

9DOF 2 Click



PID: MIKROE-4128

9DOF 2 Click is a compact add-on board for applications which require lowest power motion tracking and magnetometer functionality. This board features the [ICM-20948](#) a 9-axis MotionTracking™ sensor from TDK Invensense, which consist of two sensors combined into one package for universal 9DOF solution. In this package we have 3-axis gyroscope, a 3-axis accelerometer, 3-axis magnetometer, combined with Digital Motion Processor™ (DMP) and run-time calibration firmware. All this features makes 9DOF 2 Click excellent choice for manufacturers looking for a product to eliminate the costly and complex selection, qualification, and system level integration of discrete devices, guaranteeing optimal motion performance for consumers. Its also ideally suited for wearable sensors and IoT applications needed low power motion tracking device expandable with additional I2C sensors.

9DOF 2 Click is supported by a mikroSDK compliant library, which includes functions that simplify software development. This Click board™ comes as a fully tested product, ready to be used on a system equipped with the mikroBUS™ socket.

How does it work?

9DOF 2 Click is based on the ICM-20948, a high performance, 9-axis MotionTracking™ IC from TDK Invensense. ICM-20948 also supports an auxiliary I2C interface to external sensors which offer a greater system flexibility. The output of each MEMS is processed and digitized by a separate sigma-delta 16-bit A/D converter (ADC). Three-axis gyroscope MEMS can be programmed to measure the rotation about each axis, in four different ranges of rotational speed (degrees per angle, DPS): ± 250 , ± 500 , ± 1000 , and ± 2000 . Three-axis accelerometer MEMS can be programmed to measure the acceleration along each axis, in four different acceleration ranges: $\pm 2g$, $\pm 4g$, $\pm 8g$, and $\pm 16g$. Three-axis magnetometer can do a full scale

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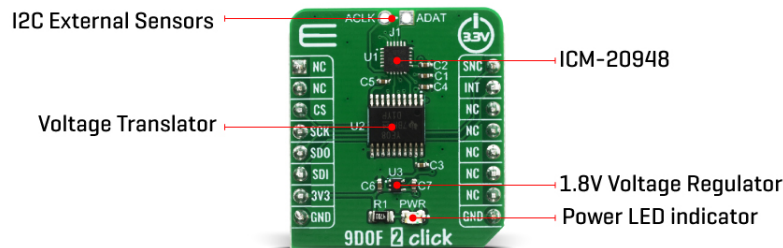


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measurement of $\pm 4900 \mu T$.



Interrupt functionality is configured via the Interrupt Configuration register. Items that are configurable include the INT pin configuration, the interrupt latching and clearing method, and triggers for the interrupt. The interrupt is routed to the INT pin of the mikroBUS™.

A FIFO buffer helps to further reduce the processing load, offering temporary storage for the output data. The ICM-20948 contains a FIFO of size 512 bytes (FIFO size will vary depending on DMP feature-set) that is accessible via the Serial Interface. The FIFO configuration register determines which data is written into the FIFO. Possible choices include gyro data, accelerometer data, temperature readings, auxiliary sensor readings, and FSYNC input. Synchronization with an external digital signal is possible over the FSYNC pin. This pin is routed to the PWM pin of the mikroBUS™, labeled as SNC.

The embedded Digital Motion Processor (DMP) within the ICM-20948 offloads computation of motion processing algorithms from the host processor. The DMP acquires data from accelerometers, gyroscopes, and additional third party sensors such as magnetometers, and processes the data. The resulting data can be read from the FIFO. The DMP has access to the external pins, which can be used for generating interrupts.

ICM-20948 supports both SPI and I2C communication interfaces but only SPI interface is used on the 9DOF 2 Click. The voltage level conversion between ICM-20948 and 3.3V MCU is done by the [TXB0108](#) bidirectional voltage level translator.

This Click Board™ uses only SPI communication interface. It is designed to be operated only with 3.3V logic levels. A proper logic voltage level conversion should be performed before the Click board™ is used with MCUs with logic levels of 5V.

Specifications

Type	Gyroscope,Magnetic,Motion
Applications	Can be used for Smartphones and Tablets, wearable sensors and IoT Applications.
On-board modules	9DOF 2 Click uses the ICM-20948 IC, the world's lowest power 9-axis MotionTracking device, from TDK Invensense.

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Key Features	Mobile phones, tablet PCs, GPS systems, Smart watches, Sport and fitness devices, and many more.
Interface	SPI
Feature	No ClickID
Compatibility	mikroBUS™
Click board size	S (28.6 x 25.4 mm)
Input Voltage	3.3V

Pinout diagram

This table shows how the pinout on 9DOF 2 Click corresponds to the pinout on the mikroBUS™ socket (the latter shown in the two middle columns).

Notes	Pin					Pin	Notes
	NC	1	AN	PWM	16	SYN	External sync
	NC	2	RST	INT	15	INT	Interrupt
SPI Chip Select	CS	3	CS	RX	14	NC	
SPI Clock	SCK	4	SCK	TX	13	NC	
SPI Data OUT	SDO	5	MISO	SCL	12	NC	
SPI Data IN	SDI	6	MOSI	SDA	11	NC	
Power Supply	3.3V	7	3.3V	5V	10	NC	
Ground	GND	8	GND	GND	9	GND	Ground

Onboard settings and indicators

Label	Name	Default	Description
LD1	PWR	-	Power LED Indicator

Software Support

We provide a library for the 9DOF 2 Click on our [LibStock](#) page, as well as a demo application (example), developed using MikroElektronika [compilers](#). The demo can run on all the main MikroElektronika [development boards](#).

Library Description

The library covers all the necessary functions that enables the usage of the 9DOF 2 Click board. It initializes and defines the SPI bus driver and drivers that offer a plethora of settings. The library also offers functions that allow reading of accelerometer, gyroscope pressure and temperature, as well as generic read and write function that offer reading(and writing) of different lengths of data to all available registers.

Key functions:

- void c9dof2_angular_rate (float *x_ang_rte, float *y_ang_rte, float *z_ang_rte); - Function is used to calculate angular rate.
- void c9dof2_acceleration_rate (float *x_accel_rte, float *y_accel_rte, float *z_accel_rte);

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- Function is used to calculate acceleration rate.
- void c9dof2_def_settings (); - Function is used to apply the default settings to the device.

Examples description

The application is composed of three sections :

- System Initialization - Initializes SPI module, LOG and GPIO structures, sets INT pin as input and PWM as output.
- Application Initialization - Initializes SPI and device drivers, performs safety check, applies default and writes an initial log.
- Application Task - (code snippet) Demonstrates use of 9DOF 2 click board by reading angular rate, acceleration rate and displaying data via USART terminal.

The full application code, and ready to use projects can be found on our [LibStock](#) page.

Other mikroE Libraries used in the example:

- SPI
- UART
- Conversions

Additional notes and informations

Depending on the development board you are using, you may need [USB UART click](#), [USB UART 2 click](#) or [RS232 click](#) to connect to your PC, for development systems with no UART to USB interface available on the board. The terminal available in all MikroElektronika [compilers](#), or any other terminal application of your choice, can be used to read the message.

mikroSDK

This Click board™ is supported with [mikroSDK](#) - MikroElektronika Software Development Kit. To ensure proper operation of mikroSDK compliant Click board™ demo applications, mikroSDK should be downloaded from the [LibStock](#) and installed for the compiler you are using.

For more information about mikroSDK, visit the [official page](#).

Resources

[mikroBUS™](#)

[mikroSDK](#)

[Click board™ Catalog](#)

[Click Boards™](#)

Downloads

[9DOF 2 click example on Libstock](#)

[TXB0108 datasheet](#)

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[ICM-20948 datasheet](#)

[9DOF 2 click 2D and 3D files](#)

[9DOF 2 click schematic](#)

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