



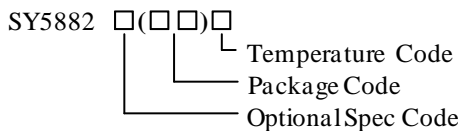
# Applications Note: SY5882Z

## DC/DC Flyback Controller with Primary Side Control for LED Lighting and Analog Dimming mode

### General Description

The SY5882Z is a DC/DC controller targeting at LED Dimming applications, which can achieve up to 2.5% dimming level and high precision for all loading range. It is a primary side controller without applying any secondary feedback circuit for low cost, and drives the converter in the quasi-resonant mode to achieve higher efficiency. It keeps the converter in peak current control to achieve low power frequency ripple.

### Ordering Information



Ordering Number	Package type	Note
SY5882ZFAC	SO8	----

### Features

- 2.5%~100.0% Dimming Range.
- CV Mode for Bias Supply when PWM=0.0%.
- Primary Side Control Eliminates the Opto-coupler.
- Valley Turn-on of the Primary MOSFET to Achieve Low Switching Losses
- 200mA Sourcing Current and 600mA Sinking Current Drive Capability
- Low Start up Current: 34μA Typical
- Reliable Short LED and Open LED Protection
- Low Power Frequency Ripple
- Compact Package: SO8

### Applications

- LED Dimming

### Typical Applications

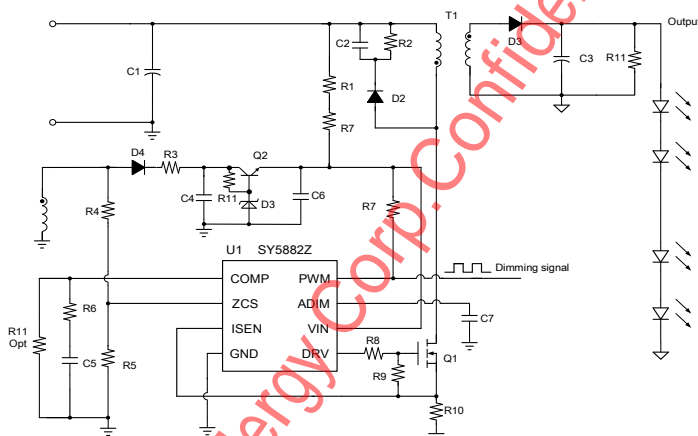


Figure.1a Analog output with PWM dimming signal

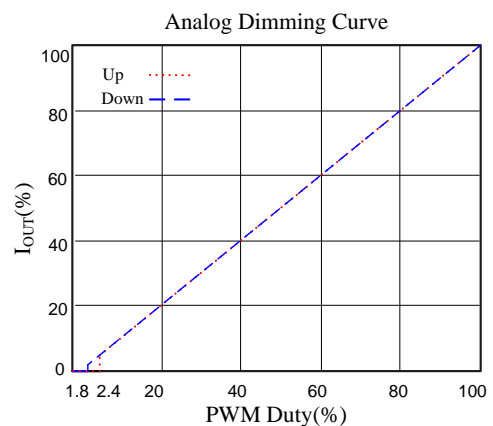
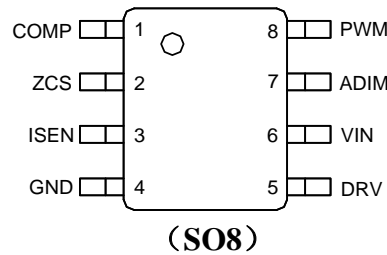


Figure.1b Dimming curve of PWM dimming

**Pinout** (top view)


**Top Mark:** CFQxyz (device code: CFQ, *x*=year code, *y*=week code, *z*=lot number code)

Pin Name	Pin number	Pin Description
COMP	1	Loop compensation pin. Connect a RC network across this pin and ground to stabilize the control loop.
ZCS	2	Inductor current zero-crossing detection pin. This pin receives the auxiliary winding voltage by a resistor divider and detects the inductor current zero crossing point. This pin also provides over voltage protection, line regulation modification function and CV detection simultaneously. If the voltage on this pin is above $V_{ZCS,OV}$ , the IC would enter over voltage protection mode.
ISEN	3	Current sense pin. Connect this pin to the source of the primary switch. Connect the sense resistor across the source of the primary switch and the GND pin. (current sense resistor $R_S$ : $R_S = k \frac{V_{REF} \times N_{PS}}{I_{OUT}}$ , $k=0.167$ )
GND	4	Ground pin
DRV	5	Gate driver pin. Connect this pin to the gate of primary MOSFET.
VIN	6	Power supply pin. This pin also provides output over voltage protection along with ZCS pin.
ADIM	7	Bypass this pin to GND with enough capacitance to hold on internal voltage reference.
PWM	8	PWM dimming input pin, this pin detects the PWM dimming signal

## Absolute Maximum Ratings (Note 1)

VIN, DRV	-0.3V~25V
Supply current I <sub>VIN</sub>	7mA
PWM	-0.3V~23V
ADIM, ZCS	-0.3V~1.8V
ISEN, COMP	-0.3~3.6V
Power Dissipation, @ T <sub>A</sub> = 25 °C SO8	1.1W
Package Thermal Resistance (Note 2)	
SO8, θ <sub>JA</sub>	88 °C/W
SO8, θ <sub>JC</sub>	45 °C/W
Junction Temperature Range	-40 °C to 150 °C
Lead Temperature (Soldering, 10 sec.)	260 °C
Storage Temperature Range	-65 °C to 150 °C

## Recommended Operating Conditions (Note 3)

VIN, DRV	8.5V~20V
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## Block Diagram

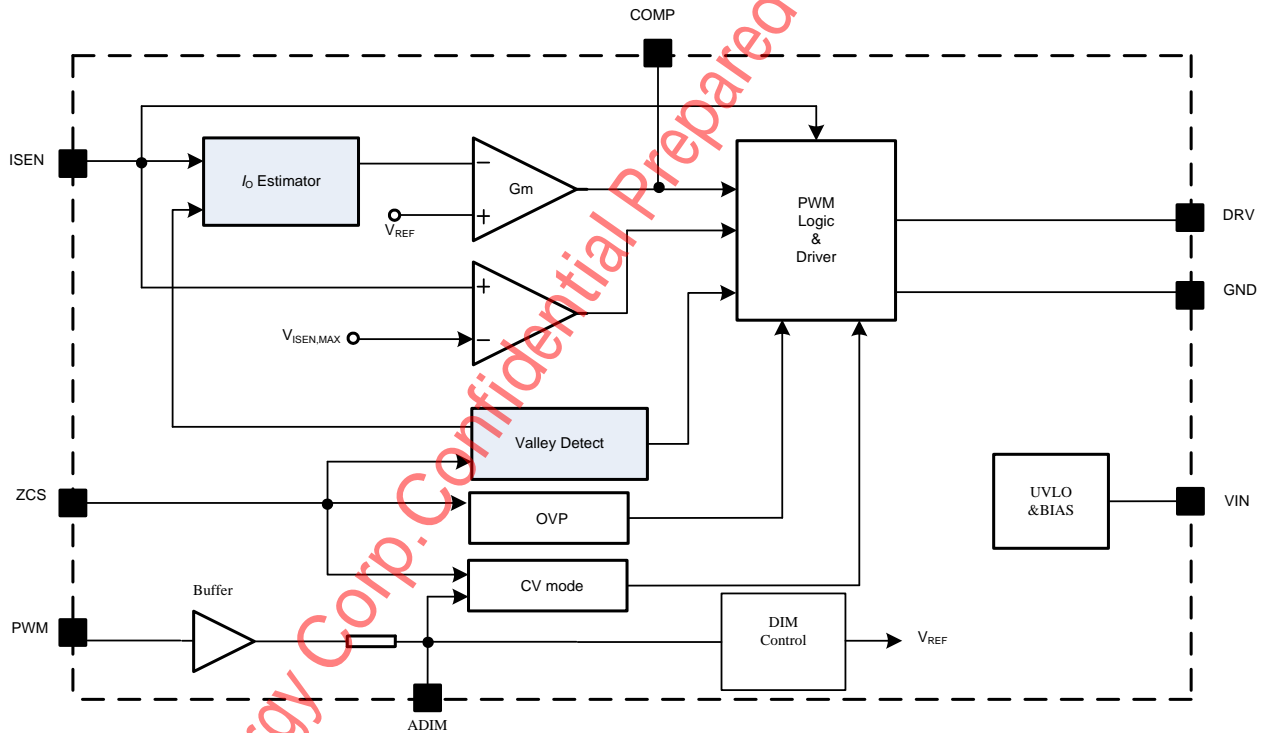


Figure.2 Block Diagram

## Electrical Characteristics

( $V_{IN} = 12V$  (Note 3),  $T_A = 25^\circ C$  unless otherwise specified)

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
<b>Power Supply Section</b>						
VIN Turn-on Threshold	$V_{VIN\_ON}$		19.5	20.5	22	V
VIN Turn-off Threshold	$V_{VIN\_OFF}$		6.7	7.3	8.0	V
VIN OVP Voltage	$V_{VIN\_OVP}$			$V_{VIN\_ON}+4$		V
Start up Current	$I_{ST}$	$V_{VIN} < V_{VIN\_ON}$	24	34	46	$\mu A$
Discharge Current in OVP Mode	$I_{VIN\_OVP}$	$V_{VIN} = 12V$ (Note 4)	5	7	10	mA
<b>Error Amplifier Section</b>						
Internal Reference Voltage	$V_{REF}$		588	600	612	mV
<b>Current Sense Section</b>						
Current Limit Reference Voltage	$V_{ISEN\_MAX}$		0.300	0.375	0.450	V
<b>ZCS Pin Section</b>						
ZCS Pin OVP Voltage Threshold	$V_{ZCS\_OVP}$		1.43	1.5	1.57	V
<b>Gate Driver Section</b>						
Gate Driver Voltage	$V_{Gate}$		9.5	12	14.5	V
Maximum Source Current	$I_{SOURCE}$		150	200	250	mA
Minimum Sink Current	$I_{SINK}$		500	600	800	mA
Max ON Time	$T_{ON\_MAX}$			24		$\mu s$
Min ON Time	$T_{ON\_MIN}$			450		ns
Max OFF Time	$T_{OFF\_MAX}$			60		$\mu s$
Min OFF Time	$T_{OFF\_MIN}$			1.5		$\mu s$
Maximum Switching Frequency	$F_{MAX}$			120		kHz
<b>ADIM Function Section</b>						
ADIM Enable ON	$V_{ADIM\_ON}$		32	42	52	mV
ADIM Enable OFF	$V_{ADIM\_OFF}$		20	32	42	mV
<b>Thermal Section</b>						
Thermal Fold back Temperature	$T_{FB}$			150		$^\circ C$
Thermal Shut down Temperature	$T_{SD}$			160		$^\circ C$
<b>PWM Function Section</b>						
PWM ON Voltage	$V_{PWM\_ON}$				1.2	V
PWM OFF Voltage	$V_{PWM\_OFF}$		0.5			V

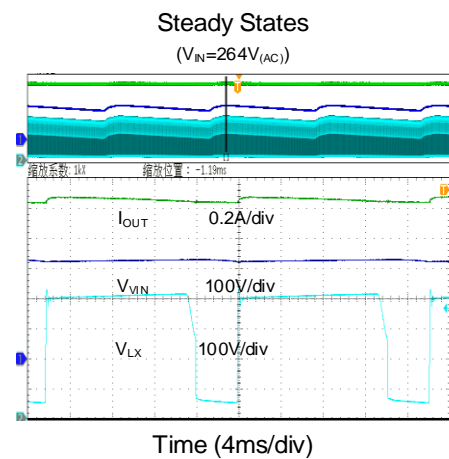
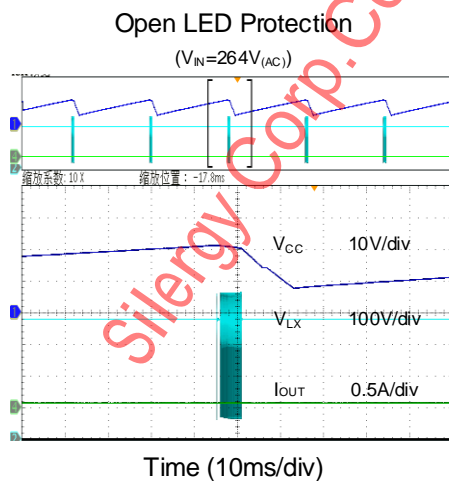
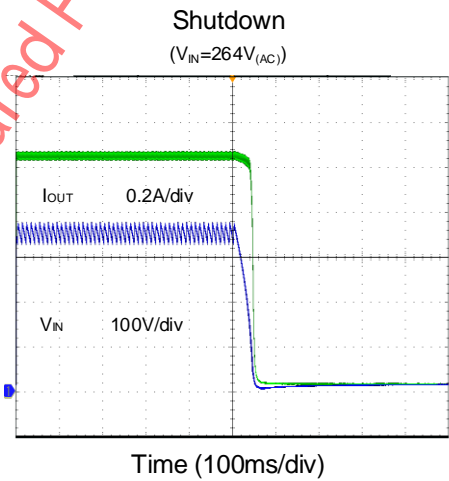
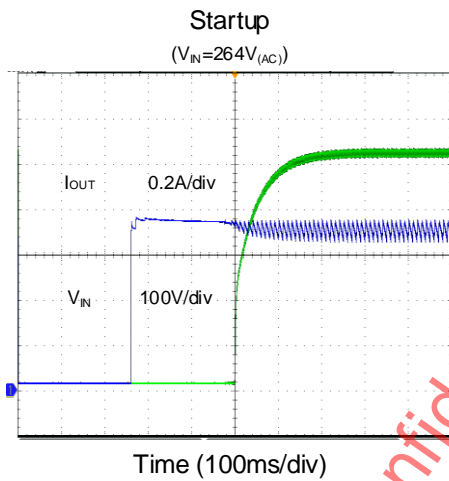
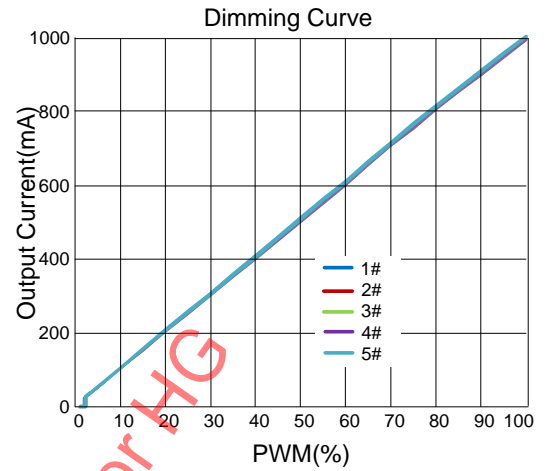
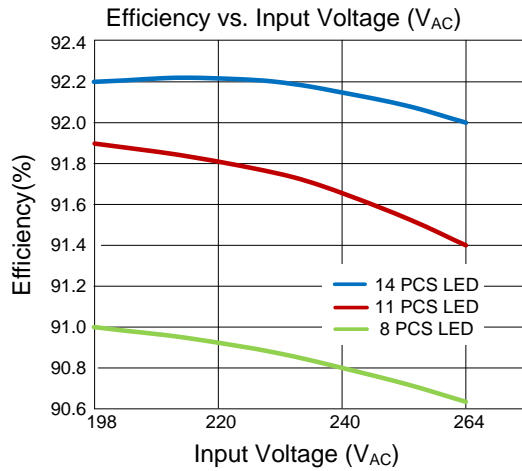
**Note 1:** Stresses beyond the “Absolute Maximum Ratings” may cause permanent damage to the device. These are stress ratings only. Functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

**Note 2:**  $\Theta_{JA}$  is measured in the natural convection at  $T_A = 25^\circ C$  on a low effective single layer thermal conductivity test board of JEDEC 51-3 thermal measurement standard. Test condition: Device mounted on 2” x 2” FR-4 substrate PCB, 2oz copper, with minimum recommended pad on top layer and thermal vias to bottom layer ground plane.

**Note 3:** Increase VIN pin voltage gradually higher than  $V_{VIN\_ON}$  voltage then turn down to 12V.

**Note 4:** Increase VIN pin voltage gradually higher than  $V_{VIN\_OVP}$  voltage then turn down to 12V.

## Typical Performance Characteristic



## Operation

The SY5882Z is a DC/DC controller targeting at LED Dimming applications, which can achieve up to 2.5% dimming level and high precision for all loading range.

It is a primary side controller without applying any secondary feedback circuit for low cost and minimizing the board size.

SY5882Z is compatible with analog dimming and PWM dimming for different application.

It keeps the converter in peak current control to achieve low power frequency ripple.

In order to reduce the switching losses and improve EMI performance, Quasi-Resonant switching mode is applied, which means to turn on the power MOSFET at voltage valley.

the startup current of SY5882Z is rather small (34μA typically) to reduce the standby power loss further.

SY5882Z provides reliable protections such as Short Circuit Protection (SCP), Open LED Protection (OLP), Over Temperature Protection (OTP), etc.

SY5882Z is available with SO8 package.

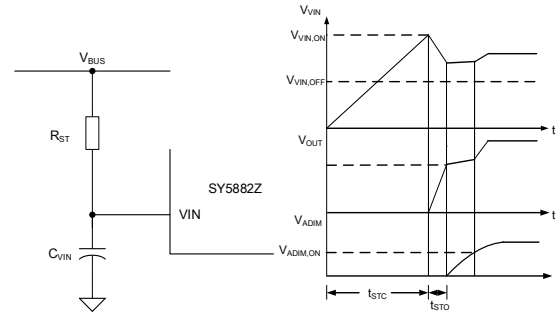
## Applications Information

### Start up

After DC BUS is powered on, the capacitor  $C_{VIN}$  between VIN and GND pin is charged up by BUS voltage through a start-up resistor  $R_{ST}$ . Once  $V_{VIN}$  rises up to  $V_{VIN\_ON}$ , the internal blocks start to work.  $V_{VIN}$  will be pulled down by internal consumption of IC until the auxiliary winding of transformer could supply enough energy to maintain  $V_{VIN}$  above  $V_{VIN\_OFF}$ .

The whole start up procedure is divided into four sections shown in Fig.4.  $t_{STC}$  is the  $C_{VIN}$  charged up section, and  $t_{STO}$  is the output voltage build-up section. The start-up time  $t_{ST}$  is composed of  $t_{STC}$  and  $t_{STO}$ , and usually  $t_{STO}$  is much smaller than  $t_{STC}$ .

$t_{STO}$  is fast start-up stage, which will help to create output voltage quickly. After  $t_{STO}$ , if  $V_{ADIM}$  is less than  $V_{ADIM\_ON}$ , IC enters into CV mode. When  $V_{ADIM}$  is larger than  $V_{ADIM\_ON}$ , IC works in peak current mode.



**Fig.4 Start up**

The start up resistor  $R_{ST}$  and  $C_{VIN}$  are designed by rules as below:

(a) Preset start-up resistor  $R_{ST}$ , make sure that the current through  $R_{ST}$  is larger than  $I_{ST}$  and smaller than 1mA.

$$\frac{V_{BUS}}{1mA} < R_{ST} < \frac{V_{BUS}}{I_{ST}} \quad (1)$$

Where  $V_{BUS}$  is the BUS line voltage

(b) Select  $C_{VIN}$  to obtain an ideal start up time  $t_{ST}$ , and ensure the output voltage is built up at one time.

$$C_{VIN} = \frac{\left(\frac{V_{BUS}}{R_{ST}} - I_{ST}\right) \times t_{ST}}{V_{VIN\_ON}} \quad (2)$$

(d) If the  $C_{VIN}$  is not big enough to build up the output voltage at one time. Increase  $C_{VIN}$  and decrease  $R_{ST}$ , go back to step (a) and redo such design flow until the ideal start up procedure is obtained.

### Internal pre-charge design for quick start up

In P3,  $V_{COMP}$  is pre-charged by internal current source until it is over the initial voltage  $V_{COMP\_IC}$ .  $V_{COMP\_IC}$  can be programmed by  $R_{COMP}$ . Such design is meant to reduce the start up time shown in Fig.5.

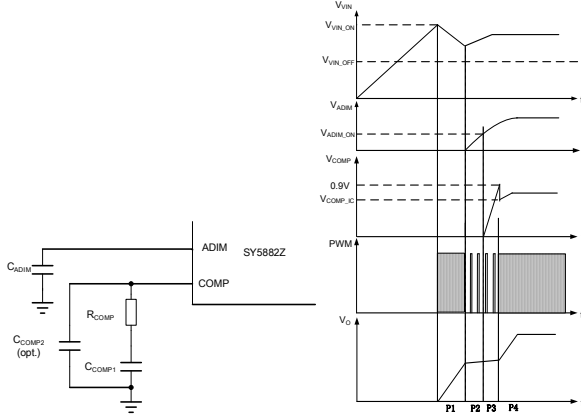
The voltage pre-charged  $V_{COMP\_IC}$  in start-up procedure can be programmed by  $R_{COMP}$ :

$$V_{COMP\_IC} = 0.9V - 300\mu A \times R_{COMP} \quad (3)$$

Where  $V_{COMP\_IC}$  is the pre-charged voltage of COMP pin.

Generally, a small capacitance of  $C_{COMP}$  is necessary to stabilize the system loop (10nF is recommended).

The voltage pre-charged in start-up procedure can be programmed by  $R_{COMP}$ ; On the other hand, larger  $R_{COMP}$  can provide larger phase margin for the control loop; A small ceramic capacitor is added to suppress high frequency interruption (10pF~100pF is recommended if necessary)



**Fig.5 Pre-charge scheme in start up**

### Shut down

After DC BUS is powered off, the energy stored in the BUS capacitor will be discharged. When the auxiliary winding of the transformer cannot supply enough energy to VIN pin,  $V_{VIN}$  will drop down. Once  $V_{VIN}$  is below  $V_{VIN\_OFF}$ , the IC will stop working and  $V_{COMP}$  will be discharged to zero.

### Primary side constant current control

Primary side control is applied to eliminate secondary feedback circuit and opto-coupler, which reduces the BOM cost. The switching waveforms are shown in Fig.6.

The output current  $I_{OUT}$  can be represented by,

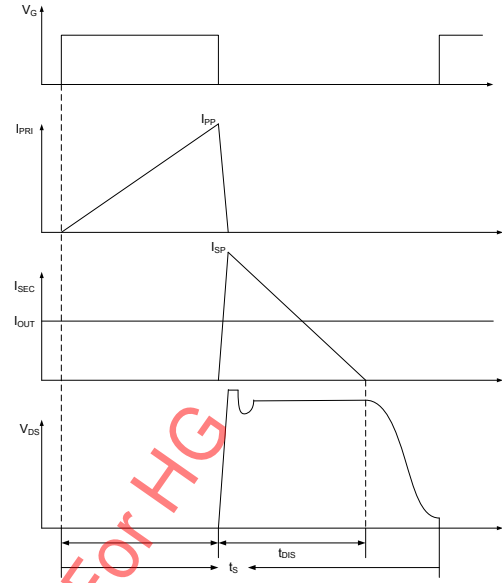
$$I_{OUT} = \frac{I_{SP}}{2} \times \frac{t_{DIS}}{t_s} \quad (4)$$

Where  $I_{SP}$  is the peak current of the secondary side;  $t_{DIS}$  is the discharge time of the transformer;  $t_s$  is the switching period.

The secondary peak current is related with primary peak current, if the effect of the leakage inductor is neglected.

$$I_{SP} = N_{PS} \times I_{PP} \quad (5)$$

Where  $N_{PS}$  is the turn ratio of primary to secondary of the transformer.



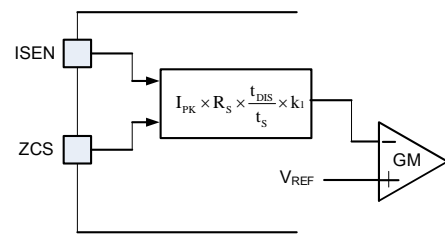
**Fig.6 Switching waveforms**

Thus,  $I_{OUT}$  can be represented by

$$I_{OUT} = \frac{N_{PS} \times I_{PP}}{2} \times \frac{t_{DIS}}{t_s} \quad (6)$$

The primary peak current  $I_{PP}$  and inductor current discharge time  $t_{DIS}$  can be detected by ISEN and ZCS pin, which is shown in Fig.7. These signals are processed and applied to the negative input of the gain modulator. In static state, the positive and negative inputs are equal.

$$V_{REF} = I_{PP} \times R_s \times \frac{t_{DIS}}{t_s} \times k_1 \quad (7)$$



**Fig.7 Output current detection diagram**

Finally, the output current  $I_{OUT}$  can be represented by

$$I_{OUT} = \frac{V_{REF} \times N_{PS}}{R_s \times 2 \times k_1} \quad (8)$$

Where  $k_1$  is the output current weight coefficient;  $k_2$  is the output modification coefficient;  $V_{REF}$  is the internal reference voltage;  $R_S$  is the current sense resistor.

$k_1$  and  $V_{REF}$  are all internal constant parameters,  $I_{OUT}$  can be programmed by  $N_{PS}$  and  $R_S$ .

$$R_S = \frac{V_{REF} \times N_{PS}}{I_{OUT} \times 2 \times k_1} \quad (9)$$

Then

$$R_S = \frac{k \times V_{REF} \times N_{PS}}{I_{OUT}}, k = \frac{1}{2k_1} \quad (10)$$

### Quasi-Resonant Operation

QR mode operation provides low turn-on switching losses for the converter.

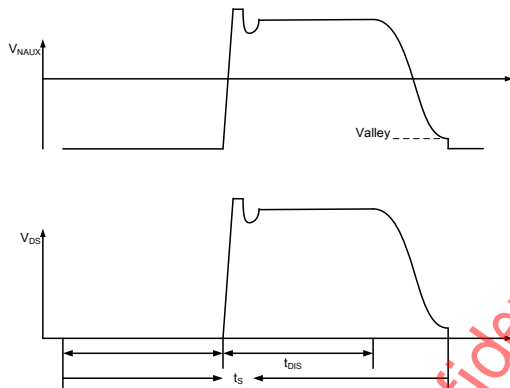


Fig.8 QR mode operation

The voltage across drain and source of the primary MOSFET is reflected by the auxiliary winding of the Flyback transformer. ZCS pin detects the voltage across the auxiliary winding by a resistor divider. When the voltage across drain and source of the primary MOSFET is at voltage valley, the MOSFET would be turned on.

### CV Mode

When  $PWM < 1.8\%$ , IC still need bias power:

- (1) If Dimming signal is greater than 2.4%, IC always works at CC mode.
- (2) If Dimming signal is lower than 1.8%, CV mode is triggered. IC works in CV mode to maintain  $V_{ZCS}$  nearby  $V_{ZCS\_CV}$  (0.5V).  $N_P$ :  $N_{AUX}$  and  $R_{ZCS}$  can be adjusted to

prevent LED flicker and keep bias supply enough at CV mode.

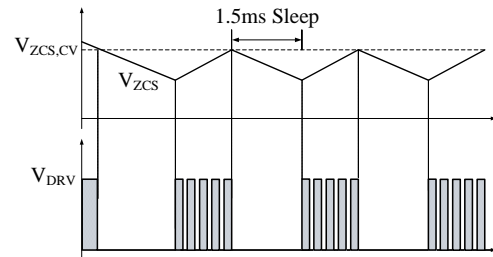


Figure.9 The working process of CV mode

In CV mode, which is shown in Fig.9.

- (1) If  $V_{ZCS}$  is greater than  $V_{ZCS\_CV}$  (0.5V), IC will sleep for 1.5ms.
- (2) After 1.5ms sleep, if  $V_{ZCS}$  is smaller than  $V_{ZCS\_CV}$ , IC will work until  $V_{ZCS}$  is greater than  $V_{ZCS\_CV}$ . During this time, MOSFET turns on by QR and turns off until the ISEN voltage reach 0.05V.

The output of CV can be calculated as below:

$$V_{OUT,CV} = 0.5V \times \left( \frac{R_{ZCSU} + R_{ZCSD}}{R_{ZCSD}} \right) \times \frac{N_S}{N_{AUX}} \quad (11)$$

Where,  $R_{ZCSU}$  is the upper resistor of ZCS pin;  $R_{ZCSD}$  is the down resistor of ZCS pin;  $N_S$  and  $N_{AUX}$  are the turns of secondary winding and auxiliary winding separately.

### Over Voltage Protection (OVP) & Open LED Protection (OLP)

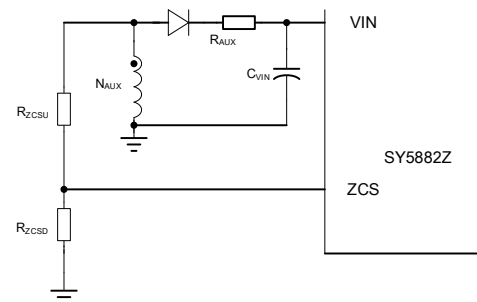


Fig.10 OVP&OLP

The output voltage is reflected by the auxiliary winding voltage of the Flyback transformer, and both ZCS pin and VIN pin provide over voltage protection function. When the load is null or large transient happens, the output voltage will exceed the rated value. When  $V_{VIN}$  exceeds  $V_{VIN\_OVP}$  or  $V_{ZCS}$  exceeds  $V_{ZCS\_OVP}$ , the over voltage protection is triggered and the IC will discharge  $V_{VIN}$  by an internal current source. Once  $V_{VIN}$  is below



$V_{VIN\_OFF}$ , the IC will shut down and be charged again by BUS voltage through start up resistor. If the over voltage condition still exists, the system will operate in hiccup mode.

Thus, the turns of the auxiliary winding  $N_{AUX}$  and the resistor divider is related with the OVP function.

$$\frac{V_{ZCS\_OVP}}{V_{OVP}} = \frac{N_{AUX}}{N_S} \times \frac{R_{ZCSD}}{R_{ZCSU} + R_{ZCSD}} \quad (12)$$

$$\frac{V_{VIN\_OVP}}{V_{OVP}} \geq \frac{N_{AUX}}{N_S} \quad (13)$$

Where  $V_{OVP}$  is the output over voltage specification;  $R_{ZCSU}$  and  $R_{ZCSD}$  compose the resistor divider. The turn ratio of  $N_S$  to  $N_{AUX}$  and the ratio of  $R_{ZCSU}$  to  $R_{ZCSD}$  could be induced from equation (12) and (13).

### Short Circuit Protection (SCP)

When the output is shorted to ground, the output voltage is clamped to zero. The voltage of the auxiliary winding is proportional to the output winding, so valley signal cannot be detected by VSEN. Without valley detection, MOSFET cannot be turned ON until maximum off time  $T_{OFF\_MAX}$  is matched. If MOSFET is turned ON by  $T_{OFF\_MAX}$  64 times continuously, IC will be shut down and enter into hiccup mode.

If the output voltage is not low enough to disable valley detection in short condition,  $V_{VIN}$  will drop down without auxiliary winding supply. Once  $V_{VIN}$  is below  $V_{VIN\_OFF}$ , the IC will shut down and be charged again by the BUS voltage through the start-up resistor. If the short circuit condition still exists, the system will operate in hiccup mode.

In order to guarantee SCP function is not effected by voltage spike of auxiliary winding, a filter resistor  $R_{AUX}$  is needed (10Ω typically) shown in Fig.10.

### Dimming Mode

SY5882Z supports PWM input and 0~1.75V input.

1). 0~1.75V input dimming:

If  $V_{ADIM}$  is lower than  $V_{ADIM\_OFF}$  (32mV), the output current is decreased to zero; While  $V_{ADIM}$  is increased from  $V_{ADIM\_OFF}$  to  $V_{ADIM\_ON}$  (42mV), the output current is created and the value is 2.5 percent of full load output

current; When  $V_{ADIM}$  is higher than 1.75V, the output current is 100 percent of full load output current;

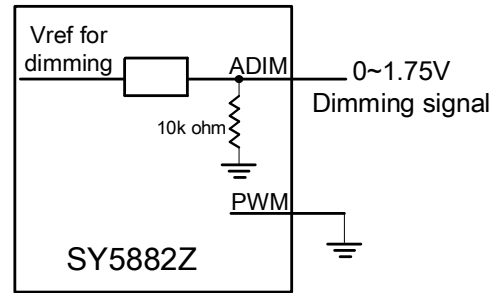


Fig.12 0~1.75V input dimming

As showed below, the available dimming range of  $V_{ADIM}$  is from 42mV to 1750mV.

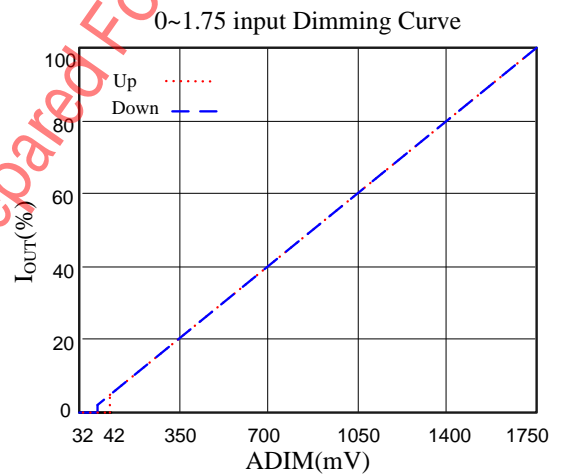


Fig.13 Dimming curve of analog dimming

2). PWM input dimming

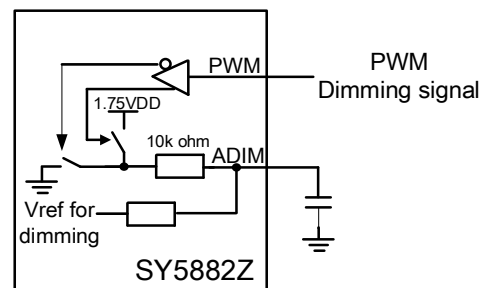


Fig.14 PWM input dimming

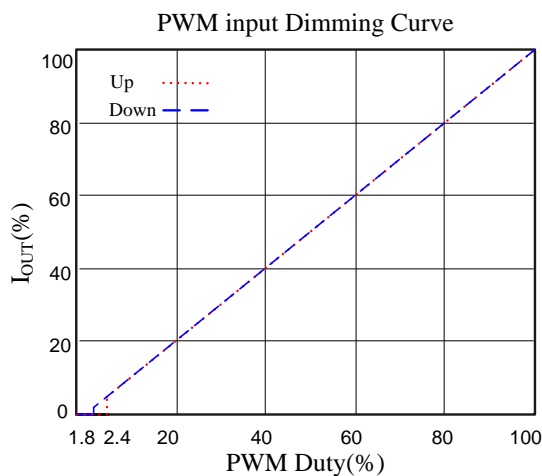
If the dimming signal is PWM signal, as showed above, there is a RC filter to convert the signal.

When the voltage of PWM pin is higher than  $V_{PWM\_ON}$ , the dimming signal is sensed as high logic level, and ADIM pin is pulled up to 1.75V by a 10kΩ resistor; when the voltage of PWM pin is lower than  $V_{PWM\_OFF}$ , the dimming signal is sensed as low logic level, and ADIM pin is pulled down to GND by a 10kΩ resistor.

The duty cycle of PWM signal is reflected by the voltage on ADIM pin  $V_{ADIM}$ .

$$V_{ADIM} = D_{PWM} \times 1.75V \quad (17)$$

So the relationship between the output current and the PWM input is showed below:



**Fig.15 the dimming curve of PWM input**

### 3) .ADIM capacitor

A capacitor  $C_{ADIM}$  need be connected across ADIM and GND pin to obtain a smooth voltage waveform of the dimming signal duty cycle.  $C_{ADIM}$  is selected by (for 1KHz PWM, 1uF typically)

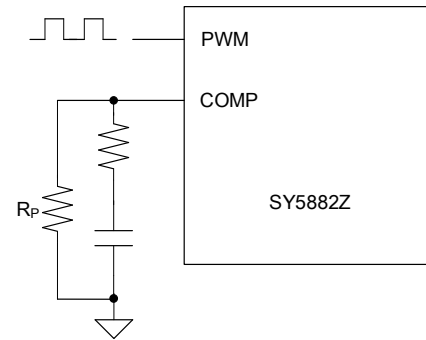
$$C_{ADIM} \geq \frac{10^{-3}}{f_{DIM}} \text{ F} \cdot \text{Hz} \quad (18)$$

$f_{DIM}$  is the frequency of PWM dimming signal.

### 4) For further dimming depth

For further dimming depth,  $R_P$  is added to achieve it and 2M is recommended.

As shown in the figure below, SY5882Z can achieve the application of dimming depth less than 2.5%.



**Fig.16 Further dimming depth circuit**

## Power Device Design

### MOSFET and Diode

When the operation condition is with maximum input voltage and full load, the voltage stress of MOSFET and secondary power diode is maximized;

$$V_{MOS\_DS\_MAX} = V_{DC\_MAX} + N_{PS} \times (V_{OUT} + V_{D\_F}) + \Delta V_S \quad (19)$$

$$V_{D\_R\_MAX} = \frac{V_{DC\_MAX}}{N_{PS}} + V_{OUT} \quad (20)$$

Where  $V_{DC\_MAX}$  is the maximum input DC voltage;  $N_{PS}$  is the turn ratio of the Flyback transformer;  $V_{OUT}$  is the rated output voltage;  $V_{D\_F}$  is the forward voltage of secondary power diode;  $\Delta V_S$  is the overshoot voltage clamped by RCD snubber during OFF time.

When the operation condition is with minimum input voltage and full load, the current stress of MOSFET and power diode is maximized.

$$I_{MOS\_PK\_MAX} = I_{P\_PK\_MAX} \quad (21)$$

$$I_{MOS\_RMS\_MAX} = I_{P\_RMS\_MAX} \quad (22)$$

$$I_{D\_PK\_MAX} = N_{PS} \times I_{P\_PK\_MAX} \quad (23)$$

$$I_{D\_AVG} = I_{OUT} \quad (24)$$

Where  $I_{P\_PK\_MAX}$  and  $I_{P\_RMS\_MAX}$  are maximum primary peak current and RMS current, which will be introduced later.

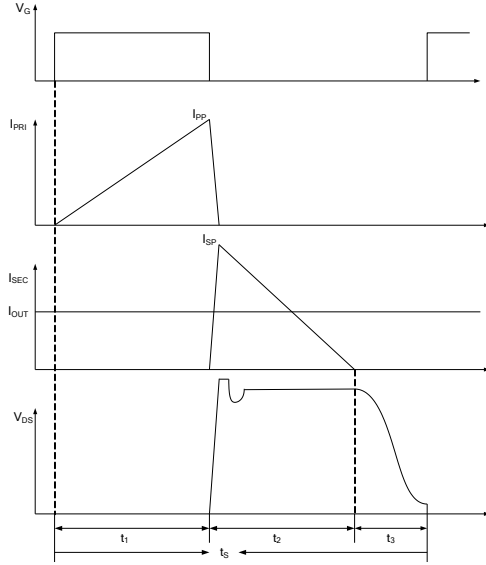
### Transformer ( $N_{PS}$ and $L_M$ )

$N_{PS}$  is limited by the electrical stress of the power MOSFET:

$$N_{PS} \leq \frac{V_{MOS\_ (BR)DS} \times 90\% - V_{DC\_MAX} - \Delta V_S}{V_{OUT} + V_{D,F}} \quad (25)$$

Where  $V_{MOS\_ (BR)DS}$  is the breakdown voltage of the power MOSFET.

In Quasi-Resonant mode, each switching period cycle  $t_s$  consists of three parts: current rising time  $t_1$ , current falling time  $t_2$  and quasi-resonant time  $t_3$  are shown as Fig.16.



**Fig.16 switching waveforms**

The ON time increases with the decreasing of input DC voltage and the increasing of load. When the operation condition is with minimum input DC voltage and full load, the ON time is maximized. Thus, the minimum switching frequency  $f_{S\_MIN}$  happens at the minimum input DC voltage and maximum load (maximum output current); meanwhile, the maximum peak current through MOSFET and the transformer happens.

Once the minimum frequency  $f_{S\_MIN}$  is set, the inductance of the transformer could be induced. The design flow is shown as below:

**(a) Select  $N_{PS}$**

$$N_{PS} \leq \frac{V_{MOS\_ (BR)DS} \times 90\% - V_{DC\_MAX} - \Delta V_S}{V_{OUT} + V_{D,F}} \quad (26)$$

**(b) Preset minimum frequency  $f_{S\_MIN}$**

**(c) Compute relative  $t_s$ ,  $t_1$  ( $t_3$  is omitted to simplify the design here)**

$$t_s = \frac{1}{f_{S\_MIN}} \quad (27)$$

$$t_1 = \frac{t_s \times N_{PS} \times (V_{OUT} + V_{D,F})}{V_{DC\_MIN} + N_{PS} \times (V_{OUT} + V_{D,F})} \quad (28)$$

**(d) Design inductance  $L_M$**

$$L_M = \frac{V_{DC\_MIN}^2 \times t_1^2 \times \eta}{2 \times P_{OUT} \times t_s} \quad (29)$$

**(e) Compute  $t_3$**

$$t_3 = \pi \times \sqrt{L_M \times C_{Drain}} \quad (30)$$

Where  $C_{Drain}$  is the parasitic capacitance at drain of MOSFET.

**(f) Compute primary maximum peak current  $I_{P\_PK\_MAX}$  and RMS current  $I_{P\_RMS\_MAX}$  for the transformer fabrication.**

$$I_{P\_PK\_MAX} = \frac{P_{OUT} \times \left[ \frac{L_M}{V_{DC\_MIN}} + \frac{L_M}{N_{PS} \times (V_{OUT} + V_{D,F})} \right]}{L_M \times \eta} + \sqrt{\frac{P_{OUT}^2 \times \left[ \frac{L_M}{V_{DC\_MIN}} + \frac{L_M}{N_{PS} \times (V_{OUT} + V_{D,F})} \right]^2 + 2L_M \times \eta \times P_{OUT} \times t_3}{L_M \times \eta}} \quad (31)$$

Where  $\eta$  is the efficiency;  $P_{OUT}$  is rated full load power

Adjust  $t_1$  and  $t_s$  to  $t_1'$  and  $t_s'$  considering the effect of  $t_3$

$$t_s' = \frac{\eta \times L_M \times I_{P\_PK\_MAX}^2}{2P_{OUT}} \quad (32)$$

$$t_1' = \frac{L_M \times I_{P\_PK\_MAX}}{V_{DC\_MIN}} \quad (33)$$

$$I_{P\_RMS\_MAX} \approx \sqrt{\frac{t_1'}{3t_s'}} \times I_{P\_PK\_MAX} \quad (34)$$

**(g) Compute secondary maximum peak current  $I_{S\_PK\_MAX}$  and RMS current  $I_{S\_RMS\_MAX}$  for the transformer fabrication.**

$$I_{S\_PK\_MAX} = N_{PS} \times I_{P\_PK\_MAX} \quad (35)$$

$$t_2' = t_s' - t_1' - t_3 \quad (36)$$

$$I_{S\_RMS\_MAX} \approx \sqrt{\frac{t'_2}{3t'_S}} \times I_{S\_PK\_MAX} \quad (37)$$

### Transformer design ( $N_P, N_S, N_{AUX}$ )

The design of the transformer is similar with ordinary Flyback transformer. The parameters below are necessary:

Necessary parameters	
Turns ratio	$N_{PS}$
Inductance	$L_M$
Primary maximum current	$I_{P\_PK\_MAX}$
Primary maximum RMS current	$I_{P\_RMS\_MAX}$
Secondary maximum RMS current	$I_{S\_RMS\_MAX}$

The design rules are as followed:

(a) Select the magnetic core style, identify the effective area  $A_e$ .

(b) Preset the maximum magnetic flux  $\Delta B$

$$\Delta B = 0.22 \sim 0.26 T$$

(c) Compute primary turn  $N_P$

$$N_P = \frac{L_M \times I_{P\_PK\_MAX}}{\Delta B \times A_e} \quad (38)$$

(d) Compute secondary turn  $N_S$

$$N_S = \frac{N_P}{N_{PS}} \quad (39)$$

(e) Compute auxiliary turn  $N_{AUX}$

$$N_{AUX} = N_S \times \frac{V_{VIN}}{V_{OUT}} \quad (40)$$

Where  $V_{VIN}$  is the working voltage of VIN pin (12V~15V is recommended).

(f) Select an appropriate wire diameter

With  $I_{P\_RMS\_MAX}$  and  $I_{S\_RMS\_MAX}$ , select appropriate wire to make sure the current density ranges from  $4A/mm^2$  to  $10A/mm^2$ .

(g) If the winding area of the core and bobbin is not enough, reselect the core style, go to (a) and redesign the transformer until the ideal transformer is achieved.

### RCD snubber for MOSFET

The power loss of the snubber  $P_{RCD}$  is evaluated first

$$P_{RCD} = \frac{N_{PS} \times (V_{OUT} + V_{D,F}) + \Delta V_S}{\Delta V_S} \times \frac{L_K}{L_M} \times P_{OUT} \quad (41)$$

Where  $N_{PS}$  is the turns ratio of the Flyback transformer;  $V_{OUT}$  is the output voltage;  $V_{D,F}$  is the forward voltage of the power diode;  $\Delta V_S$  is the overshoot voltage clamped by RCD snubber;  $L_K$  is the leakage inductor;  $L_M$  is the inductance of the Flyback transformer;  $P_{OUT}$  is the output power.

The  $R_{RCD}$  is related with the power loss:

$$R_{RCD} = \frac{(N_{PS} \times (V_{OUT} + V_{D,F}) + \Delta V_S)^2}{P_{RCD}} \quad (42)$$

The  $C_{RCD}$  is related with the voltage ripple of the snubber  $\Delta V_{C\_RCD}$ :

$$C_{RCD} = \frac{N_{PS} \times (V_{OUT} + V_{D,F}) + \Delta V_S}{R_{RCD} \times f_S \times \Delta V_{C\_RCD}} \quad (43)$$

### Layout

(a) To achieve better EMI performance and reduce line frequency ripples, line capacitor should be connected to near the switching circuit.

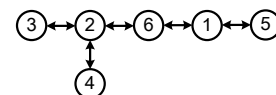
(b) The circuit loop of all switching circuit should be kept small: primary power loop, secondary loop and auxiliary power loop.

(c) Bias supply trace should be connected to the bias supply capacitor first instead of GND pin. The bias supply capacitor should be put beside the IC.

(d) Loop of 'Source pin – current sample resistor – GND pin' should be kept as small as possible.

(e) The resistor divider is recommended to be put beside the IC.

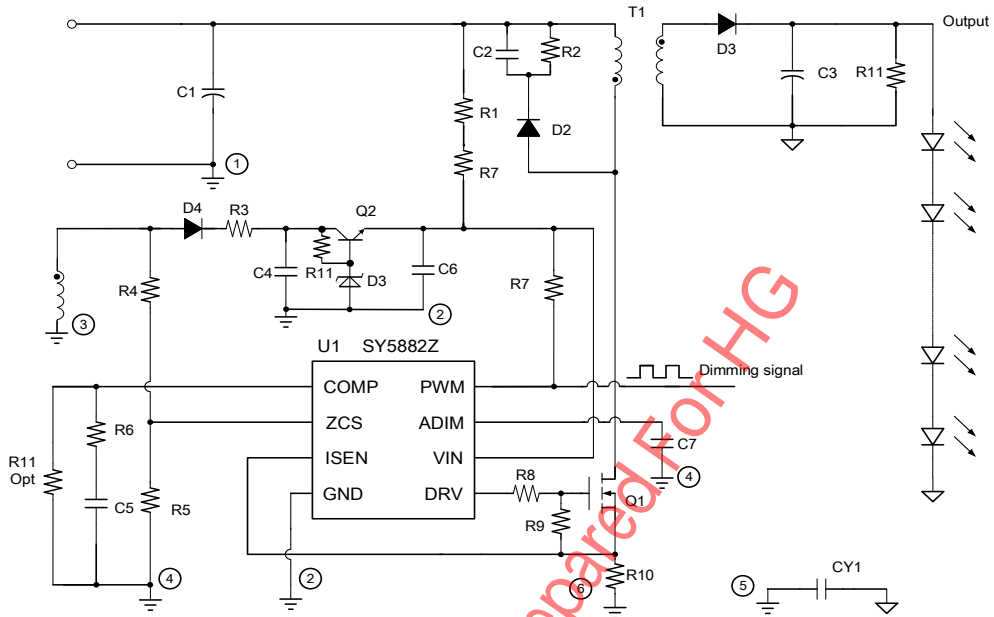
(f) The connection of ground is recommended as:



Ground ①: ground of BUS line capacitor

Ground ②: ground of bias supply capacitor and GND pin  
 Ground ③: ground node of auxiliary winding  
 Ground ④: ground of signal trace except GND pin

Ground ⑤: primary ground node of Y capacitor.  
 Ground ⑥: ground of current sample resistor.



**Fig.17 Ground Layout**

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## Design Example

A design example of typical application is shown below step by step.

### #1. Identify design specification

Design Specification			
$V_{DC}(RMS)$	380V~450V	$V_{OUT}$	42V
$I_{OUT}$	1000mA	$\eta$	92%

### #2. Transformer design ( $N_{PS}$ , $L_M$ )

Refer to Power Device Design

Conditions			
$V_{DC\_MIN}$	380V	$V_{AC\_MAX}$	450V
$\Delta V_S$	50V	$V_{MOS\_ (BR)DS}$	650V
$P_{OUT}$	42W	$V_{D,F}$	1V
$C_{Drain}$	100pF	$f_{S\_MIN}$	55kHz

#### (a) Compute turns ratio $N_{PS}$ first

$$\begin{aligned}
 N_{PS} &\leq \frac{V_{MOS\_ (BR)DS} \times 90\% - V_{DC\_MAX} - \Delta V_S}{V_{OUT} + V_{D,F}} \\
 &= \frac{700V \times 0.9 - 450V - 50V}{42V + 1V} \\
 &= 3.605
 \end{aligned}$$

$N_{PS}$  is set to

$$N_{PS} = 3$$

#### (b) $f_{S\_MIN}$ is preset

$$f_{S\_MIN} = 55kHz$$

#### (c) Compute the switching period $t_s$ and ON time $t_1$ at the peak of input voltage.

$$t_s = \frac{1}{f_{S\_MIN}} = 18.18\mu s$$

$$\begin{aligned}
 t_1 &= \frac{t_s \times N_{PS} \times (V_{OUT} + V_{D,F})}{V_{DC\_MIN} + N_{PS} \times (V_{OUT} + V_{D,F})} \\
 &= \frac{18.18\mu s \times 3.0 \times (42V + 1V)}{380V + 3.0 \times (42V + 1V)} \\
 &= 4.608\mu s
 \end{aligned}$$

#### (d) Compute the inductance $L_M$

$$\begin{aligned}
 L_M &= \frac{V_{DC\_MIN}^2 \times t_1^2 \times \eta}{2P_{OUT} \times t_s} \\
 &= \frac{380V^2 \times 4.608\mu s^2 \times 0.92}{2 \times 42W \times 18.18\mu s} \\
 &= 1847\mu H
 \end{aligned}$$

Set

$$L_M = 1800\mu H$$

(e) Compute the quasi-resonant time  $t_3$

$$\begin{aligned}
 t_3 &= \pi \times \sqrt{L_M \times C_{Drain}} \\
 &= \pi \times \sqrt{1800\mu H \times 100pF} \\
 &\approx 1333ns
 \end{aligned}$$

(f) Compute primary maximum peak current  $I_{P\_PK\_MAX}$

$$\begin{aligned}
 I_{P\_PK\_MAX} &= \frac{P_{OUT} \times \left[ \frac{L_M}{V_{DC\_MIN}} + \frac{L_M}{N_{PS} \times (V_{OUT} + V_{D,F})} \right]}{L_M \times \eta} + \frac{\sqrt{P_{OUT}^2 \times \left[ \frac{L_M}{V_{DC\_MIN}} + \frac{L_M}{N_{PS} \times (V_{OUT} + V_{D,F})} \right]^2 + 2L_M \times \eta \times P_{OUT} \times t_3}}{L_M \times \eta} \\
 &= 1.015A
 \end{aligned}$$

Adjust switching period  $t_s$  and ON time  $t_1$  to  $t'_s$  and  $t'_1$ .

$$\begin{aligned}
 t'_s &= \frac{\eta \times L_M \times I_{P\_PK\_MAX}^2}{2P_{OUT}} \\
 &= \frac{0.92 \times 1800\mu H \times 1.015A^2}{2 \times 42W} \\
 &= 20.31\mu s
 \end{aligned}$$

$$\begin{aligned}
 t'_1 &= \frac{L_M \times I_{P\_PK\_MAX}}{V_{DC\_MIN}} \\
 &= \frac{1800\mu H \times 1.015A}{380V} \\
 &= 4.806\mu s
 \end{aligned}$$

Compute primary maximum RMS current  $I_{P\_RMS\_MAX}$

$$I_{P\_RMS\_MAX} \approx \sqrt{\frac{t'_1}{3t'_s}} \times I_{P\_PK\_MAX} = \sqrt{\frac{4.806\mu s}{6 \times 20.31\mu s}} \times 1.015A = 0.285A$$

(g) Compute secondary maximum peak current and the maximum RMS current.

$$I_{S\_PK\_MAX} = N_{PS} \times I_{P\_PK\_MAX} = 3.0 \times 1.015A = 3.045A$$

$$t_2 = t'_s - t'_1 - t_3 = 20.31\mu s - 4.806\mu s - 1.333\mu s = 14.171\mu s$$

$$I_{S,RMS,MAX} \approx \sqrt{\frac{t'_2}{3t'_S}} \times I_{S,PK,MAX} = \sqrt{\frac{14.171\mu s}{3 \times 20.31\mu s}} \times 3.045A = 1.468A$$

### #3. Select power MOSFET and secondary power diode

Refer to Power Device Design

Known conditions at this step			
$V_{DC,MAX}$	450V	$N_{PS}$	3.0
$V_{OUT}$	42V	$V_{D,F}$	1V
$\Delta V_S$	50V	$\eta$	92%

(a) Compute the voltage and the current stress of MOSFET:

$$\begin{aligned} V_{MOS,DS,MAX} &= V_{DC,MAX} + N_{PS} \times (V_{OUT} + V_{D,F}) + \Delta V_S \\ &= 450V + 3.0 \times (42V + 1V) + 50V \\ &= 629V \end{aligned}$$

$$I_{MOS,PK,MAX} = I_{P,PK,MAX} = 1.015A$$

$$I_{MOS,RMS,MAX} = I_{P,RMS,MAX} = 0.285A$$

(b) Compute the voltage and the current stress of secondary power diode

$$\begin{aligned} V_{D,R,MAX} &= \frac{V_{DC,MAX}}{N_{PS}} + V_{OUT} \\ &= \frac{450V}{3.0} + 42V \\ &= 192V \end{aligned}$$

$$I_{D,PK,MAX} = N_{PS} \times I_{P,PK,MAX} = 3.0 \times 1.015A = 3.045A$$

$$I_{D,AVG} = I_{OUT} = 1A$$

### #4. Set VIN pin

Refer to **Start up**

Conditions			
$V_{DC,MIN}$	380V	$V_{DC,MAX}$	450V
$I_{ST}$	34 $\mu$ A (typical)	$V_{IN,ON}$	22V (typical)
		$t_{ST}$	500ms (designed by user)

(a)  $R_{ST}$  is preset

$$R_{ST} < \frac{V_{DC,MIN}}{I_{ST}} = \frac{380V}{34\mu A} = 11.17M\Omega,$$

$$R_{ST} > \frac{V_{DC,MAX}}{1mA} = \frac{450V}{1mA} = 450k\Omega,$$



Set  $R_{ST}$

$$R_{ST} = 510k\Omega \times 2 = 1020k\Omega$$

(b) Design  $C_{VIN}$

$$C_{VIN} = \frac{\left(\frac{V_{DC\_MIN}}{R_{ST}} - I_{ST}\right) \times t_{ST}}{V_{VIN\_ON}}$$

$$= \frac{\left(\frac{380}{1020k\Omega} - 34\mu A\right) \times 500ms}{22V}$$

$$= 7.694\mu F$$

Set  $C_{VIN}$

$$C_{VIN} = 4.7\mu F$$

#5. Set COMP pin

Refer to **Internal pre-charge design for quick start up**

Parameters designed			
$R_{COMP}$	1.5k $\Omega$		
$C_{COMP1}$	10nF		

#6. Set current sense resistor to achieve ideal output current

Refer to **Primary-side constant-current control**

Known conditions at this step			
k	0.167	$N_{PS}$	30
$V_{REF}$	0.6	$I_{OUT}$	1A

The current sense resistor is

$$R_S = \frac{k \times V_{REF} \times N_{PS}}{I_{OUT}}$$

$$= \frac{0.167 \times 0.6V \times 3.0}{1A}$$

$$= 0.3\Omega$$

#7. Set ZCS pin

Refer to **Over Voltage Protection (OVP) & Open Loop Protection (OLP)**

Parameters Designed			
$R_{ZCSU}$	200k $\Omega$		

Then compute  $R_{ZCSD}$

$$V_{IN\_CV} = \frac{0.5 \cdot (R_{ZCSU} + R_{ZCSD})}{R_{ZCSD}} \geq 11$$

$$\frac{0.5}{10.5} \geq \frac{R_{ZCSD}}{R_{ZCSU}}$$

$R_{ZCSUP} = 200k \text{ ohm}$

$$R_{ZCSD} \leq 9.5$$

$R_{ZCSD}$  is set to

$$R_{ZCSD} = 8.2k\Omega$$

#8. Set ADIM pin

$$C_{ADIM} = \frac{1.0 \times 10^{-3}}{f_{PWM}} F \times Hz = \frac{1.0 \times 10^{-3}}{f_{PWM}} F \times Hz = 1\mu F$$

Hence  $C_{ADIM}$  is set to

$$C_{ADIM} = 1\mu F$$

#9. Final result

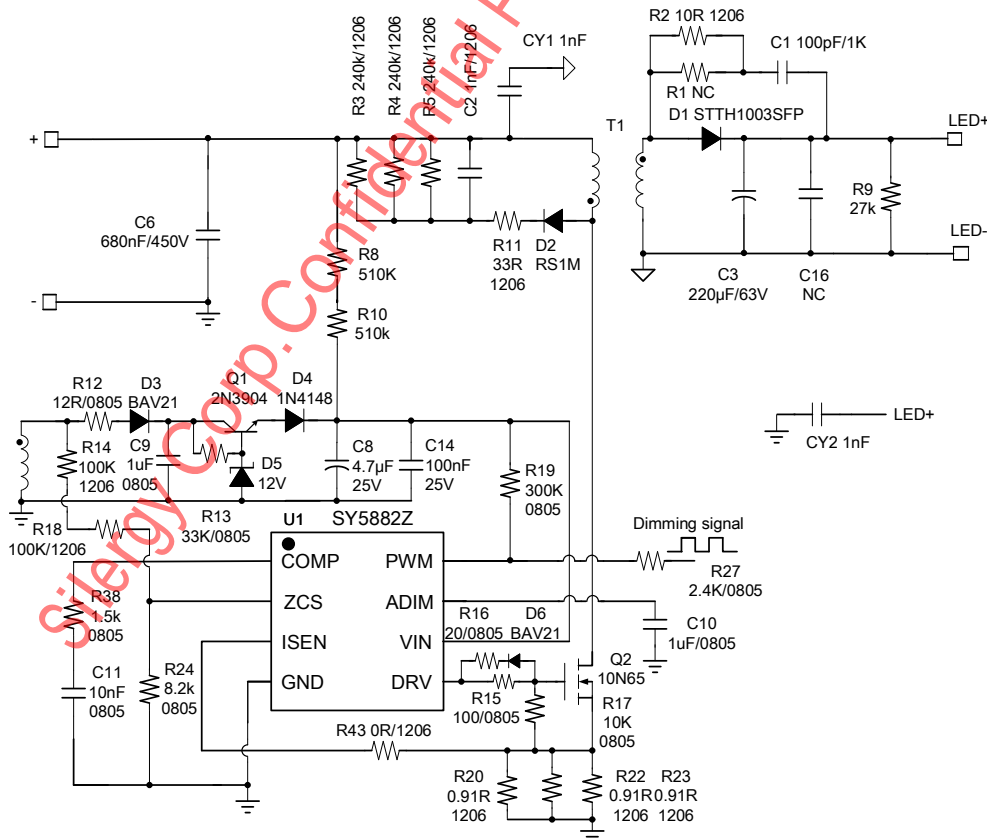
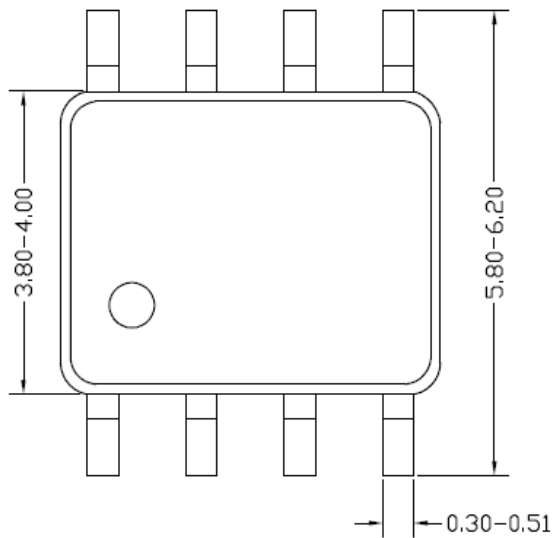
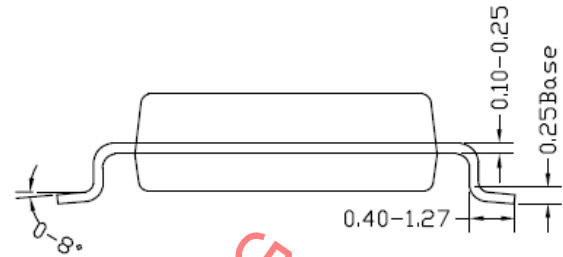


Fig.18 Final Design Result

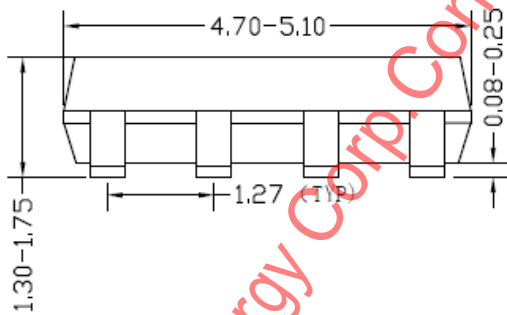
## S08 Package outline & PCB layout design



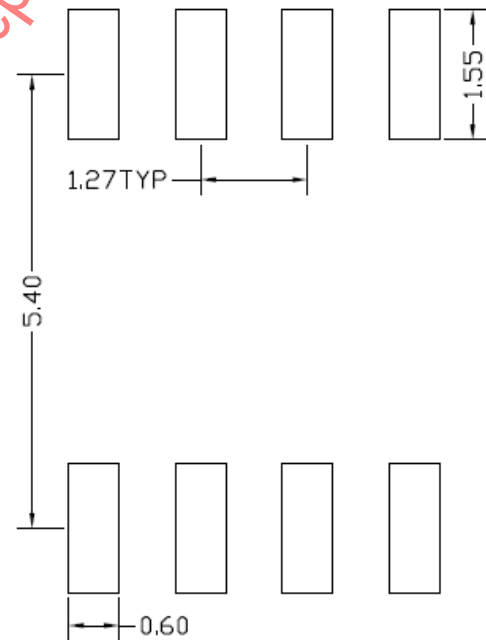
Top view



Side view



Front view



Recommended Pad Layout  
(Reference only)

**Notes: All dimension in millimeter and exclude mold flash & metal burr.**

## Revision History

The revision history provided is for informational purpose only and is believed to be accurate, however, not warranted. Please make sure that you have the latest revision.

Date	Revision	Change
May 7,2020	Revision 0.9	Initial Release

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