

MSKSEMI 美森科

SEMICONDUCTOR



ESD



TVS



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PLED

XC6202PXXXMR-MS

Product specification

GENERAL DESCRIPTION

XC6202PXXXMR-MS series are a set of Low Dropout Linear Regulator ICs implemented in CMOS technology. They can withstand voltage 20V. And they are available with low voltage drop and low quiescent current, widely used in audio, video and communication appliances.

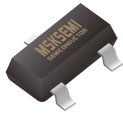
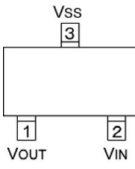
FEATURES

- Low Power Consumption
- Low Voltage Drop
- Low Temperature Coefficient
- Withstanding Voltage 20V
- Quiescent Current 2.0μA
- Output Voltage Accuracy: tolerance ±2%
- High output current: 150mA

TYPICAL APPLICATIONS

- Battery-powered Equipments
- Communication Equipments
- Audio/Video Equipments
- Smart Battery Packs
- Smoke Detectors
- CO2 DETECTORS

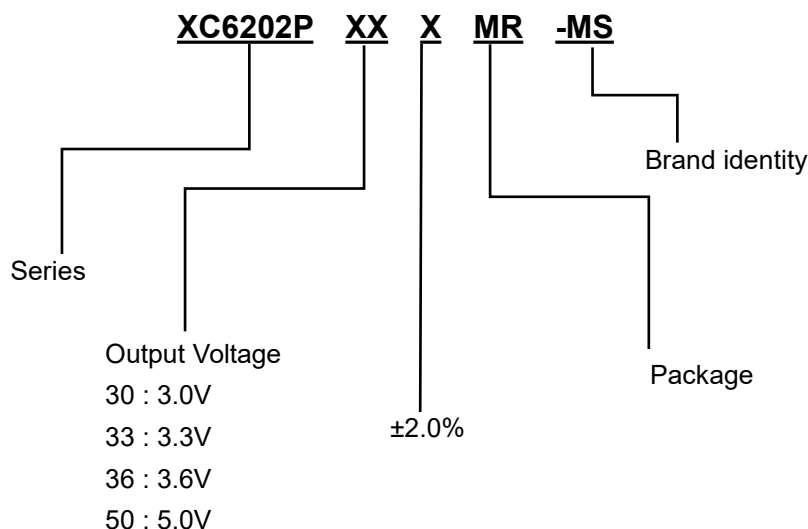
PACKAGE/ORDER INFORMATION

Part Number	Package		Pin Configuration	Marking	QTY
XC6202P302MR-MS	SOT-23			24ZX	3000
XC6202P332MR-MS				252A	3000
XC6202P362MR-MS				255B	3000
XC6202P502MR-MS				25MX	3000

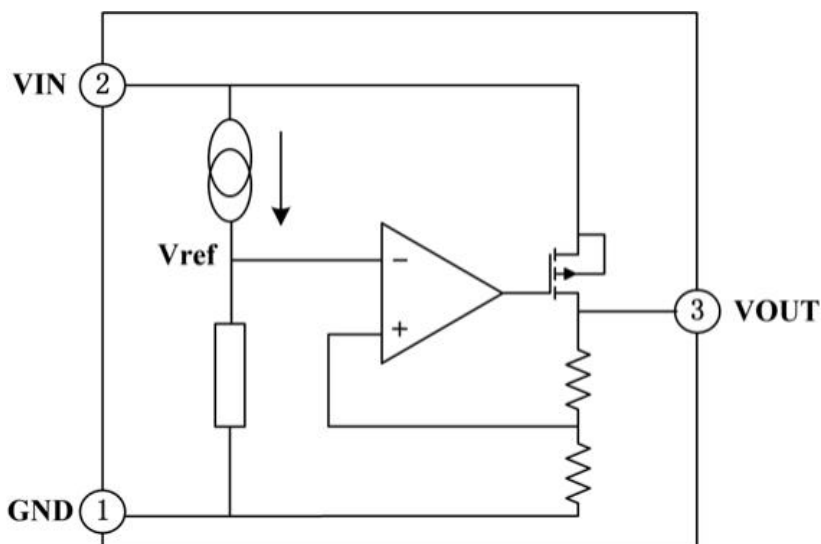
PIN DESCRIPTION

PIN No.	Name	Functions Description
SOT-23-L		
3	GND	ground
2	V _{IN}	input
1	V _{OUT}	output

PRODUCT NAMING



FUNCTIONAL BLOCK DIAGRAM



ABSOLUTE MAXIMUM RATINGS

Description	Symbol	Value range	Unit
Limit Power Voltage	V_{IN}	-0.3 ~ +22	V
Storage Temperature Range	T_{STG}	-50 ~ +125	°C
Operating Free-air Temperature Range	T_A	-40 ~ +85	°C

Note: Stresses greater than those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under “Recommended Operating Conditions” is not implied. Exposure to “Absolute Maximum Ratings” for extended periods may affect device reliability.

HEAT DISSIPATION

Description	Symbol	Package	Value range	Unit
Thermal resistance	θ_{JA}	SOT-23	500	$^{\circ}\text{C/W}$
Power dissipation	PW	SOT-23	200	mW

DC CHARACTERISTICS (unless otherwise noted $T_A = +25^{\circ}\text{C}$)

($V_{IN} = V_{OUT} + 2.0\text{V}$, $C_{IN} = C_L = 10\mu\text{F}$, $T_A = 25^{\circ}\text{C}$, unless otherwise noted)

Series +3.0V OUTPUT

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Output Voltage	V_{OUT}	$V_{IN} = V_{OUT} + 2.0\text{V}$, $I_{OUT} = 10\text{mA}$	2.94	3.0	3.06	V
Output Current	I_{OUT}	$V_{IN} = V_{OUT} + 2.0\text{V}$	70	100	—	mA
Load Regulation	ΔV_{OUT}	$V_{IN} = V_{OUT} + 2.0\text{V}$ $1\text{mA} \leq I_{OUT} \leq 50\text{mA}$	—	25	60	mV
Voltage Drop	V_{DIF}	$I_{OUT} = 1\text{mA}$, $\Delta V_{OUT} = 2\%$	—	30	100	mV
Quiescent Current	I_{SS}	—	—	2.0	3.0	μA
Line Regulation	$\frac{\Delta V_{OUT}}{V_{OUT}} \cdot \Delta V_{IN}$	$V_{OUT} + 1.0\text{V} \leq V_{IN} \leq 20\text{V}$, $I_{OUT} = 1\text{mA}$	—	—	0.2	%/V
Input Voltage	V_{IN}	—	—	—	24	V
Temperature Coefficient	$\frac{\Delta V_{OUT}}{\Delta T_A} \cdot V_{OUT}$	$V_{IN} = V_{OUT} + 2.0\text{V}$, $I_{OUT} = 10\text{mA}$, $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$	—	± 100	—	ppm/ $^{\circ}\text{C}$

Note : When $V_{IN} = V_{OUT} + 2.0\text{V}$, as the output voltage declined 2%, the $V_{DIF} = V_{IN} - V_{OUT}$.

Series +3.3V OUTPUT

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Output Voltage	V_{OUT}	$V_{IN} = V_{OUT} + 2.0\text{V}$, $I_{OUT} = 10\text{mA}$	3.23	3.3	3.36	V
Output Current	I_{OUT}	$V_{IN} = V_{OUT} + 2.0\text{V}$	70	100	—	mA
Load Regulation	ΔV_{OUT}	$V_{IN} = V_{OUT} + 2.0\text{V}$ $1\text{mA} \leq I_{OUT} \leq 50\text{mA}$	—	25	60	mV
Voltage Drop	V_{DIF}	$I_{OUT} = 1\text{mA}$, $\Delta V_{OUT} = 2\%$	—	25	55	mV
Quiescent Current	I_{SS}	—	—	2.0	3.0	μA
Line Regulation	$\frac{\Delta V_{OUT}}{V_{OUT}} \cdot \Delta V_{IN}$	$V_{OUT} + 1.0\text{V} \leq V_{IN} \leq 20\text{V}$, $I_{OUT} = 1\text{mA}$	—	—	0.2	%/V
Input Voltage	V_{IN}	—	—	—	24	V
Temperature Coefficient	$\frac{\Delta V_{OUT}}{\Delta T_A} \cdot V_{OUT}$	$V_{IN} = V_{OUT} + 2.0\text{V}$, $I_{OUT} = 10\text{mA}$, $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$	—	± 100	—	ppm/ $^{\circ}\text{C}$

Note : When $V_{IN} = V_{OUT} + 2.0\text{V}$, as the output voltage declined 2%, the $V_{DIF} = V_{IN} - V_{OUT}$.

Series +3.6V OUTPUT

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Output Voltage	V_{OUT}	$V_{IN}=V_{OUT}+2.0V$, $I_{OUT}=10mA$	3.52	3.6	3.67	V
Output Current	I_{OUT}	$V_{IN}=V_{OUT}+2.0V$	70	100	—	mA
Load Regulation	ΔV_{OUT}	$V_{IN}=V_{OUT}+2.0V$ $1mA \leq I_{OUT} \leq 50mA$	—	25	60	mV
Voltage Drop	V_{DIF}	$I_{OUT}=1mA$, $\Delta V_{OUT}=2\%$	—	25	55	mV
Quiescent Current	I_{SS}	—	—	2.0	3.0	μA
Line Regulation	$\frac{\Delta V_{OUT}}{V_{OUT}} \cdot \Delta V_{IN}$	$V_{OUT}+1.0V \leq V_{IN} \leq 20V$, $I_{OUT}=1mA$	—	—	0.2	%/V
Input Voltage	V_{IN}	—	—	—	24	V
Temperature Coefficient	$\frac{\Delta V_{OUT}}{\Delta T_A} \cdot V_{OUT}$	$V_{IN}=V_{OUT}+2.0V$, $I_{OUT}=10mA$, $-40^{\circ}C \leq T_A \leq 85^{\circ}C$	—	± 100	—	ppm/ $^{\circ}C$

Note : When $V_{IN}=V_{OUT}+2.0V$, as the output voltage declined 2%, the $V_{DIF}=V_{IN}-V_{OUT}$.

Series +5.0V OUTPUT

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Output Voltage	V_{OUT}	$V_{IN}=V_{OUT}+2.0V$, $I_{OUT}=10mA$	4.9	5.0	5.1	V
Output Current	I_{OUT}	$V_{IN}=V_{OUT}+2.0V$	100	150	—	mA
Load Regulation	ΔV_{OUT}	$V_{IN}=V_{OUT}+2.0V$ $1mA \leq I_{OUT} \leq 70mA$	—	25	60	mV
Voltage Drop	V_{DIF}	$I_{OUT}=1mA$, $\Delta V_{OUT}=2\%$	—	25	55	mV
Quiescent Current	I_{SS}	—	—	2.0	3.0	μA
Line Regulation	$\frac{\Delta V_{OUT}}{V_{OUT}} \cdot \Delta V_{IN}$	$V_{OUT}+1.0V \leq V_{IN} \leq 12V$, $I_{OUT}=1mA$	—	—	0.2	%/V
Input Voltage	V_{IN}	—	—	—	24	V
Temperature Coefficient	$\frac{\Delta V_{OUT}}{\Delta T_A} \cdot V_{OUT}$	$V_{IN}=V_{OUT}+2.0V$, $I_{OUT}=10mA$, $-40^{\circ}C \leq T_A \leq 85^{\circ}C$	—	± 100	—	ppm/ $^{\circ}C$

Note : When $V_{IN}=V_{OUT}+2.0V$, as the output voltage declined 2%, the $V_{DIF}=V_{IN}-V_{OUT}$.

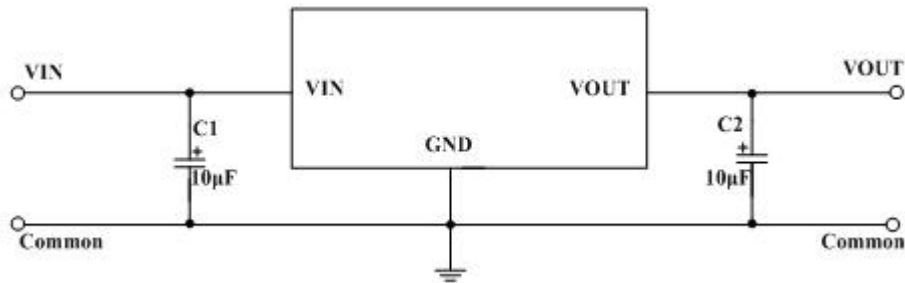
FUNCTIONAL DESCRIPTION

XC6202PXXXMR-MS series are linear voltage regulator ICs withstanding 20V voltage. The series IC consists of a voltage reference, an error amplifier, a current limiter and a phase compensation circuit plus a driver transistor. The output stabilization capacitor is also compatible with low ESR ceramic capacitors.

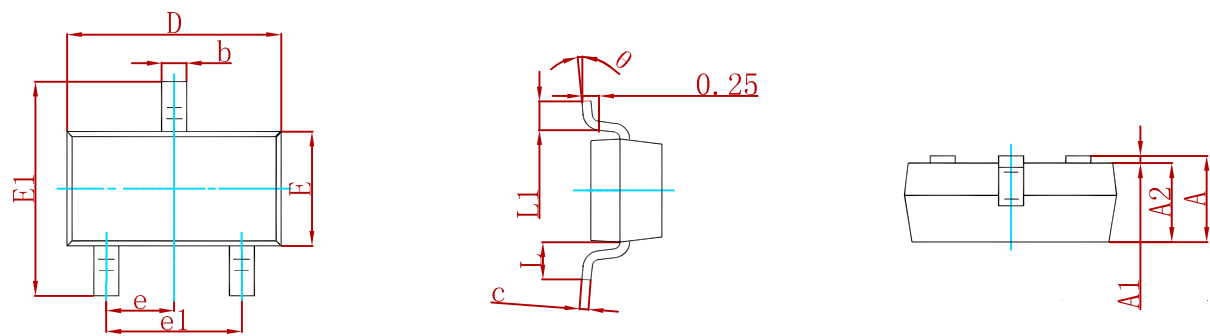
The over current protection circuit and the over voltage protection circuit are built-in. The protection circuit will operate when the output current or input voltage reaches limit level.

TYPICAL APPLICATION CIRCUIT

Basic Circuit

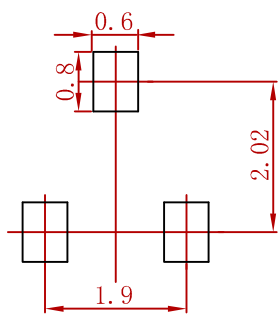


PACKAGE MECHANICAL DATA



Symbol	Dimensions In Millimeters		Dimensions In Inches	
	Min	Max	Min	Max
A	0.900	1.150	0.035	0.045
A1	0.000	0.100	0.000	0.004
A2	0.900	1.050	0.035	0.041
b	0.300	0.500	0.012	0.020
c	0.080	0.150	0.003	0.006
D	2.800	3.000	0.110	0.118
E	1.200	1.400	0.047	0.055
E1	2.250	2.550	0.089	0.100
e	0.950 TYP		0.037 TYP	
e1	1.800	2.000	0.071	0.079
L	0.550 REF		0.022 REF	
L1	0.300	0.500	0.012	0.020
θ	0°	8°	0°	8°

Suggested Pad Layout



- Note:
- 1. Controlling dimension: in millimeters.
 - 2. General tolerance: ± 0.05mm.
 - 3. The pad layout is for reference purposes only.

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