













ESD

TVS

TSS

MOV

GDT

PLED



Product specification







产品概述

TMI8260SP-MS 是一款 DC 双向马达驱动电路,它适用 玩具等类的电机驱动、自动阀门电机驱动、电磁门锁 驱等。它有两个逻辑输入端子用来控制电机前进、后 退及制动。该电路具有良好的抗干扰性,微小的待机 电流、低的输出内阻,同时,它还具有内置二极管能 释放感性负载的反向冲击电流。

TMI8260SP-MS 的封装形式是 SOP-8, 符合 ROHS 规范, 引脚框架 100%无铅。

特征

- 驱动一路有刷直流电机
- 微小的待机电流,小于 1uA
- 低 RDS (ON) 电阻
- 最大输出持续电流 5.0A
- 工作电压范围: 3.0V-18V
- 有紧急停止功能
- 有过热保护功能
- 有过流嵌流及短路保护功能
- 封装: SOP-8

应用

- 电子锁
- 玩具
- 无线充电
- 机器人

包装和订单信息

产品编号	封装		管体标记	最小包装(PCS)
TMI8260SP-MS	SOP-8	T	MSKSEMI 8260SP-MS ●	4000



脚位定义



图 1. 顶视图

引脚名称	输入/输出	描述	引脚编号
BI	输入	后退输入	1
FI	输入	前进输入	2
GND	电源	地	3
VCC	电源	功率电源	4
FO	输出	前进输出	5,6
BO	输出	后退输出	7,8

绝对最大额定值

最大工作温度范围(除非另有说明)⁽¹⁾⁽²⁾

参数	符号	数值	单位
电源电压	VCC	20	V
输出持续电流	lout	9.0	А
工作温度	Тор	-25~+85	°C
储存温度	Tstg	-55~+150	°C

(1)超出绝对最大额定值的范围可能对设备造成永久性损坏。这些只是等级强调。在那些任何其他超过建议条件下的芯片功能未说明。长时间暴露在绝对最大额定值的条件下可能影响芯片的可靠性。

(2)所有电压值都对应接地端子。

(3) 基于 40mm2 单面 PCB,FR4 PCB(1 oz.)

推荐工作条件(TA=25℃)

参数	符号	最小	典型	最大	单位
工作电压范围	VCC	3	-	18	V
输入信号电压 INH and INL	VINH	-0.3	-	18	V
输出持续电流	V _{OUT_X}	0	-	5.0*	А
逻辑输入频率	F _{IN_X}	-	-	30	KHz

*基于 40mm2 单面 PCB,FR4 PCB(1 oz.)

电特性参数

如无特殊规定,T_A=25℃

参数	符号	条件	最小	典型	最大	单位
电源参数						
工作电压	Vopr		3.0	-	18	V
待机电流	I _{CCST}	VCC=12V,FI=BI=0V,noload	-	-	1	uA
静态电流	lcc	VCC=12V,FI=BI=5V or FI=5V & BI=0V or FI=0V & BI=5V, no load	-	1.0	-	mA
PWM 电流	I _{CCPWM1}	VCC=12V, FI=5V, BI=50KHz, no load	-	2.5	-	mA
低压保护	UVLO	VCC rising	1.9	2.2	2.8	V
逻辑输入参数						
输入高电平	V _{INH}		2.2	-	-	V
输入低电平	VINL		-	-	0.7	V
输入高电平时电流	l _{inh}	VCC = 12V,VIN = 5V	-	110	200	uA
输入低电平时电流	I _{INL}	VCC = 12V,VIN= 0V	-	-	1	uA
H-bridge FETs 参数						
	R _{ds(on)}	I _{LOAD} =1A, HS+LS	-	58	-	mΩ
	R _{ds(on)}	I _{LOAD} =3A, HS+LS	-	71	-	mΩ
过热温保护参数						
过热保护温度	T _{OTP}		-	160	-	°C
恢复工作温度	TSD _R		-	130	-	°C
过流保护参数						
过流保护电流	I _{OCP}		-	12	-	А



框图



功能描述

输出真值表

FI	BI	FO	BO	状态
Н	L	Н	L	前进
L	Н	L	Н	后退
Н	Н	L	L	刹车
L	L	Open	Open	停止

输出时序图





应用电路



图 4. 应用原理图

应用电路说明

应用电路上的挂载组件,说明如下:

C1,C2 为 VCC 输入电容

- 1) 吸收马达向电源释放的能量,稳定电源电压,避免 IC 因突波电压过高而被直接击穿,且有滤波之功能。
- 2) 在马达启动的瞬间,能释放电流,帮助马达迅速启动。
- 3) VCC 输入电容 C2 的选择需依照 VCC 的电压稳定性及马达负载电流大小去选择电容,如果 VCC 的电压文波 较大或是马达负载电流较大,则须选择更大的电容值。

4) 在 PCB 配置上 C1,C2 电容需要尽量靠近 VCC。

BI,FI 输入端建议悬空,避免高温时,由于 IC 本体 P/N 接面间存在微弱漏电流,该漏电流流过下拉电阻会导致 悬空引脚的输入电位由低电位变高电位,造成电路输出错误的信号。

工作模式说明

基本工作模式

a)前进模式

前进模式定义: BI=L, FI=H, 此时 BO=L, FO=H

b)后退模式

后退模式定义: BI=H, FI=L, 此时 BO=H, FO=L

c) 刹车模式

刹车模式定义: BI=H, FI=H, 此时 BO=L, FO=L

d)停止模式

停止模式定义: BI=L, FI=L, 此时 BO=Open, FO=Open



TMI8260SP-MS



保护机制说明

1) 使用此 IC 时,当 IC 温度超过 150℃(典型值),此是内置设计的 IC 过热保护电路会强制关闭部分驱动 MOS 晶体管,确保客户产品的安全。当 IC 温度降至 120℃(典型值)是,IC 会迅速自动恢复开始工作。

上电时序



图 5. 上电时序图

如图 5,在 VCC 上电之前,BI / FI 必须保持低电平或无输入高阻状态,不能对 BI / FI 输入高电平,直到 VCC 上电并延时 3ms (t_D) 后,才能对 BI / FI 进行逻辑控制;

输入控制时序



图 6. 上电时序图

如图 6, 输入控制脚 BI / FI 的频率不能超过 30kHz, t_H + t_L > 33us。同时需要注意, t_H 和 t_L 都不能小于 100ns

MSKSEMI SEMICONDUCTOR

SOP-8



(Unit: mm)

Symbol	Min	Мах
A	1.300	1.600
A1	0.050	0.200
A2	0.550	0.650
A3	0.550	0.650
b	0.356	0.456
с	0.203	0.233
D	4.800	5.000
е	1.270(BSC)	
E	3.800	4.000
E1	5.800	6.200
L	0.400	0.800
θ	0°	8°



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