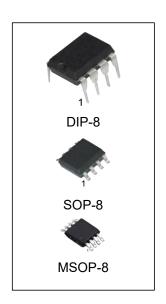


### **MAX515E 10-BIT DIGITAL-TO-ANALOG CONVERTERS**

#### **Features**

- 10-Bit CMOS Voltage Output DAC in an 8-Terminal Package
- 5V Single Supply Operation
- 3-Wire Serial Interface
- High-Impedance Reference Inputs
- Voltage Output Range:2 Times the Reference Input Voltage
- Internal Power-On Reset
- Low Power Consumption:1.75mW(Max)
- Update Rate of 1.21 MHz
- Settling Time to 0.5 LSB:12.5 μs(Typ)
- Monotonic Over Temperature
- Pin Compatible With the TLC5615



### **Ordering Information**

DEVICE	Package Type	MARKING	Packing	Packing Qty
MAX515EIN	DIP-8	X515EI	TUBE	2000pcs/box
MAX515ECN	DIP-8	X515EC	TUBE	2000pcs/box
MAX515EIM/TR	SOP-8	X515EI	REEL	2500pcs/reel
MAX515ECM/TR	SOP-8	X515EC	REEL	2500pcs/reel
MAX515EIMM/TR	MSOP-8	X515EI	REEL	3000pcs/reel
MAX515ECMM/TR	MSOP-8	X515EC	REEL	3000pcs/reel



### **Description**

The MAX515E is a 10-bit voltage output digital-to-analog converter (DAC) with a buffered reference input (high impedance). The DAC has an output voltage range that is two times the reference voltage, and the DAC is monotonic. The device is simple to use, running from a single supply of 5 V. A power-on-reset function is incorporated to ensure repeatable start-up conditions.

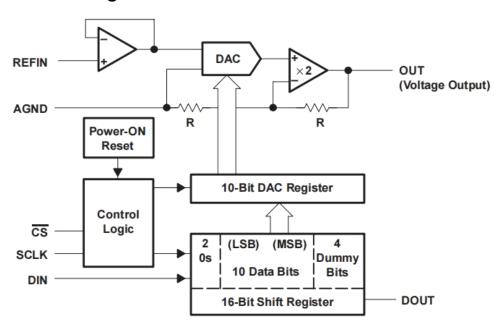
Digital control of the MAX515E is over a three-wire serial bus that is CMOS compatible and easily interfaced to industry standard microprocessor and micro controller devices. The device receives a 16-bit data word to produce the analog output. The digital inputs feature Schmitt triggers for high noise immunity. Digital communication protocols include the SPI<sup>TM</sup>, QSPI<sup>TM</sup>, and Microwire<sup>TM</sup> standards.

The 8-terminal small-outline D package allows digital control of analog functions in space-critical applications. The MAX515EC is characterized for operation from 0°C to 70°C. The MAX515EI is characterized for operation from -40°C to 85°C.

### **Applications**

- Battery-Powered Test Instruments
- Digital Offset and Gain Adjustment
- Battery Operated/Remote Industrial Controls
- Machine and Motion Control Devices
- Cellular Telephones

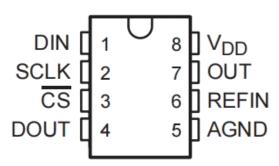
### Functional block diagram





## **Pin Configuration**

DIP-8/SOP-8/MSOP-8



### **Terminal Functions**

TERMI NAME	NAL NO.	I/O	DESCRIPTION
DIN	1	I	Serial data input
SCLK	2	I	Serial clock input
CS	3	I	Chip select, active low
DOUT	4	0	Serial data output for daisy chaining
AGND	5		Analog ground
REFIN	6	I	Reference input
OUT	7	0	DAC analog voltage output
V <sub>DD</sub>	8		Positive power supply



## **Absolute Maximum Ratings**

over operating free-air temperature range (unless otherwise noted)

Condition	Condition		
Supply voltage (VDD to AGND)		-	7 V
Digital input voltage range to AGND		- 0.3 V	VDD + 0.3 V
Reference input voltage range to AGND		-0.3 V	VDD + 0.3 V
Output voltage at OUT from extrnal source	-	VDD + 0.3 V	
Continuous current at any terminal		-20mA	+20mA
O	MAX515EC	0℃	70℃
Operating free-air temperature range,TA:	MAX515EI	-40℃	85℃
Storage temperature range, T <sub>Stg</sub>		-65℃	150℃
Lead Temperature (Soldering, 10 seconds)		-	245℃

Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability

## **Recommended Operating Conditions**

		MIN	NOM	MAX	UNIT
Supply voltage, VDD	Supply voltage, V <sub>DD</sub>		5	5.5	V
High-level digital input voltage, V <sub>IH</sub>		2.4			V
Low-level digital input voltage, V <sub>IL</sub>				0.8	V
Reference voltage, Vref to REFIN term	ninal	2	2.048	V <sub>DD</sub> -2	V
Load resistance, RL		2			kΩ
Operating free-air temperature, TA	MAX515EC	0		70	$^{\circ}$
	MAX515EI	<del>-4</del> 0		85	$^{\circ}\!\mathbb{C}$

#### **Electrical Characteristics**

over recommended operating free-air temperature range,  $VDD = 5 V \pm 5\%$ , Vref = 2.048 V (unless otherwise noted) static DAC specifications

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
Resolution			10			bits
Integral nonlinearity, end point adjus	ted (INL)	V <sub>ref</sub> = 2.048 V,See Note 1			±1	LSB
Differential nonlinearity (DNL)		V <sub>ref</sub> = 2.048 V,See Note 2		±0.1	±0.5	LSB
E <sub>ZS</sub> Zero-scale error (offset error at zero scale)		V <sub>ref</sub> = 2.048 V,See Note 3			±3	LSB
Zero-scale-error temperature coeffic	ient	V <sub>ref</sub> = 2.048 V,See Note 4		3		ppm/℃
EG Gain error		V <sub>ref</sub> = 2.048 V,See Note 5			±3	LSB
Gain-error temperature coefficient		V <sub>ref</sub> = 2.048 V,See Note 6		1		ppm/℃
DODD Devers are borner of the market	Zero scale	O N-4 7 1 0	80			-ID
PSRR Power-supply rejection ratio	Gain	See Notes 7 and 8	80			dB
Analog full scale output		R <sub>L</sub> = 100 kΩ	2V <sub>r</sub>	ef(1023/10	)24)	V



- The relative accuracy or integral nonlinearity (INL), sometimes referred to as linearity error, is the maximum deviation of the output from the line between zero and full scale excluding the effects of zero code and full-scale errors (see text).
- The differential nonlinearity (DNL), sometimes referred to as differential error, is the difference between the measured and ideal 1 LSB amplitude change of any two adjacent codes. Monotonic means the output voltage changes in the same direction (or remains constant) as a change in the digital input code.
- 3. Zero-scale error is the deviation from zero-voltage output when the digital input code is zero (see text).
- Zero-scale-error temperature coefficient is given by:
  EZS TC = [EZS (Tmax) EZS (Tmin)]/Vref ×10<sup>6</sup>/(Tmax Tmin).
- 5. Gain error is the deviation from the ideal output (Vref 1 LSB) with an output load of 10 kΩ excluding the effects of the zero-scale error.
- 6. Gain temperature coefficient is given by: EG TC = [EG(Tmax) EG (Tmin)]/Vref ×10<sup>6</sup>/(Tmax Tmin).
- 7. Zero-scale-error rejection ratio (EZS-RR) is measured by varying the VDD from 4.5 V to 5.5 V dc and measuring the proportion of this signal imposed on the zero-code output voltage.
- 8. Gain-error rejection ratio (EG-RR) is measured by varying the VDD from 4.5 V to 5.5 V dc and measuring the proportion of this signal imposed on the full-scale output voltage after subtracting the zero-scale change.

### **Voltage Output (Out)**

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Vo	Voltage output range	R <sub>L</sub> = 10 kΩ	0		V <sub>DD</sub> -0.4	V
	Output load regulation accuracy	$VO(OUT) = 2 V_{RL} = 2 k\Omega$			0.5	LSB
losc	Output short circuit current	OUT to VDD or AGND		20		mA
VOL(low)	Output voltage, low-level	IO(OUT) ≤ 5 mA			0.25	V
VOH(high)	Output voltage, high-level	IO(OUT) ≤ -5 mA	4.75			V

#### **Electrical Characteristics**

over recommended operating free-air temperature range,  $V_{DD}$  = 5 V ± 5%, Vref = 2.048 V (unless otherwise noted) (continued) reference input (REFIN)

	PARAMETER	TES	T CONDITIONS	MIN	TYP	MAX	UNIT
VI	Input voltage			0		V <sub>DD</sub> -2	V
rį	Input resistance			10			ΜΩ
Ci	Input capacitance			5			pF

#### digital inputs (DIN, SCLK, CS)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
VIH	High-level digital input voltage		2.4			V
VIL	Low-level digital input voltage				0.8	V
lіН	High-level digital input current	VI = V <sub>DD</sub>			±1	μA
IJL	Low-level digital input current	V <sub>I</sub> = 0			±1	μA
Ci	Input capacitance		8			pF

#### digital output (DOUT)

PARAMETER	TEST CONDITIONS	MIN 1	TYP MAX	UNIT
VOH Output voltage, high-level	I <sub>O</sub> = -2 mA	V <sub>DD</sub> –1		V
VOL Output voltage, low-level	I <sub>O</sub> = 2 mA		0.4	V



## power supply

PARAMETER	TEST CONDITIONS			TYP	MAX	UNIT
V <sub>DD</sub> Supply voltage			4.5	5	5.5	V
	V <sub>DD</sub> = 5.5 V,					
	No load,	Vref = 0		150	250	μΑ
IDD Barren arrantir arrant	All inputs = 0 V or VDD					
IDD Power supply current	V <sub>DD</sub> = 5.5 V,					
	No load,	V <sub>ref</sub> = 2.048 V		230	350	μΑ
	All inputs = 0 V or VDD					

## analog output dynamic performance

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Signal-to-noise + distortion, S/(N+D)	V <sub>ref</sub> = 1 V <sub>pp</sub> at 1 kHz + 2.048 Vdc, code = 11 1111 1111,	60			dB
	See Note 9				

NOTE 9: The limiting frequency value at 1 Vpp is determined by the output-amplifier slew rate.

## digital input timing requirements (see Figure 1)

	PARAMETER	MIN	TYP	MAX	UNIT
tsu(DS)	Setup time, DIN before SCLK high	45			ns
th(DH)	Hold time, DIN valid after SCLK high	0			ns
t <sub>su(CSS)</sub>	Setup time, $\overline{\text{CS}}$ low to SCLK high	1			ns
tsu(CS1)	Setup time, $\overline{\text{CS}}$ high to SCLK high	50			ns
th(CSH0)	Hold time, SCLK low to $\overline{\text{CS}}$ low	1			ns
th(CSH1)	Hold time, SCLK low to $\overline{\text{CS}}$ high	0			ns
tw(CS)	Pulse duration, minimum chip select pulse width high	20			ns
tw(CL)	Pulse duration, SCLK low	25		·	ns
tw(CH)	Pulse duration, SCLK high	25		·	ns

## output switching characteristic

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
tpd(DOUT) Propagation delay time, DOUT	CL = 50 pF			50	ns



## **Operating Characteristics**

over recommended operating free-air temperature range,  $V_{DD}$  = 5 V ±5%, Vref = 2.048 V (unless otherwise noted) analog output dynamic performance

	PARAMETER	TEST C	MIN	TYP	MAX	UNIT				
SR	Output slew rate	C <sub>L</sub> = 100 pF,T <sub>A</sub> = 25°C	$R_L = 10 \text{ k}\Omega$	0.3	0.5		V/µs			
ts	Output settling time	To 0.5 LSB,R <sub>L</sub> = 10 kΩ,	C <sub>L</sub> = 100 pF, See Note 10		12.5		μs			
Glitch energy		DIN = All 0s to all 1s			5		Nv•s			

NOTE 10: Settling time is the time for the output signal to remain within  $\pm 0.5$  LSB of the final measured value for a digital input code change of 000 hex to 3FF hex or 3FF hex to 000 hex.

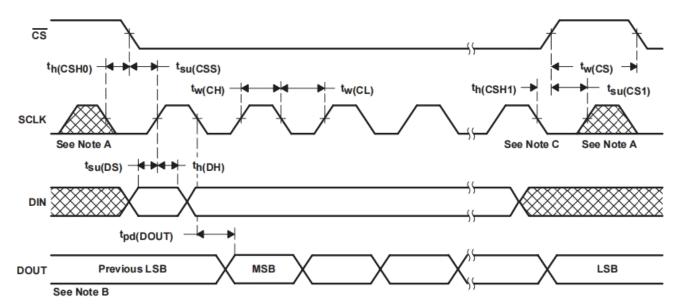
## reference input (REFIN)

PARAMETER	TEST CO	MIN	TYP	MAX	UNIT	
Reference feedthrough	REFIN = 1 V <sub>pp</sub> at 1 kHz +		-80		dB	
Reference input bandwidth (f–3dB)	REFIN = 0.2 V <sub>pp</sub> + 2.048 Vdc	REFIN = 0.2 V <sub>pp</sub> + 2.048		30		kHz

NOTE 11: Reference feed through is measured at the DAC output with an input code = 000 hex and a Vref input = 2.048 Vdc + 1 Vpp at 1 kHz.



### **Parameter Measurement Information**

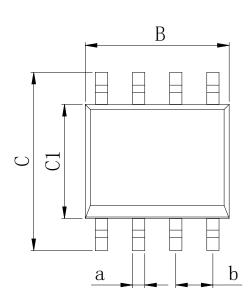


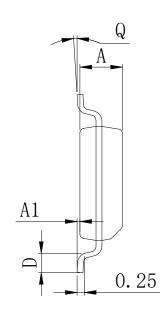
- A. The input clock, applied at the SCLK terminal, should be inhibited low when CS is high to minimize clock feedthrough.
- B. Data input from preceeding conversion cycle.
- C. Sixteenth SCLK falling edge



# **Physical Dimensions**

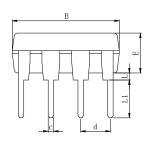
## SOP-8



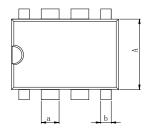


Dimensions In M	Dimensions In Millimeters(SOP-8)									
Symbol:	Α	A1	В	С	C1	D	Q	а	b	
Min:	1.35	0.05	4.90	5.80	3.80	0.40	0°	0.35	1 27 DSC	
Max:	1.55	0.20	5.10	6.20	4.00	0.80	8°	0.45	1.27 BSC	

DIP-8





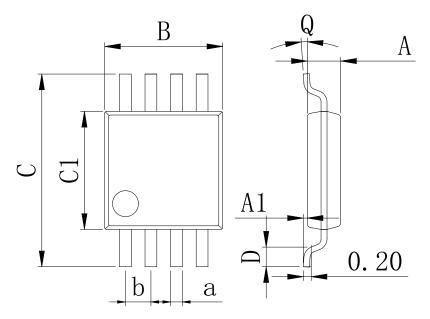


Dimensions In Millimeters(DIP-8)											
Symbol:	Α	В	D	D1	Е	L	L1	а	b	С	d
Min:	6.10	9.00	8.10	7.42	3.10	0.50	3.00	1.50	0.85	0.40	2.54 BSC
Max:	6.68	9.50	10.9	7.82	3.55	0.70	3.60	1.55	0.90	0.50	



# **Physical Dimensions**

MSOP-8



Dimensions In Millimeters(MSOP-8)									
Symbol:	Α	A1	В	С	C1	D	Q	а	b
Min:	0.80	0.05	2.90	4.75	2.90	0.35	0°	0.25	0.05.000
Max:	0.90	0.20	3.10	5.05	3.10	0.75	8°	0.35	0.65 BSC



## **Revision History**

DATE	REVISION	PAGE			
2015-8-9	New	1-12			
2023-8-26	Update encapsulation type 、 Update Lead Temperature 、 Updated DIP-8	1, 4, 9			
2023-0-20	dimension				



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