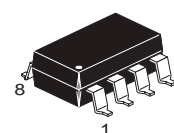


## CMOS Real-time clock/calendar

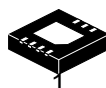
Microcircuit HT4337A is essentially the complete binary-decimal digital watch with calendar, alarm, timer and possesses low power consumption. Addresses and data are transferred in series via the double wire bi-directional bus. The microcircuit is intended for count of real time in hours, minutes and seconds, count of week days, date, month and year. The last day of the month is automatically adjusted for the months with fewer, than 31 days, including correction for the leap year. The watch functions in the 24 hour mode. The microcircuit HT4337A has the built-in power control circuit, which determines the power level < 1V and forms the bit, signaling, that information about the real time may not be correct.

### Functions and Features

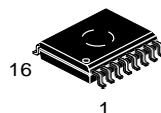
- count of seconds, minutes, hours, week days, date, months and years with consideration of leap years (until 2100);
- 400 kHz, double wire serial interface;
- programmed orthogonal output signal;
- function programming of alarm, timer and interruption;
- automatic determination of the supply voltage drop;
- consumption current of less, than 450 nA with supply of 2V with the operating oscillator;
- operating temperature range: -40°C – +85 °C.



**DUB8 U**  
**SUFFIX**  
**HT4337ARUZ**



**DFN8(5\*6) D**  
**SUFFIX**  
**HT4337ARDZ**

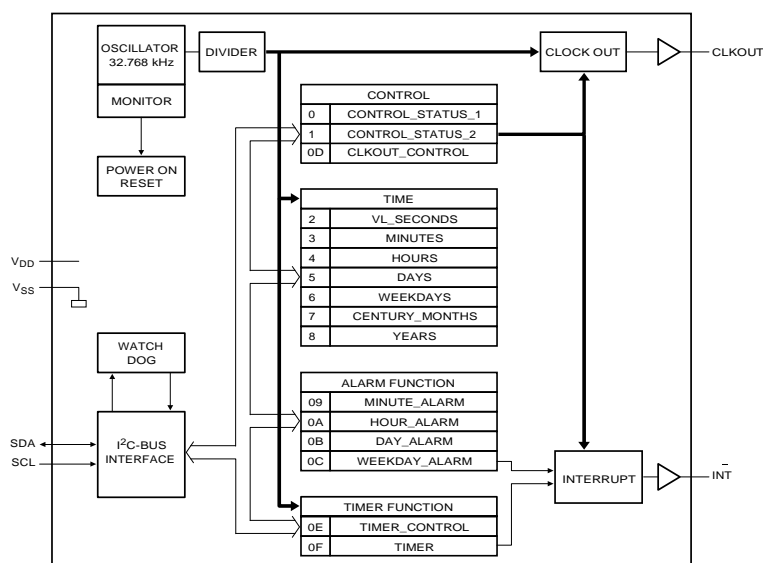


**WSOP16 W**  
**SUFFIX**  
**HT4337ARWZ**

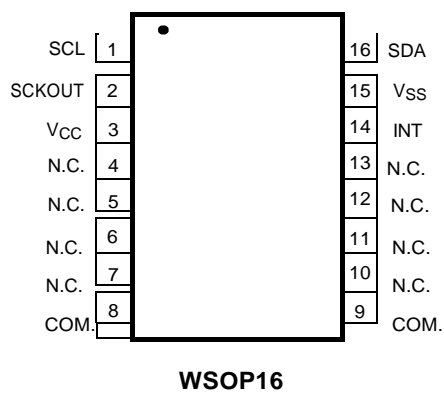
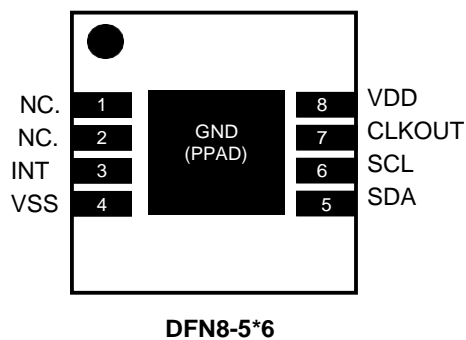
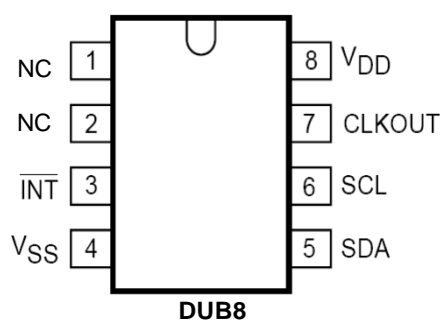
**T<sub>A</sub> = -40°C to +85°C**

**NOTE: If you need to customize the packaging shape, please contact the manufacturer.**

### Tructural Diagram HT4337A



## Pin Configuration and Functions



## Pin Functions

Identification	Purpose of Pin
INT	Interruption output
V <sub>SS</sub>	Common pin
SDA	Input / Output of data
SCL	Synchrosignal input
CLKOUT	Frequency divider output
V <sub>DD</sub>	Supply source pin

**Operating temperature range HT4337A**

Operating temperature range of the microcircuit HT4337A:  $T_A = -40 \dots +85 \text{ }^{\circ}\text{C}$ .

**Limit operating mode HT4337A**

Limit and limit permissible operating modes of the microcircuit HT4337A are listed in the table

Parameter Description, Measurement Unit	Identifi- cation	Norm			
		Limit Permissible		Limit	
		Not less	Not over	Not less	Not over
Supply voltage, V	$V_{DD}$	1.0	5.5	-0.5	6.5
Dissipated power, mWt	$P_{tot}$	-	-	-	300
Input voltage SCL, SDA, OSCI, V	$V_I$	0	5.5	-0.5	6.5
Output voltage CLKOUT, INT, V	$V_O$	0	5.5	-0.5	6.5
Direct input or output current via any pin, mA	$I_{IO}$	-	-	-10	10

All voltages are listed relative to ground. Under influence of the limit mode serviceability of the microcircuits is not guaranteed. After plotting the limit mode serviceability is guaranteed in the limit permissible mode.

**Electric Parameters HT4337A**

Electric parameters of the microcircuit HT4337A at the temperature of  $T_A = -40 \dots +85 \text{ }^{\circ}\text{C}$ ,

$V_{CC} = 4.5 - 5.5 \text{ B}$  are indicated in the table

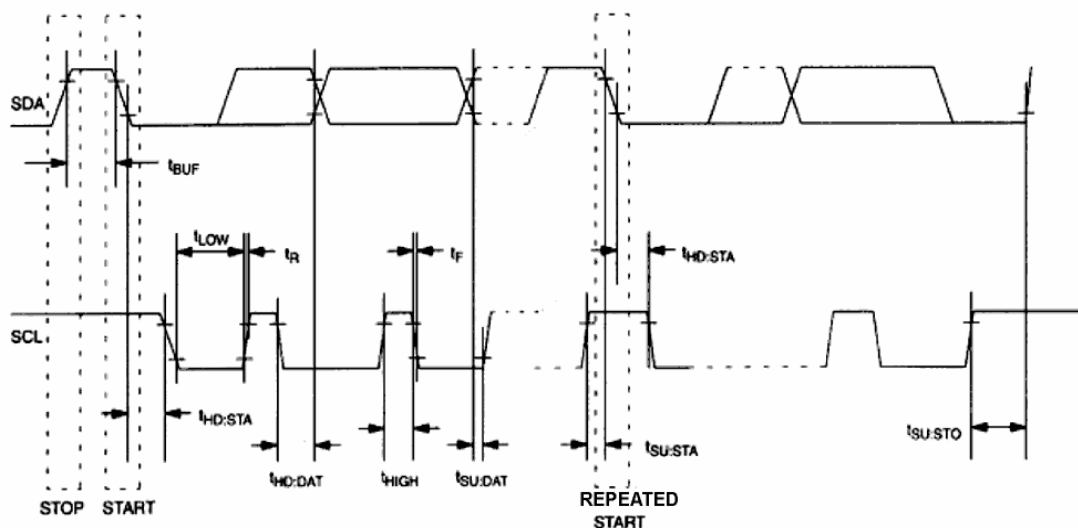
Parameter Description, Measurement Unit	Identifi- cation	Measurement Mode	Norm		Remark
			Not less	Not over	
1	2	3	4	5	6
Supply voltage, V	$V_{DD}$	I2C bus –active; $F_{SCL} = 400 \text{ kHz}$	1.8	5.5	
		in the non-active mode	1.0	5.5	1,2
Input leakage current, $\mu\text{A}$	$I_{LI}$	$V_{IN} = V_{DD}; V_{IN} = V_{SS}$	-	1	
Output leakage current, $\mu\text{A}$	$I_{LO}$	$V_{OUT} = V_{DD}; V_{OUT} = V_{SS}$	-	1	
Consumption current, $\mu\text{A}$	$I_{DD1}$	CLKOUT–off, $F_{SCL} = 400 \text{ kHz}$	-	800	
		CLKOUT–off, $F_{SCL} = 100 \text{ kHz}$	-	200	
		CLKOUT–off, $F_{SCL} = 0 \text{ kHz}, V_{DD} = 5\text{V}$	-	0.55	1,2
		CLKOUT–off, $F_{SCL} = 0 \text{ kHz}, V_{DD} = 2\text{V}$	-	0.45	1,2
Low level input voltage, V	$V_{IL}$		$V_{SS}$	$0.3V_{DD}$	
High level input voltage, V	$V_{IH}$		$0.7V_{DD}$	$V_{DD}$	
Low level output current at pin CLKOUT, mA	$I_{OL1}$	$V_{OL} = 0.4 \text{ V}, V_{DD} = 5 \text{ V}$	1	-	
High level output current at pin CLKOUT, mA	$I_{OH1}$	$V_{OH} = 4.6 \text{ V}, V_{DD} = 5 \text{ V}$	1	-	
Low level output current at pin INT, mA	$I_{OL2}$	$V_{OL} = 0.4 \text{ V}, V_{DD} = 5 \text{ V}$	1	-	

1	2	3	4	5	6
Low level output current at pin SDA, mA	$I_{OL3}$	$VOL = 0.4 V, VDD = 5 V$	3	-	
Supply low level, detected by the circuit, V	$V_{LOW}$			1	1
Remarks 1 $T_A = (25 \pm 5)^\circ C$ 2 Parameters of the quartz oscillator: $f_{OSC} = 32.768 \text{ kHz}$ , $R_S \leq 40 \text{ k}\Omega$ , $C_L = 8 \text{ pF}$					

Dynamic parameters of the microcircuit HT4337A at the temperature  $T_A = -40 \dots + 85^\circ C$ ,  
 $V_{CC} = 4.5 - 5.5 \text{ V}$  are listed in the table

Parameter Description, Measurement Unit	Identification	Measurement Mode	Norm	
			Not less	Not over
Cycle frequency SCL, kHz	$f_{SCL}$	—	0	400
Time of bus vacant condition between the conditions STOP and START, usec	$t_{BUF}$	—	4.7	—
Hold time (repeated) of the condition START, usec	$t_{HD:STA}$	—	0.6	—
Low condition duration of the cycle pulse SCL, usec	$t_{LOW}$	—	1.3	—
High condition duration of the cycle pulse SCL, usec	$t_{HIGH}$	—	0.6	—
Presetting time for the repeated condition START, usec	$t_{SU:STA}$	—	0.6	—
Data hold time, usec	$t_{HD:DAT}^{2)}$	—	0	—
Data presetting time, nsec	$t_{SU:DAT}$	—	100	—
Rise time for signals SDA and SCL, nsec	$t_R$	—	—	300
Drop time for signals SDA and SCL, nsec	$t_F$	—	—	300
Presetting time for the condition STOP, usec	$t_{SU:STO}$	—	0.6	—
Total capacitance load on each bus line, pF	$C_B$	—	—	400
Capacity input/output, pF	$C_{I/O}$	—	10	10
Load capacitance of the quartz resonator, pF	$C_{LX}$	—	12.5	12.5
1) After this time interval the first cycle signal is formed; 2) The device should internally ensure the hold time, at least, 300 nsec for the signal SDA (relative to $V_{IHMIN}$ of the signal SCL) in order to overlap the indeterminacy area of the signal SCL drop front Maximum value $t_{HD:DAT}$ should be definite in that case, if the device does not increase duration of the low condition ( $t_{LOW}$ ) of the signal SCL				

### Timing diagramm



### HT4337A Operation description

HT4337A operates as the «slave» device on the serial bus. For access to it expedient to set the condition START and transfer after the register address the device identification code. The next registers can be address in series till the condition STOP is preset. With  $V_{CC}$  below 1.8 V, access granting to the device by the serial interface is not guaranteed. The current time is counted with the supply voltage  $1 \div 5.5$  V. When the supply level becomes lower, than 1V, the bit VL=1 is formed, signaling, that the information about the current time may be incorrect.

#### Description of Signals

$V_{DD}$  – connection of the constant supply.  $V_{DD}$  – input from +1 till +5 V. With supply < 1.8 V access to the interface circuit is not guaranteed.

INT – interruption output. Interruption condition is formed with coincidence of the current time with the alarm settings, or with attainment of the condition “0” of the timer countdown. Interruption, formed from the alarm, forms the continous signal, and from the timer can be both continous and pulse one.

SCL (Input of serial synchrosignal) – SCL is used for synchronization of the data transfer by the serial interface.

SDA (Input/Output of serial data) – SDA is input/output for the double wire serial interface. Output SDA is the open drain, for which the external load resistor is required to be connected.

CLKOUT (Former output of the orthogonal signal) – For output activation the bit FE is preset to “1”. CLKOUT generates the orthogonal signal of four different frequencies (1 Hz, 32 Hz, 1 kHz, 32 kHz). Output CLKOUT is essentially the open drain, for which the external load resistor is required to be connected.

OSCI, OSCO – connection of the standard quartz resonator for the frequency 32.768 kHz. Capacitance load of the internal oscillator for the quartz resonator is equal to

12 pF. HT4337A can operate from the external oscillator with the frequency 32.768 kHz. With this configuration the output OSC1 is connected to the signal external oscillator, and OSC0 is left unconnected.

### Watch and Calendar

Acquisition of information on time and date is performed by means of reading the appropriate register bytes. Presetting and time and calendar initialization is performed by means of the appropriate bytes. Information, contained in the time, calendar and alarm registers, is essentially the binary-decimal code. Bit 7 of register 2 is essentially the indication bit of the supply level decrease. < 1V (VL). When this bit = "1", this signifies, that the supply voltage was below the norm, and the information on the current time may be unreliable.

When switching power supply on, all register bits are preset to "0", with the exception of bits FE, VL, TD1, TD0, TESTC and AE, which are preset to "1".

When applying the signal "START" on the double wire bus, the current time transfer occurs from the counters to the auxiliary set of registers. The data on time are read out from these auxiliary registers, while the watch continue to operate. This eliminates the necessity in the repeated reading in case of updating the basic registers in the access process.

### Registers RTC HT4337A

Address	Data								Registers / Range	
	D7	D6	D5	D4	D3	D2	D1	D0		
00H	TEST 1	0	STOP	0	TEST C	0	0	0	Control 1	
01H	0	0	0	TI/TP	AF	TF	AIE	TIE	Control 2	
02H	VL	Tens of seconds			Units of seconds				Seconds	00 – 59
03H	x	Tens of minutes			Units of minutes				Minutes	00 – 59
04H	x	x	Tens of hours		Units of hours				Hours	00 – 23
05H	x	x	Tens of date		Units of date				Dates	01 – 31
06H	x	x	x	x	x	Day of week			Day of week	0 – 6
07H	C	x	x	10 M.	Units of month				Century / month	0-1/01-12
08H	Tens of years				Units of years				Year	00 – 99
09H	AE	Tens of minutes			Units of minutes				Minutes of alarm	00 – 59
0AH	AE	x	Tens of hours		Units of hours				Hours of alarm	00 – 23
0BH	AE	x	Tens of date		Units of date				Date of alarm	01 – 31
0CH	AE	x	x	x	x	Day of week			Week day of alarm	0 – 6
0DH	FE	x	x	x	x	x	FD1	FD0	Control of CLKOUT	
0EH	TE	x	x	x	x	x	TD1	TD0	Control of timer	
0FH	Value of timer								Timer	

## Control Registers

### Control Register 1

TEST1 (activation of test mode) – This bit, preset to logic “1”, activates the test mode, with logic “0” normal functioning of the circuit.

STOP – This bit, preset to logic “1” in the test mode perform the zero setting of all dividers, with logic “0” – normal functioning of the circuit.

TESTC (activation of the test mode) – This bit, preset to logic “1”, activates the test mode, with logic “0” normal functioning of the circuit.

### Control Register 2

TI/TP (formation of the pulse interruption signal at output INT) – This bit, preset to logic “0”, with appearance of the timer flag TF at output INT forms the constant interruption signal of the low level. The bit, preset to logic “1” at output INT, forms the interruption pulse signal (signal frequencies are listed in the table).

Timer Input Frequency (Hz)	Period INT (sec). <sup>[1]</sup>	
	N = 1 <sup>[2]</sup>	N > 1
4096	1/8192	1/4096
64	1/128	1/64
1	1/64	1/64
1/60	1/64	1/64

[1] TF and INT become active simultaneously.

[2] N – value, loaded to the timer register. Timer is stopped with N = 0.

AF (alarm flag) - bit, in logic “1” informs about interruption by actuation of the alarm, by means of software the bit AF can be reset only.

TF (timer flag) - bit, in logic “1” informs about interruption by actuation of the timer, by the software means the bit TF can be reset only.

AIE (activation of alarm) - bit, preset to logic “1”, activates operation of the alarm.

TIE (activation of timer) - bit, preset to logic “1”, activates operation of the alarm.

### Control Register CLKOUT.

FE (output activation CLKOUT): This bit, preset to logic “1”, activates output CLKOUT. Frequency of the output orthogonal signal is determined by the bits FD0 and FD1.

FD – bits determine the frequency of the output orthogonal signal, when output of the orthogonal signal is activated. The frequencies are listed in the table, which can be selected by bits FD.

FD1	FD0	Frequency CLKOUT
0	0	32.768 kHz
0	1	8.192 kHz
1	0	4.096 kHz
1	1	1 Hz

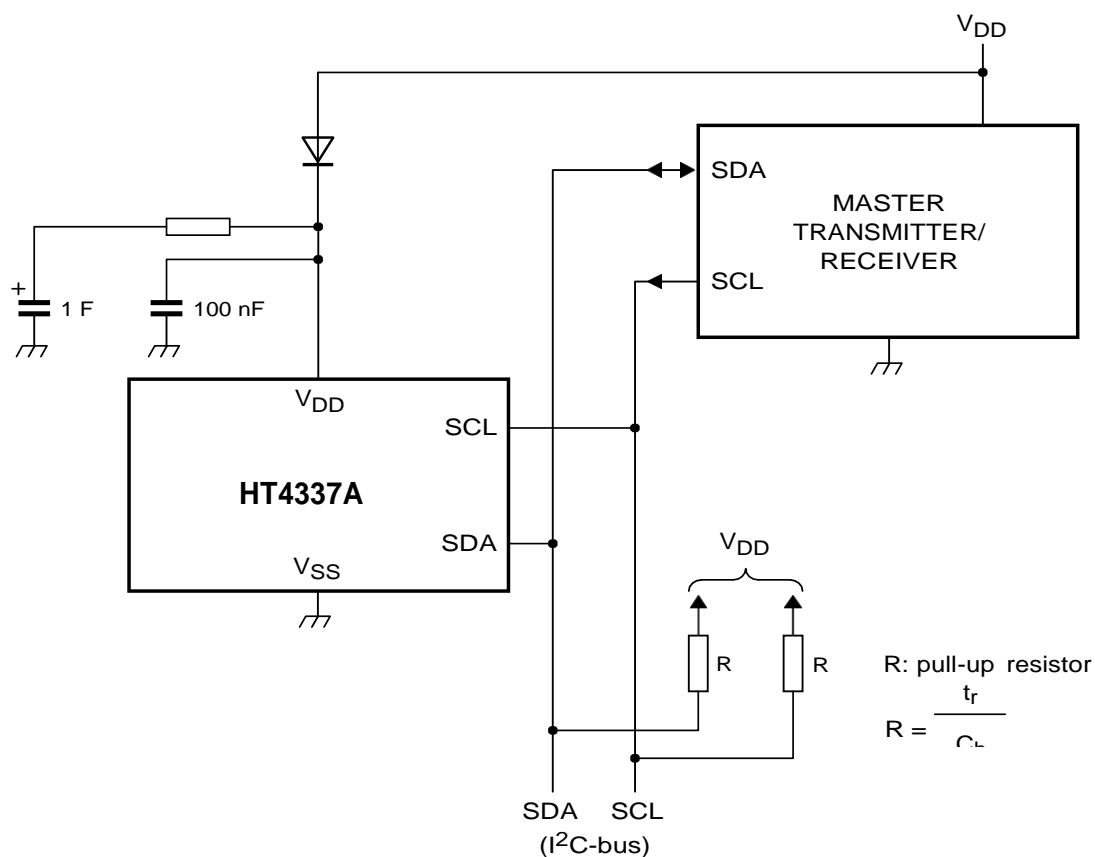
### Timer Control Register

TE (timer activation): This bit, preset to logic “1”, activates the frequency application to the timer input from the oscillator. The signal frequency is determined by bits TD0 and TD1.

TD1	TD0	Timer Input Frequency
0	0	4096 Hz
0	1	64 Hz
1	0	1 Hz
1	1	1 / 60 Hz

### Double Wire Serial Data Bus

HT4337A supports the bi-directional double wire bus and the data transfer protocol. The bus can be controlled by the “master” device, which generates the cycle signal (SCL), controls access to the bus, generates the conditions START and STOP. Typical bus configuration with the double wire is indicated in the Figure.





Data transfer can be started only when the bus is not busy. In the process of the data transfer, the data line should remain stable, while the cycle signal line is in the HIGH condition. Alterations of the data line conditions at that moment, when the cycle line is in the high condition, will be regarded as the control signals.

In compliance with this the following conditions are determined:

Bus is not busy: both lines of data and cycle signal are in the HIGH condition.

Data transfer start: Alteration of the data line condition during transition from HIGH to LOW, while the cycle line is in the HIGH condition, is determined as the status START.

Depending on the status of the bit  $R/W$ , two types of transfer are possible:

1. Data are transferred from the «master» transmitter to the «slave» receiver. The first byte, transferred by the «master» one, is the address of the «slave» one. Then follows sequence of the data bytes. The «slave» one returns the reception confirmation bits after each received byte. Order of the data transfer: the first one is the most senior digit (MSB).

2. Data are transferred from the «slave» transmitter to the «master» receiver. The first byte (address of «slave») is transferred to the «master» one. Then the «master» returns the confirmation bit. This follows after the «slave» one of the data sequence. The «master» one returns the reception confirmation bit after each received byte, with exception of the last byte. After reception of the last byte the reception confirmation bit does not return.

The «master» device generates all cycle pulse and the conditions START and STOP. Transmission completes with emergence of the condition STOP or the repeated emergence of the condition START. As the repeated condition START is the beginning of the next serial transmission, then the bus is not vacated. Data transfer order: the first one is the most senior digit (MSB).

HT4337A :

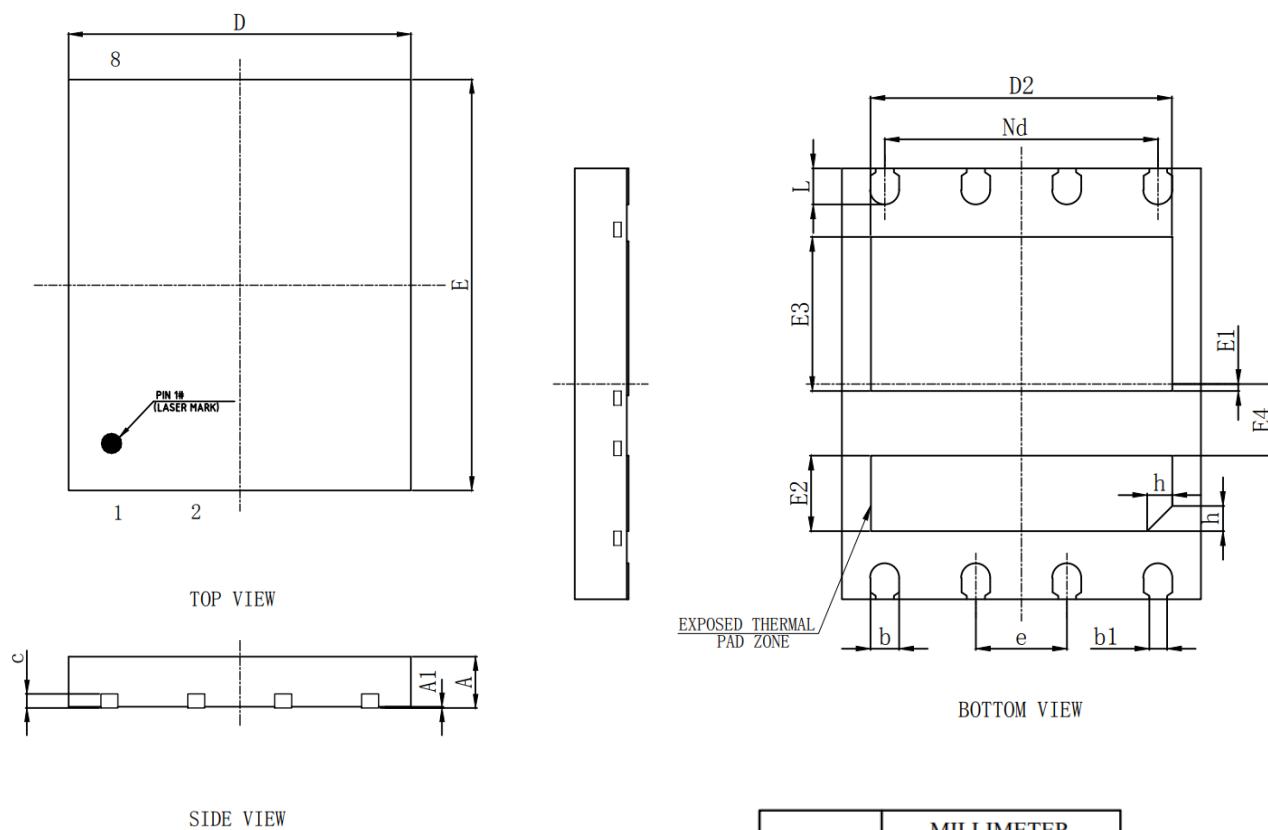
1. Mode of the «slave» receiver (writing mode of HT4337A): Serial data and cycles are received via SDA and SCL appropriately. After transfer of each byte the confirming bit is transferred. Conditions START and STOP are understood as the start and end of the serial transmission. Address recognition is performed by the hardware means after reception of the address of the «slave» one and the direction bit. The address byte is the first byte, received after emergence of the condition START, generated by the «master» one. Address byte contains seven address bits HT4337A, equal to 1010001, accompanied

by the direction bit ( $R/W$ ), which is equal to 0 for writing. After reception and decoding the address HT4337A provides confirmation on the line SDA. After confirmation by HT4337A of the

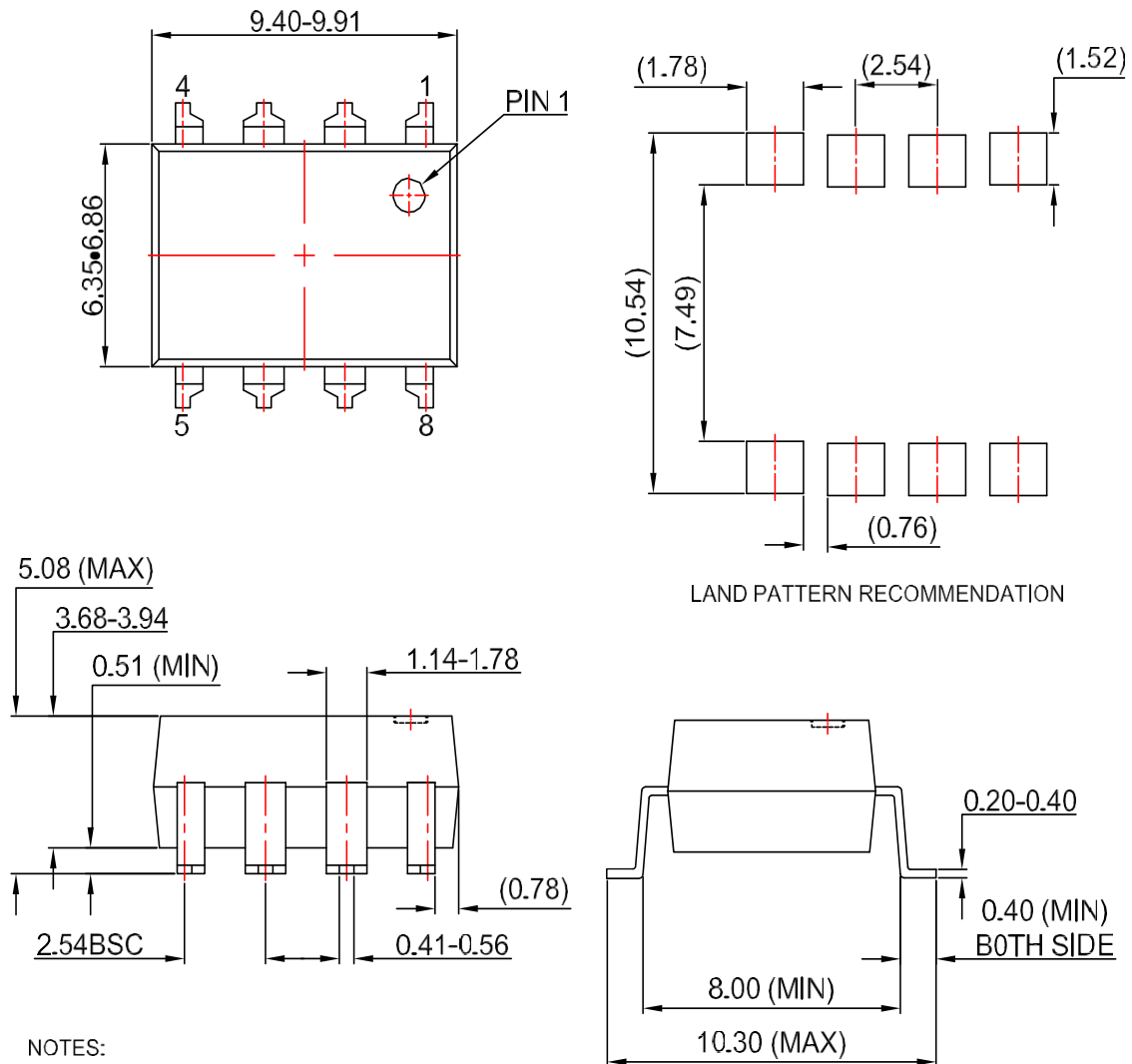
«slave» address and the write bit, the «master» one transmits the register address of HT4337A. Thus, the register indicator will be set in HT4337A. Then the «master» one will start to transfer each data byte with the subsequent confirmation reception of each byte receipt. Upon completion of writing the «master» one will form the condition STOP, for termination of the data transfer.

#### Data writing – mode of the receiver

2. Mode of the «slave» transmitter (read-out mode from HT4337A): The first byte is accepted and is processed as in the mode of the «slave» receiver. But in this mode the direction bit will indicate, that the transmission direction is altered. The serial data are transferred by HT4337A by means of SDA, the cycle pulses – by means of SCL. The statuses of START and STOP are recognized as the start and end of transmission in series. The address byte is the first byte, received after emergence of the status START, generated by the «slave» one. The address byte contains the seven address bits HT4337A, equal to 1010001, accompanied with the direction bit (  $R/W$  ), which is equal to 1 for reading. After reception and decoding the address byte HT4337A accepts confirmation from the line SDA. Then HT4337A starts to transmit the data from the address, to which the register indicator indicates. If the register indicator is not written prior to initialization of the writing mode, then the first read address will be the last address, stored in the register indicator. HT4337A should transmit the bit of «non-confirmation», in order to complete reading.

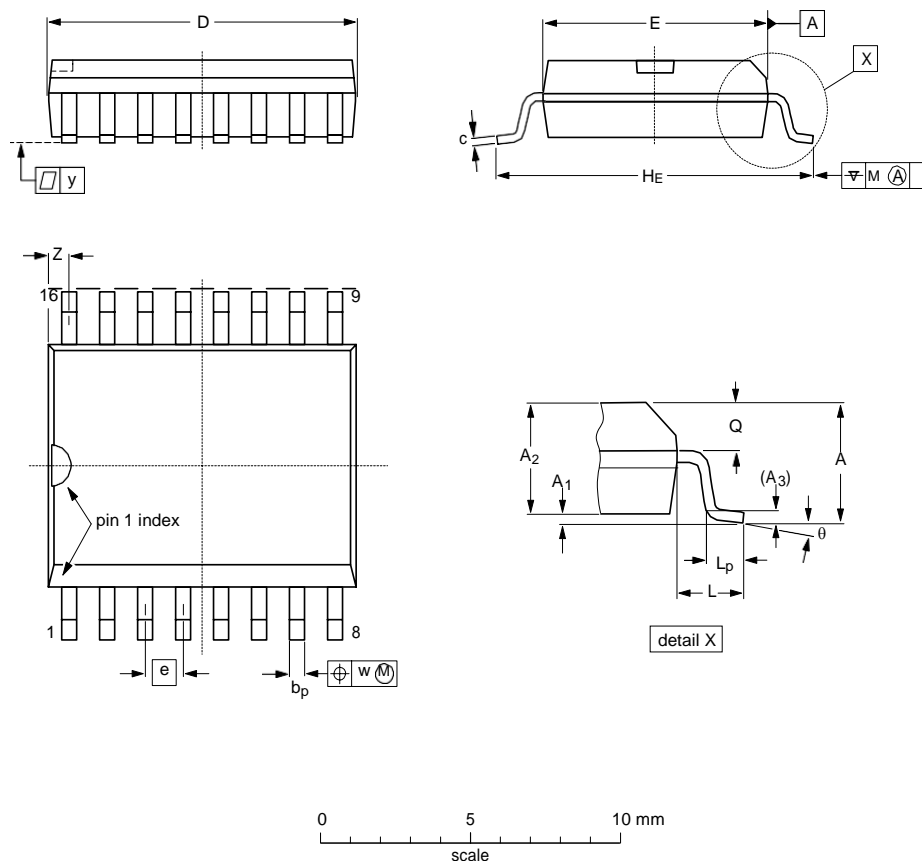
**DFN8(5\*6) package information**


SYMBOL	MILLIMETER		
	MIN	NOM	MAX
A	0.70	0.75	0.80
A1	0	0.02	0.05
b	0.35	0.40	0.45
b1	0.25REF		
c	0.15	0.20	0.25
D	4.90	5.00	5.10
Nd	3.81 BSC		
e	1.27 BSC		
E	5.90	6.00	6.10
D2	4.10	4.20	4.30
E1	0.05	0.10	0.15
E2	0.95	1.05	1.15
E3	2.10	2.15	2.20
E4	0.95	1.00	1.05
L	0.45	0.50	0.55
h	0.30	0.35	0.40
L/F载体尺寸	4.60x2.55/4.60x1.45		

**DUB8 (7.5\*6.5) package information**


- NOTES:
- A) NO STANDARD APPLIES TO THIS PACKAGE
  - B) ALL DIMENSIONS ARE IN MILLIMETERS.
  - C) DIMENSIONS ARE EXCLUSIVE OF BURRS, MOLD FLASH, AND TIE BAR EXTRUSION
  - D) DRAWING FILENAME AND REVISION: MKT-N08Hrev7.

WSOP16: plastic small outline package; 16 leads; body width 7.5 mm

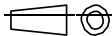


**DIMENSIONS** (inch dimensions are derived from the original mm dimensions)

UNIT	A max.	A <sub>1</sub>	A <sub>2</sub>	A <sub>3</sub>	b <sub>p</sub>	c	D <sup>(1)</sup>	E <sup>(1)</sup>	e	H <sub>E</sub>	L	L <sub>p</sub>	Q	v	w	y	z <sup>(1)</sup>	θ
mm	2.65	0.30 0.10	2.45 2.25	0.25	0.49 0.36	0.32 0.23	10.5 10.1	7.6 7.4	1.27	10.65 10.00	1.4	1.1 0.4	1.1 1.0	0.25	0.25	0.1	0.9 0.4	8° 0°
inches	0.10	0.012 0.004	0.096 0.089	0.01	0.019 0.014	0.013 0.009	0.41 0.40	0.30 0.29	0.050	0.419 0.394	0.055	0.043 0.016	0.043 0.039	0.01	0.01	0.004	0.035 0.016	

**Note**

1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.

OUTLINE VERSION	REFERENCES				EUROPEAN PROJECTION	ISSUE DATE
	IEC	JEDEC	EIAJ			
SOT162-1	075E03	MS-013				97-05-22 99-12-27