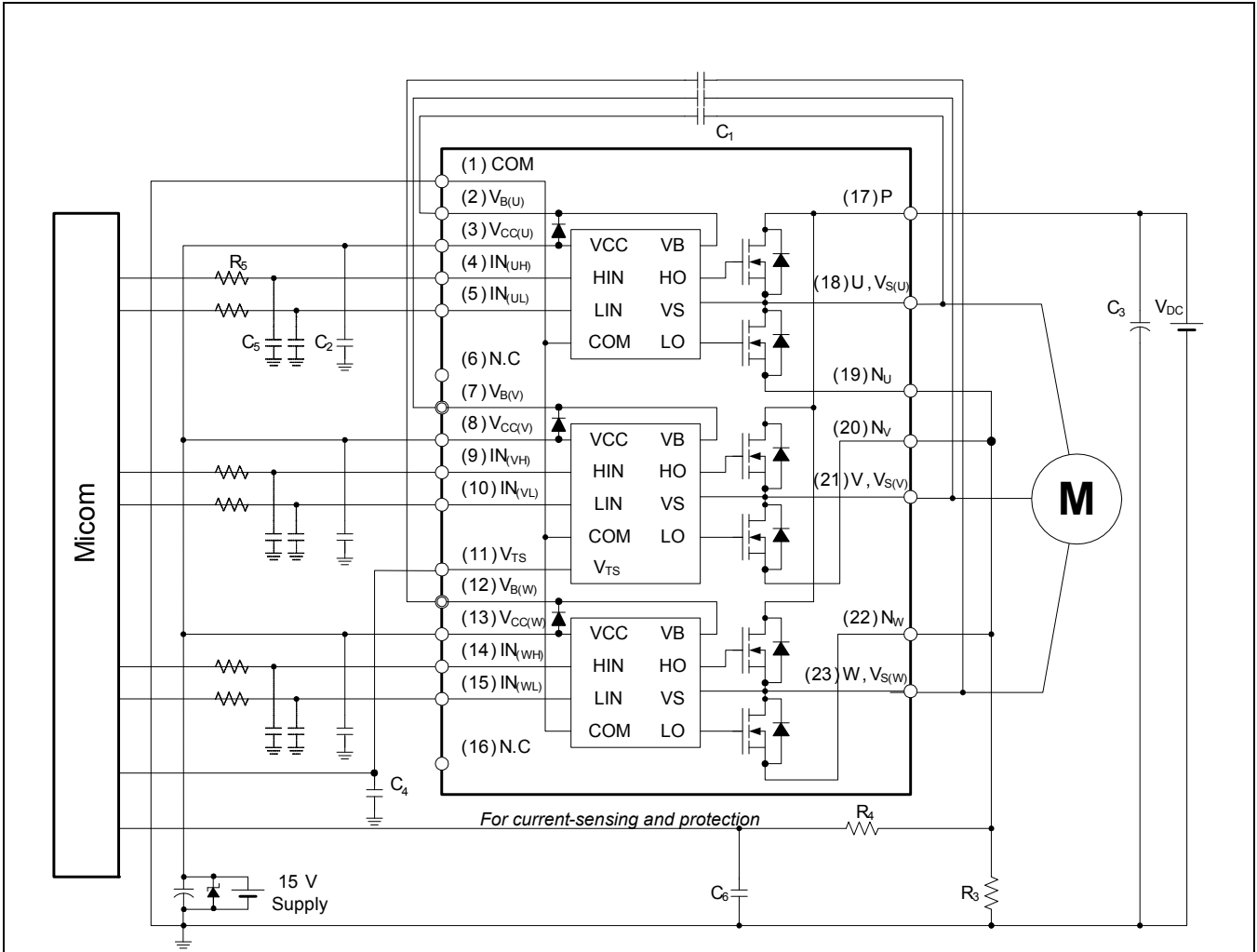
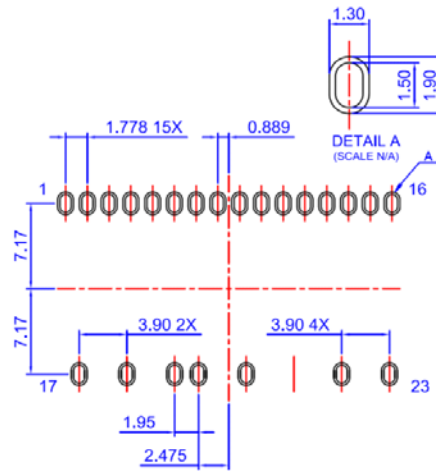
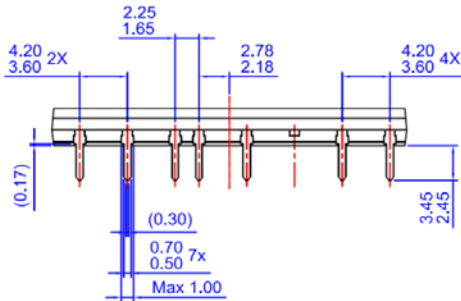
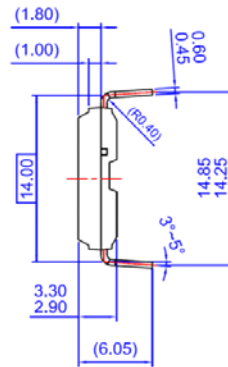
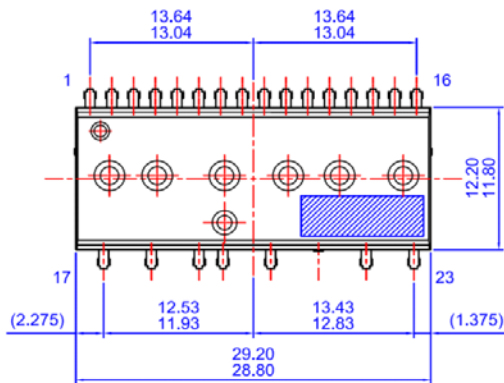
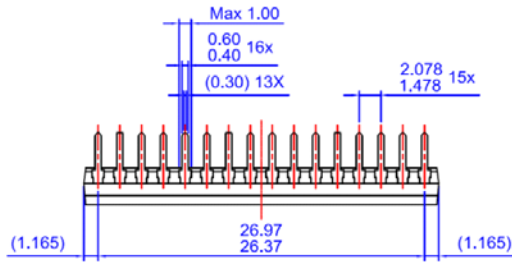


图 10. 应用电路实例

注:

1. 关于引脚的位置, 请参阅图 1。
2. Motion SPM® 5 产品和 MCU 的每个输入端的 RC 耦合 (R_5 和 C_5 , R_4 和 C_6) 和 C_4 , 能有效的防止由浪涌噪声产生的错误的输入信号。
3. 由于位于 COM 和低端 MOSFET 的源极端子之间, R_3 的压降会影响低端的开关性能和自举特性。为此, 稳态情况下 R_3 的压降应小于 1 V。
4. 为避免浪涌电压和 HVIC 故障, 接地线和输出端子之间的接线应短且粗。
5. 所有的滤波电容器应紧密连接到 Motion SPM 5 产品, 它们应当具有能够很好的阻挡高频纹波电流的特性。

轮廓封装详图 (FSB50550A)



- NOTES: UNLESS OTHERWISE SPECIFIED
 A) THIS PACKAGE DOES NOT COMPLY TO ANY CURRENT PACKAGING STANDARD
 B) ALL DIMENSIONS ARE IN MILLIMETERS
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 F) DRAWING FILENAME: MOD23DCREV2.0
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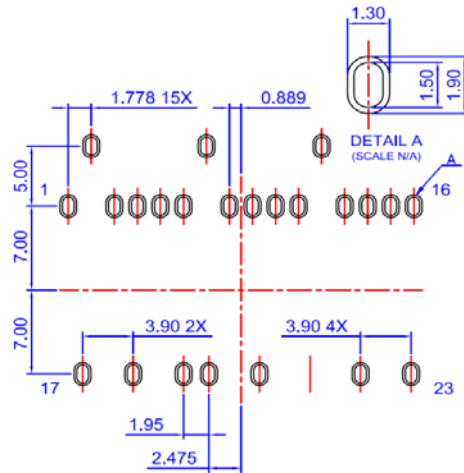
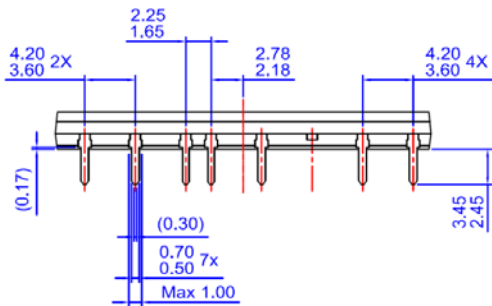
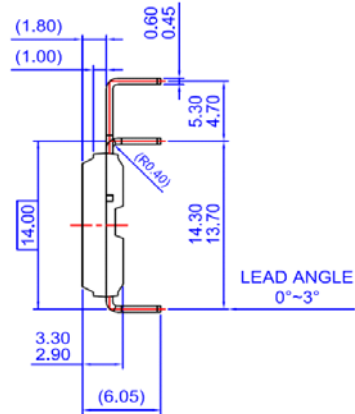
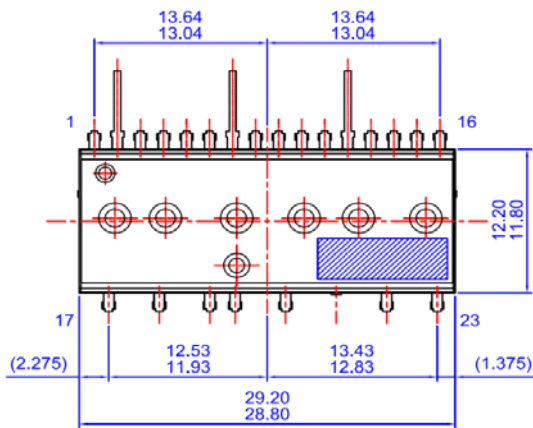
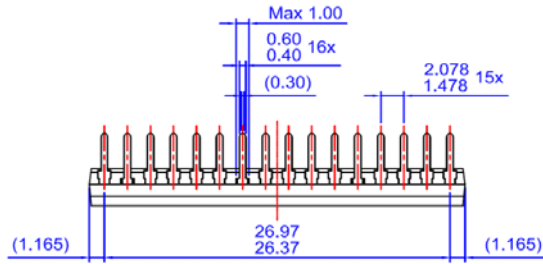
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