

600kHz, 18V, 5A FPWM Synchronous COT Step-Down Converter

Features

- 39mΩ/20mΩ Low $R_{DS(ON)}$ internal FETs
- Force PWM Operation Mode
- Wide Input Range: 4.5V to 18V
- Feedback Voltage Accuracy $0.6V \pm 1.5\%$
- 600kHz Switch Frequency Typical
- Up to 5A Output Current
- COT control to achieve fast transient responses
- Integrated internal compensation
- Stable with Low ESR Ceramic Output Capacitors
- Over Current Protection with Hiccup Mode
- Thermal Shutdown
- Inrush Current Limit and Soft Start
- Build in Input Over Voltage Protection
- Available in SOT23-6 Package

Description

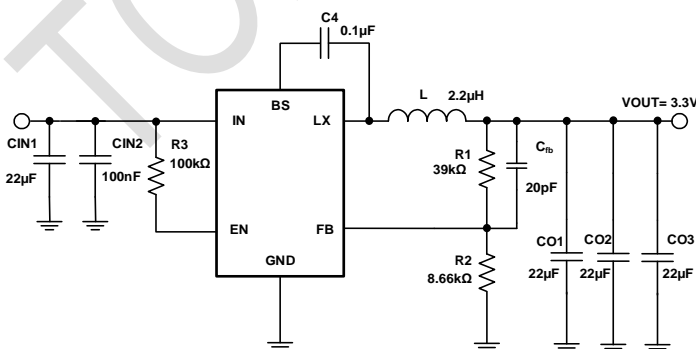
The TMI3255SF is a high efficiency, Constant on-Time (COT) control mode synchronous step-down DC-DC converter capable of delivering up to 5A current. TMI3255SF integrates main switch and synchronous switch with very low $R_{DS(ON)}$ to minimize the conduction loss. Low output voltage ripple and small external inductor and capacitor size are achieved with typical 600kHz switching frequency. It adopts the COT architecture and force PWM operation in steady state to achieve fast transient responses for high voltage step down applications.

The TMI3255SF requires a minimum number of readily available standard external components and is available in a 6-pin SOT23-6 RoHS compliant package.

Application

- Digital Set Top Boxes
- Flat Panel Television and Monitors
- Wireless and DSL Modems

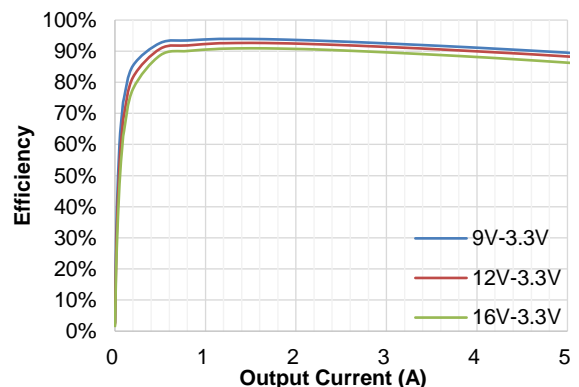
Typical Application



TMI3255SF Typical Application Circuits

Efficiency

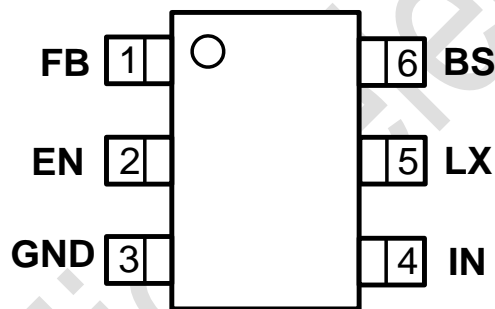
$V_{OUT}=3.3V$, $I_{OUT}=1mA$ to 5A, $T_A=25^\circ C$



Absolute Maximum Ratings (Note 1)

| Parameter | Min | Max | Unit |
|---------------------------------------------|------|------|------|
| Input Supply Voltage IN, EN | -0.3 | 20 | V |
| LX Voltages | -0.3 | 20 | V |
| LX Voltages (<10ns transient) | -4.5 | 22 | V |
| FB Voltage | -0.3 | 6 | V |
| BS Voltage | -0.3 | 23 | V |
| Storage Temperature Range | -65 | 150 | °C |
| Junction Temperature <small>(Note2)</small> | - | 160 | °C |
| Power Dissipation | - | 1500 | mW |
| Lead Temperature (Soldering, 10s) | - | 260 | °C |

Package and Pin Map



Top View

SOT23-6

Top Marking: TF6XXX

TF6: Device Code

XXX: Inside Code

Order Information

| Part Number | Package | Top Marking | Quantity/Reel |
|-------------|---------|-------------|---------------|
| TMI3255SF | SOT23-6 | TF6XXX | 3000 |

TMI3255SF devices are Pb-free and RoHS compliant.

Pin Functions

| Pin | Name | Function |
|-----|------|-------------------------------------------------------------------------------------------------------------------------------------------------|
| 1 | FB | Output Voltage feedback input. Connect FB to the center point of the external resistor divider. |
| 2 | EN | Drive this pin to a logic-high to enable the IC. Drive to a logic-low to disable the IC and enter micro-power shutdown mode. Don't floating EN. |
| 3 | GND | Ground Pin |
| 4 | IN | Power supply Pin |
| 5 | LX | Switching Pin |
| 6 | BS | Bootstrap. A capacitor connected between LX and BS pins is required to form a floating supply across the high-side switch driver. |

ESD Rating

| Items | Description | Value | Unit |
|----------------------|-----------------------------------|-------|------|
| V _{ESD_HBM} | Human Body Model for all pins | ±2000 | V |
| V _{ESD_CDM} | Charged Device Model for all pins | ±1000 | V |

JEDEC specification JS-001

Recommended Operating Conditions

| Items | Description | Min | Max | Unit |
|----------------|--------------------------------|-----|-----|------|
| Voltage Range | IN | 4.5 | 18 | V |
| T _J | Operating Junction Temperature | -40 | 125 | °C |

Thermal Resistance (Note3)

| Items | Description | Value | Unit |
|-----------------|------------------------------------------|-------|------|
| θ _{JA} | Junction-to-ambient thermal resistance | 25 | °C/W |
| θ _{JC} | Junction-to-case(top) thermal resistance | 5 | °C/W |

Electrical Characteristics

$V_{IN}=12V$, $V_{OUT}=3.3V$, $T_A = 25^{\circ}C$, unless otherwise noted.

| Parameter | Conditions | Min | Typ | Max | Units |
|-------------------------------------------------|----------------------------------------------|-------|------|-------|-------------|
| Input Voltage Range | | 4.5 | | 18 | V |
| OVP Threshold | | 18.2 | 19 | 20 | V |
| OVP Hysteresis | | | 0.45 | | V |
| UVLO Rising Threshold | | | 4.2 | | V |
| UVLO Hysteresis | | | 0.6 | | V |
| Quiescent Current | $V_{EN}=2V$, $V_{FB}=V_{REF} \times 105\%$ | | 340 | 600 | μA |
| Standby Current | $V_{EN}=2V$, No load | 3 | | 20 | mA |
| Shutdown Current | $V_{IN}=12V$, $EN=0V$ | | 5 | 15 | μA |
| Regulated Feedback Voltage | $T_A=25^{\circ}C$ | 0.591 | 0.6 | 0.609 | V |
| FB Input Leakage Current | | -0.5 | | 0.5 | μA |
| High-Side Switch On-Resistance | | | 39 | | m Ω |
| Low-Side Switch On-Resistance | | | 20 | | m Ω |
| High-Side Switch Leakage Current | $V_{EN}=0V$, $V_{LX}=0V$ | 1 | | 10 | μA |
| High-side Switch Peak Current Limit | | | 9 | | A |
| Low-side Switch Valley Current Limit | | | 7 | | A |
| On Time | $V_{IN}=12V$, $V_{OUT}=3.3V$, $I_{OUT}=1A$ | | 450 | | ns |
| Oscillation Frequency | | 450 | 600 | 800 | kHz |
| Maximum Duty Cycle | | | 84 | | % |
| Minimum On-Time _(Note 4) | | 70 | 85 | 100 | ns |
| Soft Start Time | 10% $\times V_{OUT}$ to 90% $\times V_{OUT}$ | 0.4 | 0.6 | 0.9 | ms |
| Hiccup on Time _(Note 4) | | | 1 | | ms |
| Hiccup Time Before Restart _(Note 4) | | | 12 | | ms |
| EN Enable Delay Time _(Note 4) | | | 300 | | μs |
| EN Rising Threshold | | 0.90 | 1.05 | 1.20 | V |
| EN Hysteresis | | | 120 | | mV |
| EN Input Leakage Current | $V_{EN}=2V$ | -1 | | 1 | μA |
| Thermal Shutdown Threshold _(Note 4) | | | 165 | | $^{\circ}C$ |
| Thermal Shutdown Hysteresis _(Note 4) | | | 30 | | $^{\circ}C$ |

Note 1: Absolute Maximum Ratings are those values beyond which the life of a device may be impaired.

Note 2: T_J is calculated from the ambient temperature T_A and power dissipation P_D according to the following formula: $T_J = T_A + P_D \times \theta_{JA}$. The maximum allowable continuous power dissipation at any ambient temperature is calculated by $P_{D(MAX)} = (T_{J(MAX)} - T_A) / \theta_{JA}$.

Note 3: Measured on JESD51-7, 4-layer PCB.

Note 4: Guaranteed by design.

Block Diagram

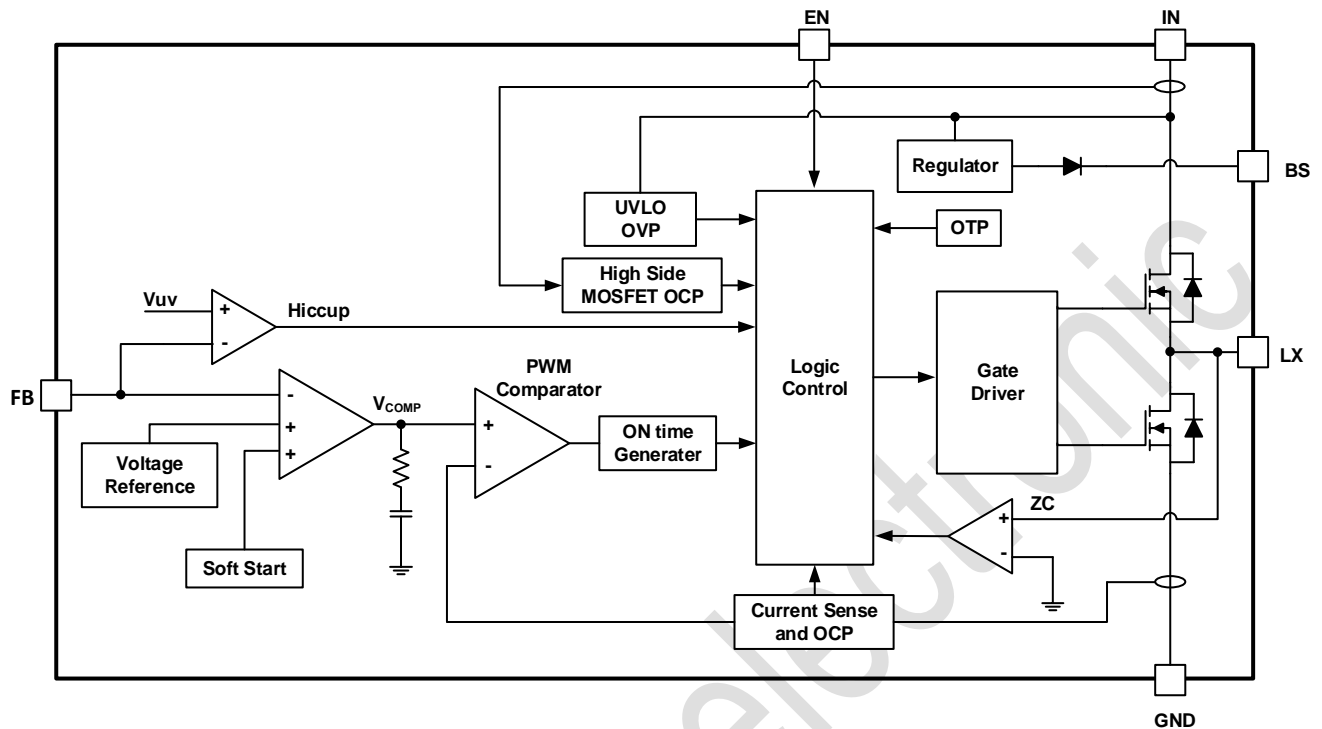


Figure 1. TMI3255SF Block Diagram

Operation Description

Internal Regulator

The TMI3255SF is a constant on-time (COT) step down DC/DC converter that provides excellent transient response with no extra external compensation components. This device contains low resistance, high voltage high side and low side power MOSFETs, and operates at typical 600kHz operating frequency to ensure a compact, high efficiency design with excellent AC and DC performance.

Error Amplifier

TMI3255SF adopts operational transconductance amplifier (OTA) as error amplifier. The error amplifier compares the FB pin voltage with the internal FB reference (V_{REF}) and outputs a current proportional to the difference between the two. This output current is then used to charge or discharge the internal compensation network to form the V_{COMP} voltage, which is used to compare with the low side power MOSFET current sensing signal and trigger on time pulse. The optimized internal compensation network minimizes the external component counts and simplifies the control loop design.

Internal Soft-Start

The soft-start is implemented to prevent the converter output voltage from overshooting during startup. When the chip starts, the internal circuitry generates a soft-start voltage (SS) ramping up from 0V to V_{REF} . When it is lower than the internal FB reference (V_{REF}), SS overrides REF so the error amplifier uses SS as the reference. When SS is higher than V_{REF} , V_{REF} regains control. The SS time is internally fixed to 0.6ms typically.

Over-Current-Protection and Short Circuits Protection

The TMI3255SF has both high-side and low-side MOSFET cycle-by-cycle current limit function. When the inductor current peak value is larger than the switch peak current limit after the blinking time, high side MOSFET is turned off immediately. When inductor current valley value is larger than the valley current limit during low side MOSFET on state, the device enters into valley over current protection mode and low side MOSFET keeps on state until inductor current drops down to the value equal or lower than the valley current limit, and then on time pulse could be generated and high side MOSFET could turn on again.

If the output is short to GND and the output voltage drop until feedback voltage V_{FB} is below the output under-voltage V_{UV} threshold, TMI3255SF enters into hiccup mode to periodically disable and restart switching operation. The hiccup mode helps to reduce power dissipation and thermal rise during output short condition. The period of TMI3255SF hiccup mode is typically 13ms.

In the application with high output voltage, when the input voltage is close to input UVLO threshold voltage, TMI3255SF operates in maximum duty condition and the FB voltage may be lower than V_{UV} and the hiccup mode may be triggered during power on and off process. Using external divider resistor from VIN to EN and GND to set external UVLO could avoid this application issue.

Startup and Shutdown

If both VIN and EN are higher than their appropriate thresholds, the chip starts switching operation. The reference block starts first, generating stable reference voltage and currents, and then the internal regulator is enabled. The regulator provides stable supply for the remaining circuitries. Three events can shut down the chip: EN low, VIN low and thermal shutdown. In the shutdown procedure, the signaling path is first blocked to avoid any fault triggering. The V_{COMP} voltage and the internal supply rail are then pulled down. The floating driver is not subject to this shutdown command.

Application Information

Setting the Output Voltage

The external resistor divider is used to set the output voltage (see Typical Application on page 1). Choose R1 to be around 39k Ω for optimal transient response. R2 is then given by:

Table 1: Selection for Common Output Voltages ($V_{FB}=0.6V$)

| V_{OUT} (V) | R1 (k Ω) | R2 (k Ω) | C_{FB} (pF) | L (μ H) |
|---------------|------------------|------------------|---------------|--------------|
| 5 | 39 | 5.36 | 20 | 3.3 |
| 3.3 | 39 | 8.66 | 20 | 2.2 |
| 2.5 | 39 | 12.4 | 20 | 1.5 |
| 1.8 | 39 | 19.6 | 20 | 1.5 |
| 1.5 | 39 | 26.1 | 20 | 1.5 |
| 1.2 | 39 | 39 | 20 | 1 |
| 1 | 39 | 59 | 20 | 1 |

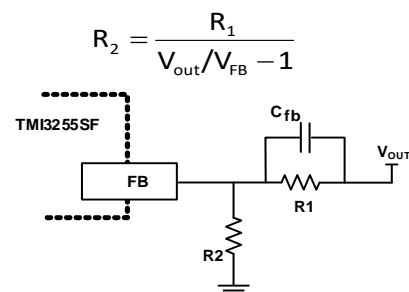


Figure 2. Feedback Network

A C_{fb} capacitor paralleling with high side divider resistor R1 can be used to improve load transient performance. It adds a zero in the frequency $1/2\pi \cdot R1 \cdot C_{fb}$ to increase bandwidth of the system. 20pF C_{fb} is sufficient in most application. In fast transient load current condition, increasing C_{fb} capacitance helps

to improve transient performance and reduce output ripple value. C_{fb} capacitor value could be regulated according to output capacitor value and loop stability margin.

Selecting the Inductor

An inductor with a DC current rating of at least 25% percent higher than the maximum load current is recommended for most applications. For highest efficiency, the inductor DC resistance should be as small as possible. For most designs, the inductance value can be derived from the following equation.

$$L = \frac{V_{out} \times (V_{in} - V_{out})}{V_{in} \times \Delta I_L \times f_{OSC}}$$

Where ΔI_L is the inductor ripple current. TMI3255SF is force PWM operation mode. In dull load condition, the average inductor current is zero and valley inductor current is $-\Delta I_L/2$. the minus current valley is limited to around -2.5A, so the inductor ripple current ΔI_L should be smaller than 5A, and the minimum inductance value is limited. The maximum inductor peak current is:

$$I_{L(MAX)} = I_{LOAD} + \frac{\Delta I_L}{2}$$

Such as, for 5V output voltage, the recommended inductor should not be smaller than 1.5 μ H, and for 3.3V output voltage, the recommended inductor should not be smaller than 1.0 μ H.

Selecting the Output Capacitor

The output capacitors are required to maintain the DC output voltage. Ceramic, tantalum, or low ESR electrolytic capacitors are recommended. Low ESR capacitors are preferred to keep the output voltage ripple low. The output voltage ripple can be estimated by:

$$\Delta V_{OUT} = \frac{V_{OUT}}{f_s \times L} \times \left[1 - \frac{V_{OUT}}{V_{IN}} \right] \times \left[R_{ESR} + \frac{1}{8 \times f_s \times C_2} \right]$$

Where L is the inductor value and R_{ESR} is the equivalent series resistance (ESR) value of the output capacitor. In the case of ceramic capacitors, the impedance at the switching frequency is dominated by the capacitance. The output voltage ripple is mainly caused by the capacitance. For simplification, the output voltage ripple can be estimated by:

$$\Delta V_{OUT} = \frac{V_{OUT}}{8 \times f_s^2 \times L \times C_2} \times \left[1 - \frac{V_{OUT}}{V_{IN}} \right]$$

In the case of tantalum or electrolytic capacitors, the ESR dominates the impedance at the switching frequency. For simplification, the output ripple can be approximated to:

$$\Delta V_{OUT} = \frac{V_{OUT}}{f_s \times L} \times \left[1 - \frac{V_{OUT}}{V_{IN}} \right] \times R_{ESR}$$

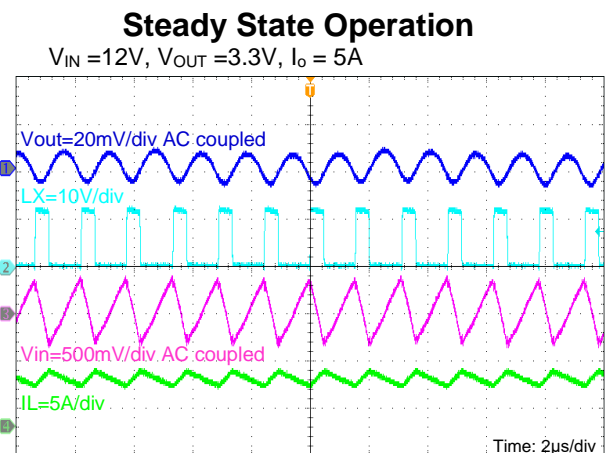
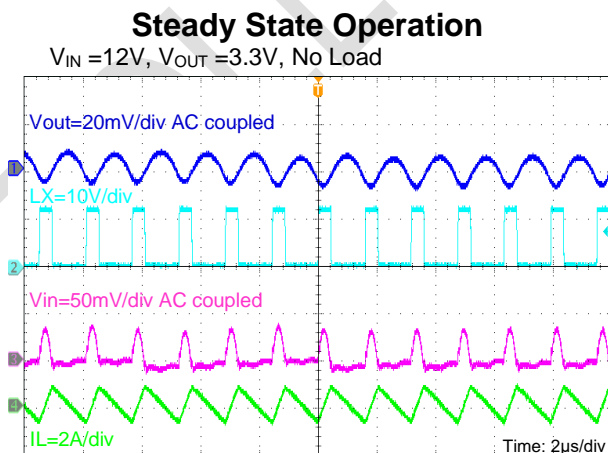
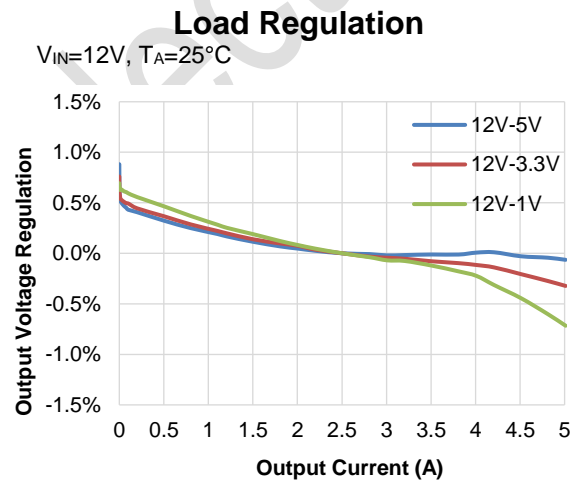
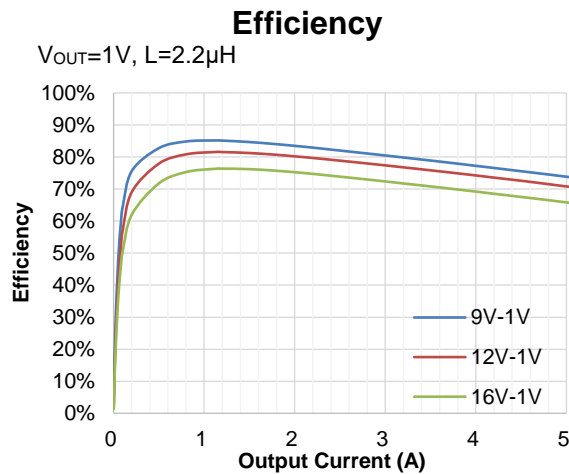
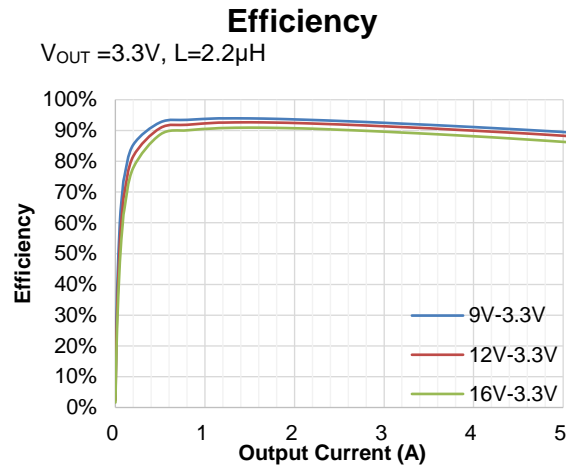
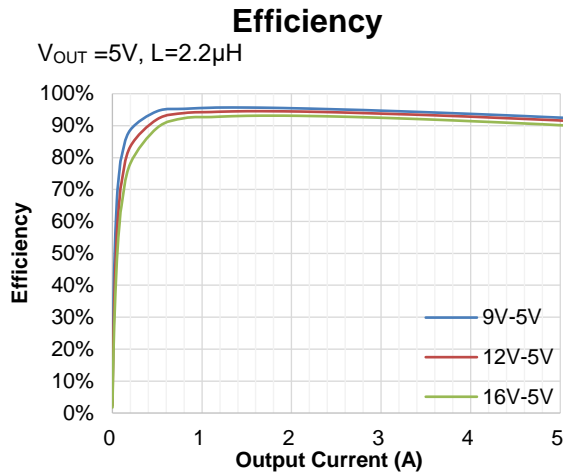
The characteristics of the output capacitor also affect the stability of the regulation system. The TMI3255SF can be optimized for a wide range of capacitance and ESR values. Three or more 22 μ F ceramic output capacitors for most application are sufficient.

PCB Layout Guide

PCB layout is very important to achieve stable operation. Please follow these guidelines for reference.

- 1) Keep the path of switching current short and minimize the loop area formed by Input capacitor, IN pin and GND.
- 2) Bypass ceramic capacitors are suggested to be put close to the IN Pin.
- 3) Ensure all feedback connections are short and direct. Place the feedback resistors as close to the chip as possible.
- 4) VOUT, LX away from sensitive analog areas such as FB.
- 5) Connect IN, LX, and especially GND respectively to a large copper area to cool the chip to improve thermal performance and long-term reliability.

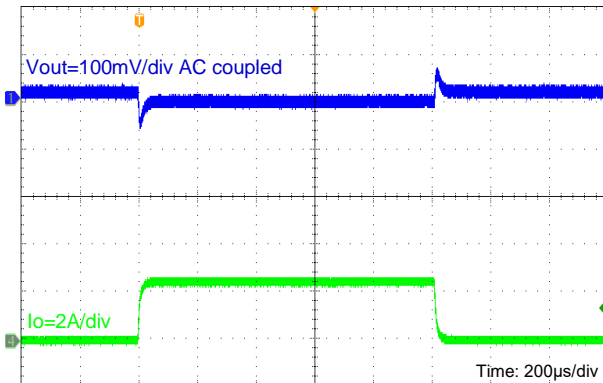
Typical Performance Characteristics



Typical Performance Characteristics_(continued)

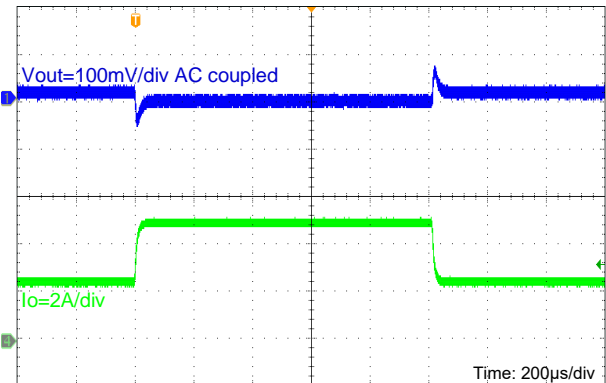
Load Transient

$V_{IN}=12V$, $V_{OUT}=3.3V$, $I_o=0A$ to $2.5A$



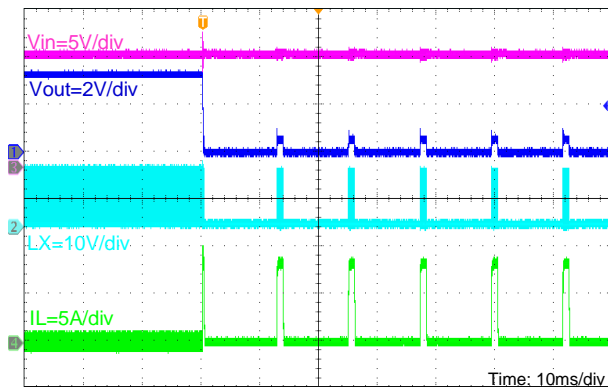
Load Transient

$V_{IN}=12V$, $V_{OUT}=3.3V$, $I_o=2.5A$ to $5A$



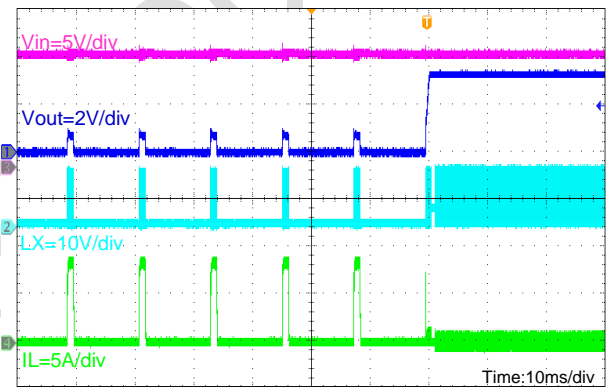
Output Short Entry

$V_{IN}=12V$, $V_{OUT}=3.3V$, No Load



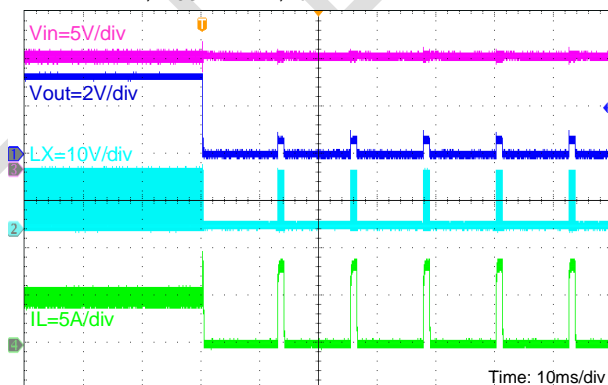
Output Short Recovery

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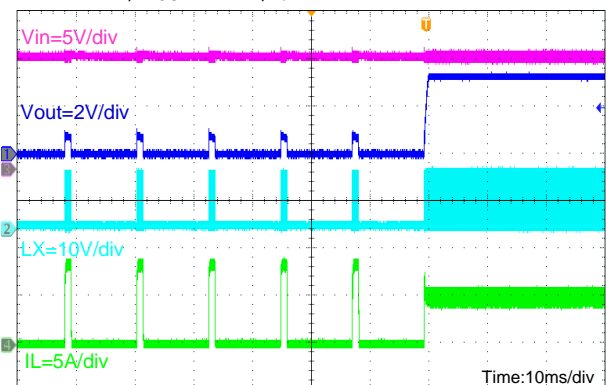
Output Short Entry

$V_{IN}=12V$, $V_{OUT}=3.3V$, $I_o=5A$



Output Short Recovery

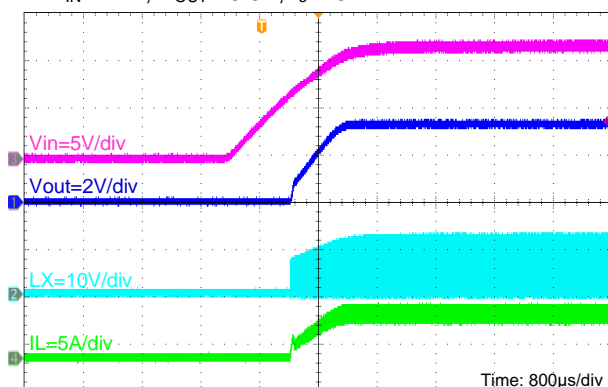
$V_{IN}=12V$, $V_{OUT}=3.3V$, $I_o=5A$



Typical Performance Characteristics_(continued)

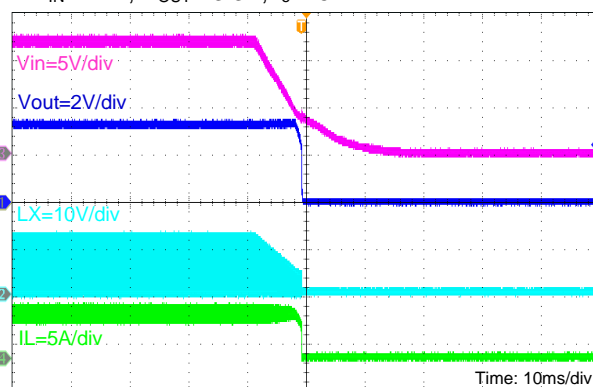
Input Power On

$V_{IN} = 12V$, $V_{OUT} = 3.3V$, $I_o = 5A$



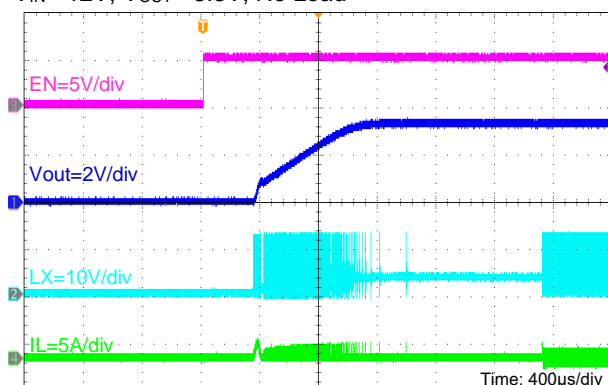
Input Power Down

$V_{IN} = 12V$, $V_{OUT} = 3.3V$, $I_o = 5A$



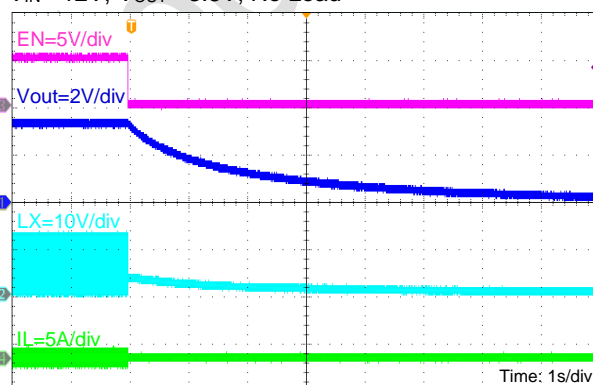
EN Enable

$V_{IN} = 12V$, $V_{OUT} = 3.3V$, No Load



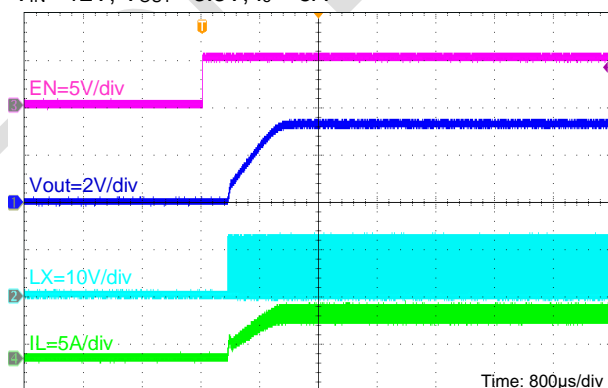
EN Disable

$V_{IN} = 12V$, $V_{OUT} = 3.3V$, No Load



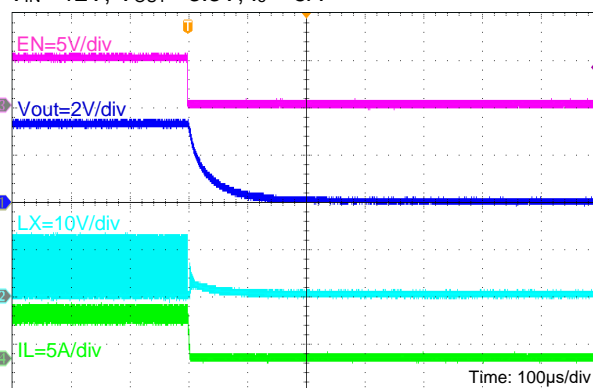
EN Enable

$V_{IN} = 12V$, $V_{OUT} = 3.3V$, $I_o = 5A$



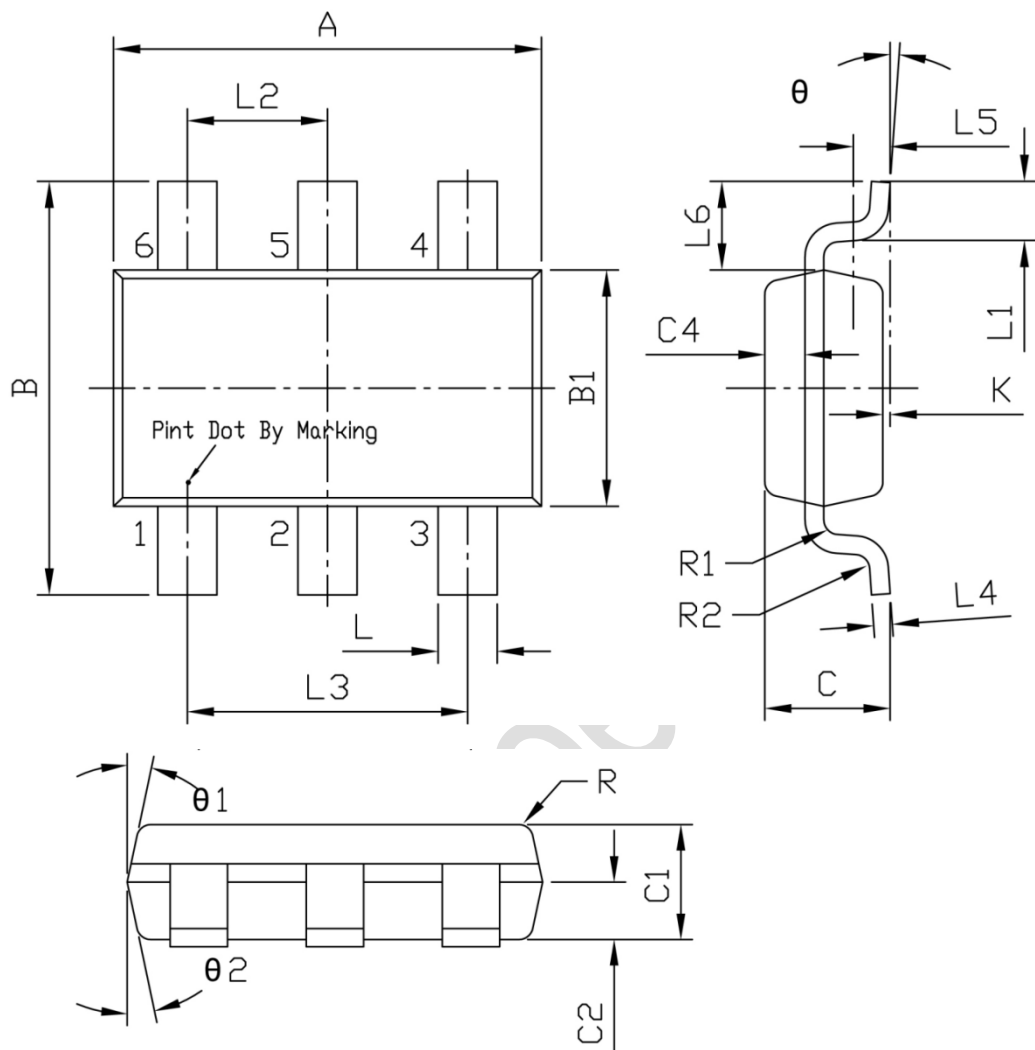
EN Disable

$V_{IN} = 12V$, $V_{OUT} = 3.3V$, $I_o = 5A$



Package Information

SOT23-6

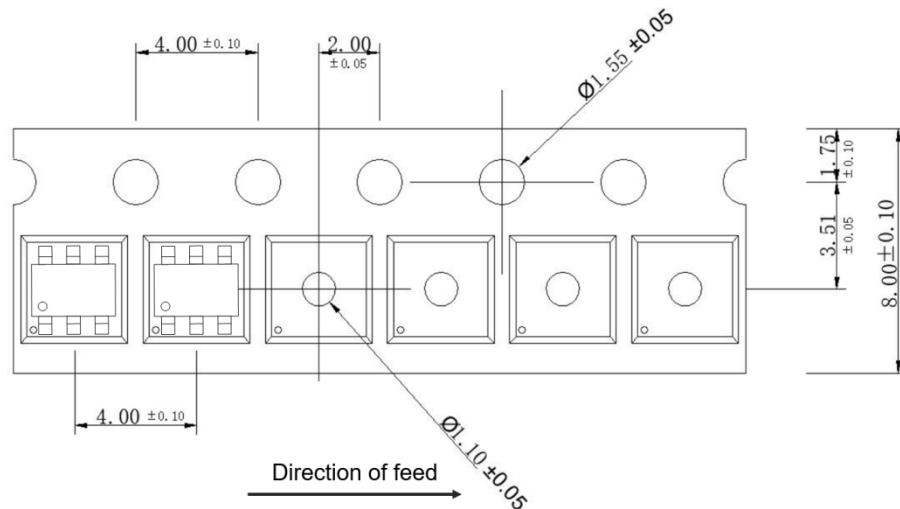


Unit: mm

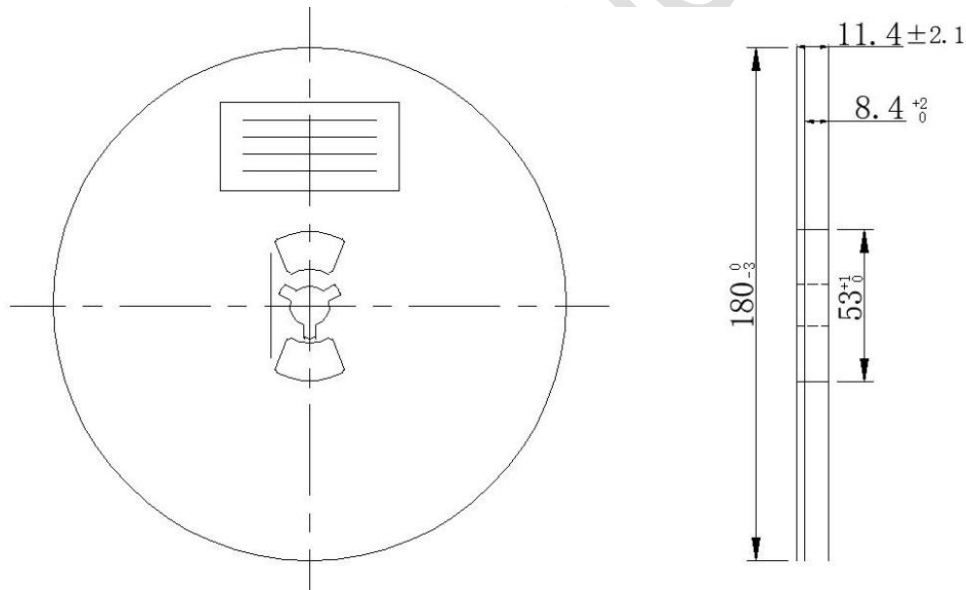
| Symbol | Dimensions In Millimeters | | | Symbol | Dimensions In Millimeters | | |
|--------|---------------------------|-------|-------|------------|---------------------------|-------|-------|
| | Min | Typ | Max | | Min | Typ | Max |
| A | 2.80 | 2.90 | 3.00 | L3 | 1.800 | 1.900 | 2.000 |
| B | 2.60 | 2.80 | 3.00 | L4 | 0.077 | 0.127 | 0.177 |
| B1 | 1.50 | 1.60 | 1.70 | L5 | - | 0.250 | - |
| C | - | - | 1.05 | L6 | - | 0.600 | - |
| C1 | 0.60 | 0.80 | 1.00 | θ | 0° | | 0° |
| C2 | 0.35 | 0.40 | 0.45 | θ_1 | 10° | 12° | 14° |
| C4 | 0.223 | 0.273 | 0.323 | θ_2 | 10° | 12° | 14° |
| K | 0.000 | 0.075 | 0.150 | R | - | 0.100 | - |
| L | 0.325 | 0.400 | 0.475 | R1 | - | 0.100 | - |
| L1 | 0.325 | 0.450 | 0.550 | R2 | - | 0.100 | - |
| L2 | 0.850 | 0.950 | 1.050 | | | | |

Tape and Reel Information

Tape Dimensions: SOT23-6



Reel Dimensions: SOT23-6



Note:

- 1) All Dimensions are in Millimeter
- 2) Quantity of Units per Reel is 3000
- 3) MSL level is Level 3.

Important Notification

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