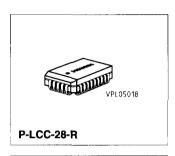
# ISDN Primary Access Transceiver (IPAT®)

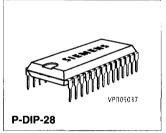
**PEB 2235** 

#### CMOS IC

#### **Features**

- ISDN line interface for 1544 and 2048 kbit/s (T1, NTT and CEPT)
- Data and clock recovery
- Transparent to ternary codes
- Low transmitter output impedance for a high return loss with reasonable protection resistors (CCITT G.703 requirements for the line input return loss fulfilled).
- Adaptively controlled receiver threshold
- Programmable pulse shape for T1 applications
- Jitter specifications of CCITT I.431, TR-TSY-000312 and many AT&T/BELLCORE publications met.
- Jitter tolerance of receiver: 0.43 UI s
- Implements local and remote loops for diagnostic purposes
- Monolithic line driver for a minimum of external components
- Low power, reliable 2 μ CMOS technology





Туре	Version	Ordering Code	Package
PEB 2235-N	V4.1	Q67100-H6208	P-LCC-28-R (SMD)
PEB 2235-P	V4.1	Q67100-H6207	P-DIP-28

The ISDN Primary Access Transceiver IPAT® (PEB 2235) is a monolithic CMOS device which implements the analog receive and transmit line interface functions to primary rate PCM carriers. It may be programmed or hard wired to operate in 24 channel (T1) or 32 channel (CEPT) carrier systems.

The IPAT recovers clock and data using an adaptively controlled receiver threshold. It is transparent to ternary codes and shapes the output pulse following the AT&T Technical Advisory # 34 or CCITT G.703. The jitter tolerance of the device meets the latest CCITT (I.431), latest US recommendations (TR-TSY-000312), NTT specification and many other specifications by AT&T/BELLCORE. Diagnostic facilities are included.

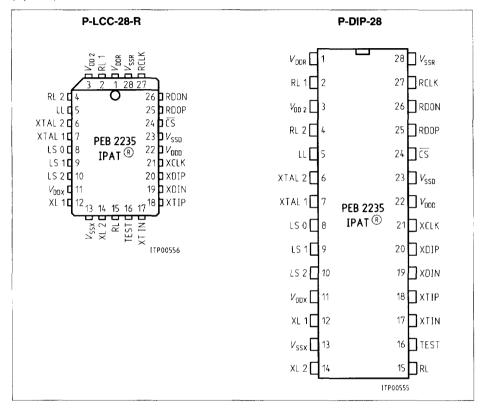
Specially designed line interface circuits simplify the tedious task of protecting the device against overvoltage damage while still meeting the return loss requirements.

The IPAT is suitable for use in a wide range of voice and data applications such as for connections of digital switches and PABX's to host computers, for implementations of primary ISDN subscriber loops as well as for terminal applications. The maximum range is determined by the maximum allowable attenuation.

In the T1 case the IPAT's power consumption is mainly determined by the line length and type of the cable.

### **Pin Configuration**

(top view)



## Pin Definitions and Functions

Pin No.	Symbol	Input (I) Output (O)	Function
1	$V_{DDR}$	ı	Positive power supply for the receive subcircuits
2	RL1	1	Line receiver pin 1
3	$V_{DD2}$	0	Reference voltage output for tapping the input transformer
4	RL2	ı	Line receiver pin 2
5	LL	1	Local loopback: A high level selects the device for the local loopback mode
6 7	XTAL2 XTAL1	0	Reference clock inputs: A 24704- or 32768-kHz crystal reference should be connected to these pins for T1 or CEPT applications, respectively. It is also possible to connect an external precision clock to XTAL1 leaving XTAL2 unconnected. The external reference must be provided at full CMOS levels.
8 9 10	LS0 LS1 LS2	1 1	Line length select: determine to what extent the line output signals are preshaped prior to transmission
11	$V_{DDX}$	1	Positive power supply for transmit subcircuits
12	XL1	0	Line transmitter pin 1
13	$V_{SSX}$	ſ	Ground for transmit subcircuits
14	XL2	0	Line transmitter pin 2
15	RL	ı	Remote loopback: A high level puts the device to the remote loopback mode
16	TEST	1	Test input not connected or connected to $V_{ m DD}$
17 18	XTIN XTIP	1	Positive and negative transmit test data inputs, active low, half or fully bauded
19 20	XDIN XDIP	. I	Positive and negative transmit data inputs, active low, half or fully bauded
21	XCLK		Transmit Clock
22	$V_{DDD}$	. 1	Positive power supply for the digital subcircuits
23	$V_{SSD}$	1	Power ground supply for the digital subcircuits
24	ĊS	ı	Chip Select: A low level selects the PEB 2235 for a register write operation
25 26	RDOP RDON	0	Receive data output positive and negative, fully bauded, active low

#### Pin Definitions and Functions (cont'd)

Pin No.	Symbol	Input (I) Output (O)	Function
27	RCLK	0	Receive clock
28	$V_{SSR}$	1	Power ground supply for receive subcircuits

#### **Logic Symbol and Wiring**

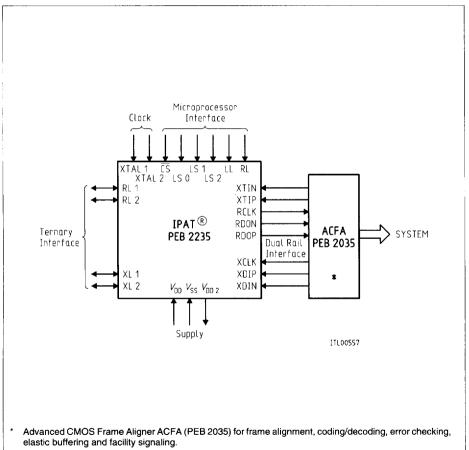


Figure 1 Logic Diagram of the IPAT®

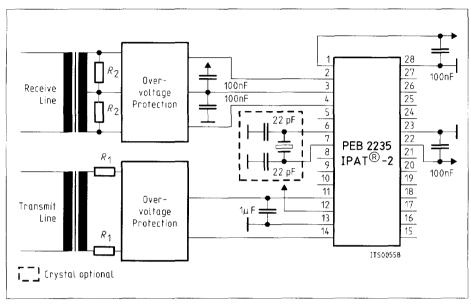


Figure 2
External Wiring of the IPAT®

#### **System Integration**

**Figure 3** shows the architecture of a primary access board with common channel signaling using four CMOS devices. It exhibits the following functions:

Line Interface (PEB 2235)

Clock and Data Recovery (PEB 2235)

Coding/Decoding (PEB 2035)

Framing (PEB 2035)

Elastic Buffer (PEB 2035)

Switch (PEB 2045)

System Adaptation (PEB 2045)

Data Link Signaling Handling (SAB 82525)

μP Interface (all devices)

Since the PEB 2045 is a switch for 256 output time slots and the SAB 82525 is actually a dual channel HDLC controller a quad primary access unit with a non-blocking switch requires a total of 11 devices.

- 4 IPAT (PEB 2235)
- 4 ACFA (PEB 2035)
- 2 HSCX (SAB 82525)
- 1 MTSC (PEB 2045),

as shown in figure 4.

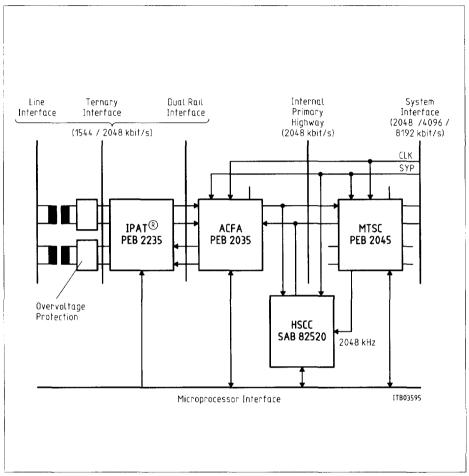


Figure 3
Architecture of a Primary Access Unit

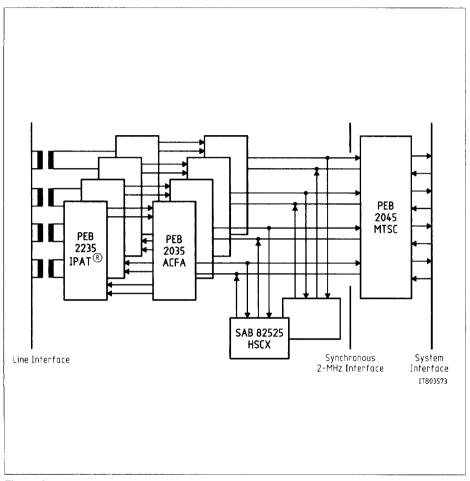


Figure 4
Quad Primary Access Unit

#### **Functional Description**

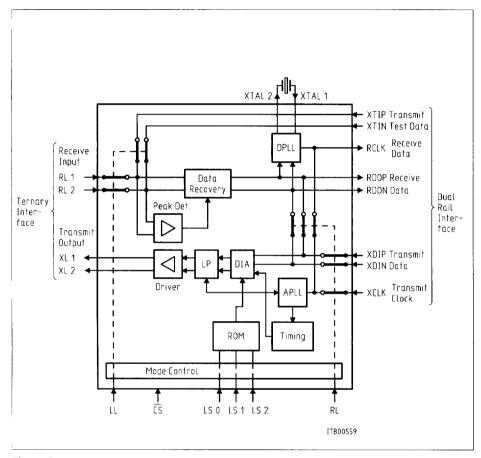


Figure 5
Functional Block Diagram of the IPAT®

#### Receiver

#### **Basic Functionality**

The receiver recovers data from the ternary coded signal at the ternary interface and outputs it as 2 unipolar signals at the dual rail interface. One of the lines carries the positive pulses, the other the negative pulses of the ternary signal.

The signal at the ternary interface is received at both ends of a center-tapped transformer as shown in **figure 6**.

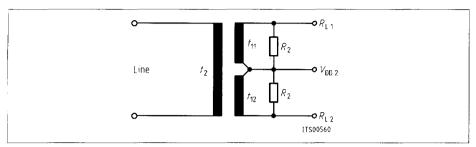


Figure 6 Receiver Configuration

The transformer is center-tapped at the IPAT side. The recommended transmission factors for the different line characteristic impedances are listed in **table 1**.

Table 1
Recommended Receiver Configuration Values

Application	T-	/NTT	C	EPT
Characteristic Impedances [Ω]	100	140 (ICOT)	120	75
$R_2 \pm (2.5 \%) [\Omega]$	28.7	39.2	60	60
$t_2: t_1 = t_2: (t_{11} + t_{12})$	69 : 52 69 : (26 + 26)	69 : 52 69 : (26 + 26)	52 : 52 52 : (26 + 26)	41 : 52 41 : (26 + 26)

Wired in this way the receiver has a return loss

 $a_r > 12 \text{ dB for } 0.025 f_b \le f \le 0.05 f_b$ 

 $a_{\rm r} > 18$  dB for  $0.05 f_{\rm b} \le {\rm f} \le 1.0 f_{\rm b}$  and

 $a_r > 14 \text{ dB for } 1.0 f_b \le f \le 1.5 f_b$ 

with  $f_b$  being 2048 kHz. Thus it complies with CCITT G.703.

The receiver is transparent to the logical 1's polarity and outputs positive logical 1's on RDOP and negative logical 1's on RDON. RDON and RDOP are active low and fully bauded. The comparator threshold to detect logical 1's and logical 0's is automatically adjusted to be 44 % of the peak signal level.

Provided the noise is below 10  $\mu$ V/ $\sqrt{Hz}$  the bit error rate will be less than 10<sup>-7</sup>. The data is stable, and hence may be sampled at the falling edge of the recovered clock RCLK.

#### PLL

A digital PLL extracts the receive clock RCLK from the data stream received at the RL1 and RL2 lines. The PLL uses as a reference either a crystal at XTAL1 and XTAL2 or an external oscillator at XTAL1. The IPAT does not remove any jitter. Since the crystal frequency is 16 times the input data frequency the digital PLL adds an jitter of max. 0.0625 (unit intervals). In the absence of an input signal the jitter of clock, and recovered data lies within the tolerance range of the used reference.

#### Input Jitter Tolerance

The IPAT receiver's tolerance to input jitter complies to CCITT and AT&T requirements for CEPT and T1 application.

Figure 7 shows the curves of the different input jitter specifications stated above as well as the IPAT performance for the various line codes used at the S1/S2 interfaces.

As can be seen in **figure 7**, the curve for the IPAT at low frequencies describes a 20 dB/decade fall off, and at high frequencies a horizontal (at least 0.43 UI).

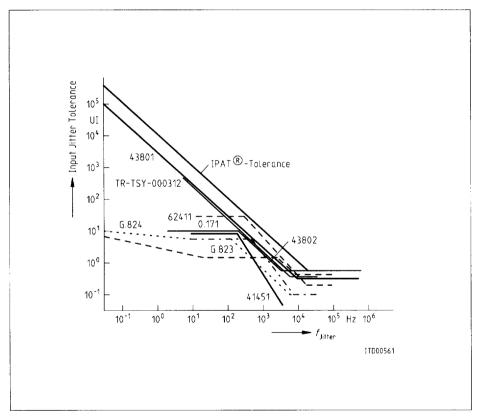


Figure 7
Comparison of Input Jitter Specification and IPAT® Performance

#### **Transmitter**

#### **Basic Functionality**

The transmitter transforms unipolar data to ternary (alternate bipolar) return to zero signals of the appropriate shape. The unipolar data is provided at XDIP (positive pulses) and XDIN (negative pulses), synchronously with the transmit clock XCLK. XDIP and XDIN are active low and can be half or fully bauded.

The transmitter includes a programmable pulse shaper to satisfy the requirements of the AT&T Technical Advisory #34 at the cross connect point for T1 applications. The pulse shaper is programmed via the line length selection pins LS0, LS1 and LS2. The pulse shape is formed using an analog PLL, which multiplies by four the transmit clock XCLK. This signal is used internally to generate the 4 segment/bit transmit pulse (CEPT: 2 segment/bit).

For T1 application the line length selection supports both low capacitance cable with a characteristic line capacitance of  $C' \le 40$  nF/km  $\equiv 65$  nF/mile (e.g. MAT, ICOT) and higher capacitance cable with a characteristic line capacitance of 40 nF/km  $\le C' \le 54$  nF/km (65 nF/mile  $\le C' \le 87$  nF/mile) e.g. ABAM, PIC and PULP cables. This ensures that for various cable types the signal at the DSX-1 cross connect point complies with the pulse shape of the AT&T Technical Advisory # 34.

The line length is selected programming the LS0, LS1 and LS2 pins as shown for typical values in table 2

Table 2 Line Length Selection

LS2	LS1	LS0		PIC/PULP-Cable 24 AWG Range/m	ICOT-Cable Range/m*
0	0	0	CEPT	_	_
0	0	1	T1/NTT	0 - 50	0 - 80
0	1	0	T1	20 - 80	65 – 145
0	1	1	T1	60 130	130 – 210
1	0	0	T1	110 – 200	195 – 275
1	0	1	T1	140 – 230	260 – 340
1	1	0	T1	210 – 290	325 – 405
1	1	1	T1	270 – 320	390 – 470

Note: For ICOT-cable the characteristic impedance is 140 Ω.

By selecting an all-zero code for LS0, LS1 and LS2 the IPAT can be adapted for CEPT applications.

The pulse shape for NTT applications is achieved by using the same line length selection code as for the lowest T1 cable range. To switch the device into a low power dissipation mode, XDIP and XDIN should be held high.

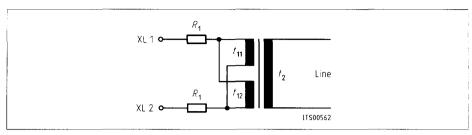


Figure 8
Transmitter Configuration

Table 3: Transmitter Configuration Values

Application		T1/NTT	CEPT		
Characteristic line impedances [Ω]	100	140 (ICOT)	120	75	
$t_{11}: t_2 = t_{12}: t_2$	26 : 69	26 : 69	26 : 52	26 : 41	
$R_1$ (± 2.5 %) [ $\Omega$ ]	4.3	6	15	15	

The transmitter requires an external step up transformer to drive the line. The transmission factor and the source serial resistor values can be seen in **figure 8** and **table 3** for the various applications.

Wired in this way the transmitter has a return loss

 $a_r > 8 \text{ dB for } 0.025 f_b \le f \le 0.05 f_b$ 

 $a_{\rm r} > 14 \text{ dB for } 0.05 f_{\rm b} \le {\rm f} \le 1.0 f_{\rm b}$  and

 $a_{\rm r} > 10$  dB for  $1.0 f_{\rm h} \le {\rm f} \le 1.5 f_{\rm h}$ ,

with  $f_b$  being 2048 kHz (CEPT applications). A termination resistor of 120  $\Omega$  is assumed.

In T1 and NTT applications the return loss is higher than 10 dB.

Please note, that the transformer ratio at the receiver is half of that at the transmitter. The same type of transformer can thus be used at the receiver and at the transmitter. At the transmitter the two windings are connected in parallel, at the receiver in series. Thus, unbalances are avoided.

#### **Output Jitter**

In the absence of any input jitter the IPAT generates an output jitter at most 0.014 UI in CEPT and 0.01 UI in T1 applications.

#### Local Loopback

The local loopback mode disconnects the receive lines RL1 and RL2 from the receiver. Instead of the signals coming from the line the data provided at XTIP and XTIN is routed through the receiver. The XDIN and XDIP signals continue to be transmitted on the line. The local loopback occurs in response to LL going high.

#### Remote Loopback

In the remote loopback mode the clock and data recovered from the line inputs RL1 and RL2 are routed back to the line outputs XL1 and XL2 via the transmitter. As in normal mode they are also output at RDOP, RDON and RCLK. XDIP and XDIN are disconnected from the transmitter. In this mode a device jitter of 0.0765 UI for CEPT and 0.0725 UI for T1 is added.

The remote loopback mode is selected by a high RL signal.

Please keep in mind that the IPAT is not capable of removing jitter. Therefore in remote loopback mode jitter is not reduced.

### Microprocessor Interface

The IPAT is fully controlled by five parallel data lines (LS0, LS1, LS2, LL and RL) and one control line  $(\overline{CS})$ . To adapt the device to a standard microprocessor interface the low state of  $\overline{CS}$  is decoded from the microprocessor address,  $\overline{CS}$ ,  $\overline{WR}$  and ALE lines.

To hardwire the chip,  $\overline{CS}$  must be fixed to ground.

#### **Loss of Signal Indication**

In the case that the signal at the line receiver input (pins RL1, RL2) becomes smaller than  $V_{\rm IN} \le 0.4~V_{\rm OP}$  loss of signal is indicated. This voltage value corresponds to a line attenuation of about 12 dB in the CEPT case. This is performed by turning both signals RDOP, RDON after at least 16 bits simultaneously to  $V_{\rm DDD}$ , i.e. a logical 0 on both lines. The following ACFA processes this indication for the system.

#### Operational Description

#### Reset

In order to work properly, the IPAT needs to be started with a software reset. This is done by simultaneously setting the pins PL and LL to logical 1 (i.e. 5 V) for at least one bit period and releasing both lines thereafter simultaneously.

It is possible to connect the pins RL and LL to  $V_{\rm DD}$  and to consequently turn on the power supply. In this way a power-up reset is achieved.

#### Selection of CEPT, T1 or NTT Application

Besides the crystal frequency the selection of CEPT, T1 or NTT application is achieved by setting the pins LS2, LS1, LS0 simultaneously with the reset to 000 for CEPT application, to 001 for the NTT applications or to a T1 line length code (001 ... 111 see **table 2**).

#### **Line Length Selection**

In the second step the line selection code has to be given. This will be normally the same one as in the first step.

The following figures explain the procedure in some examples.

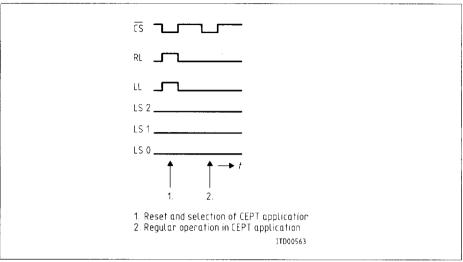


Figure 9
Timing of Software Programming for CEPT Applications

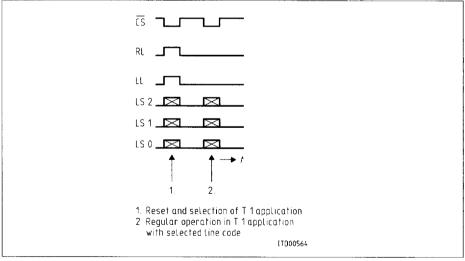


Figure 10
Timing of Software Programming for T1 Application

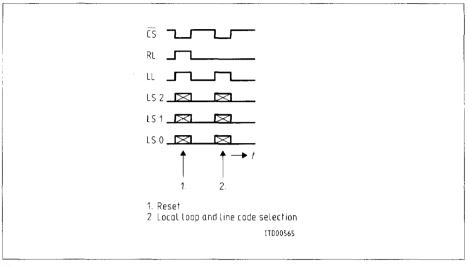


Figure 11
Timing of Software Programming for LL Operation at CEPT or T1 Applications

## **Electrical Specification**

## **Absolute Maximum Ratings**

Parameter	Symbol	Limit Values	Unit
Voltage on any pin with respect to ground	$V_{S}$	$-0.4$ to $V_{\rm DD}$ + 0.4	V
Ambient temperature under bias	$T_{A}$	0 to 70	c
Storage temperature	$T_{stg}$	- 65 to 125	Ĉ

### **DC Characteristics**

 $T_{\rm A}$  = 0 to 70 °C;  $V_{\rm DD}$  = 5 V ± 5 %,  $V_{\rm SS}$  = 0 V

Parameter	Symbol	Limit \	Values	Unit	Test Condition	Pins
		min.	max.	1		
L-input voltage	$V_{IL}$	- 0.4	0.8	V		
H-input voltage	$V_{IH}$	2.0	V <sub>DD</sub> + 0.4	V		All pins
L-output voltage	$V_{OL}$		0.45	٧	I <sub>OL</sub> = 2 mA	except RLx.
H-output voltage H-output voltage	$V_{OH} \ V_{OH}$	2.4 <i>V</i> <sub>DD</sub> – 0.5		V	$I_{\text{OH}} = -400 \mu\text{A}$ $I_{\text{OH}} = -100 \mu\text{A}$	XLx, XTALx, V <sub>DD2</sub>
Input leakage current Output leakage current	I <sub>LI</sub> I <sub>LO</sub>		10	μА	$ \begin{array}{c c} \text{O V} < V_{\text{IN}} < V_{\text{DD}} \text{ to 0 V} \\ \text{O V} < V_{\text{OUT}} < V_{\text{DD}} \text{ to 0 V} \\ \end{array} $	
Peak voltage of a mark (CEPT) Peak voltage of a mark (T1)	$V_{XCEPT}$ $V_{XT1}$	1.8	3.3	v v	wired according figure 8 and table 3 T1 application: depending on line length	
Transmitter output impedance	$R_{X}$		0.3	Ω		XL1, XL2
Transmitter output current	I <sub>×</sub>		50 150	mA mA	CEPT application T1 application: depending on line length	
Receiver input peak voltage of a mark	$V_{R}^{\star}$	0.4	2.5	V	BER 10 <sup>-7</sup> , wired according figure 6 and table 1	RL1,
Receiver input threshold	$V_{RTH}$		45	%	of mark peak	RL2
Voltage at $V_{\rm DD2}$	$V_{DD2}$	2.4	2.6	٧		
L-input voltage	$V_{XTALIL}$	- 0.4	1.0	٧		
H-input voltage	$V_{XTALIH}$	4.0	V <sub>DD</sub> + 0.4	٧		
Input leakage current	IXTALI		10	μ <b>A</b>	$0 \text{ V} \leq V_{\text{IN}} \leq V_{\text{DD}} \text{ to } 0 \text{ V}$	1
Operational power supply current	Icc	40 55	110 190	mA mA	CEPT application T1 application, min. value for all zeros, max. value for all ones and max. line length for T1 appl.	XTAL1, XTAL2

 $<sup>^\</sup>star$  measured against  $V_{ t pp2}$ 

#### Capacitances

$$T_{\rm A}$$
 = 25 °C,  $V_{\rm DD}$  = 5 V ± 5 %,  $V_{\rm SS}$  = 0 V

Parameter	Symbol	Lin	nit Values	Unit	Pins
		min.	max.		
Input capacitance	$C_{IN}$		10	pF	all except RLx, XLx, XTALx
Output capacitance	$C_{OUT}$		15	pF	all except RLx, XLx, XTALx
Input capacitance	$C_{IN}$		7	pF	RLx
Output capacitance	$C_{OUT}$		20	pF	XLx
Load capacitance	$C_{LD}$		10	pF	XTALx

#### **Recommended Oscillator Circuits**

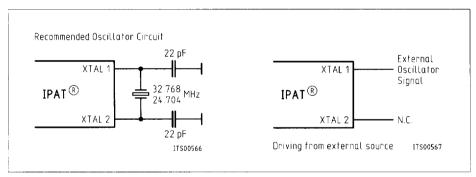


Figure 12 Oscillator Circuits

If no crystal is used XTAL1 has to be connected to an external precision clock source and XTAL2 left unconnected.

In CEPT applications, the oscillator circuit should provide a 32768-kHz clock, in T1 applications 24704 kHz.

If no signal is received, a  $\pm$  50 ppm frequency range of the oscillator circuit transforms into a  $\pm$  50 ppm range of the RCLK signal.

#### **AC Characteristics**

 $T_{\rm A}$  = 0 to 70 °C,  $V_{\rm DD}$  = 5 V ± 5 %

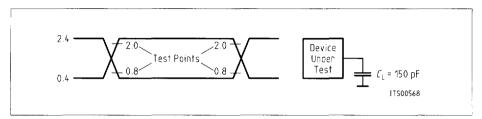


Figure 13 Input/Output Waveform for AC Tests

Except from the ternary and clock interface, inputs are driven at 2.4 V for a logical 1 and at 0.4 V for a logical 0. Timing measurements are made at 2.0 V for a logical 1 and at 0.8 V for a logical 0. The AC testing input/output waveforms are shown in **figure 15**.

In the receive direction the IPAT adds at most 0.0625 UI intrinsic jitter. This is true for both jitter free as well as jitterized inputs. In transmit direction the IPAT adds at most 0.014 UI of jitter in CEPT and 0.01 UI in T1 applications measured in the frequency range 20 Hz ... 185 kHz.

In both directions the device does not remove or attenuate the accumulated jitter.

#### **Dual Rail Interface**

RDOP, RDON, XDIP, XDIN, XTIP, XTIN are active low.

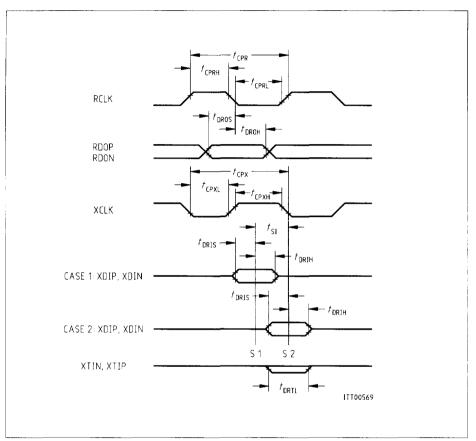


Figure 14 Timing of the Dual Rail Interface

Note: For the data XDIP, XDIN both cases are possible. The IPAT detects a logical one, if XDIP, XDIN is low for the sampling point S1 or S2!

## **Dual Rail Interface Timing Parameter Values**

Symbol		Limit	Values		Unit
	PC	M 30	PC	M 24	1
	min.	max.	min.	max.	
t <sub>CPR</sub>	typ	. 488	typ	. 648	ns
t <sub>CPRL</sub>	200		260		ns
t <sub>CPRH</sub>	200		260		ns
t <sub>DROS</sub>	200		260		ns
$t_{DROH}$	200		260		ns
$t_{CPX}$	typ	. 488	typ	. 648	ns
$t_{CPXL}$	80	300	100	430	ns
t <sub>CPXH</sub>	125	350	170	500	ns
t <sub>SI</sub>	55	67	75	87	ns
t <sub>DRIS</sub>	25		25		ns
t <sub>DRIH</sub>	25		25		ns
t <sub>DRTL</sub>	170		220		ns
	ICPR ICPRL ICPRH IDROS IDROH ICPX ICPXL ICPXL ICPXL ICPXH ISI IDRIS IDRIH	PC   min.   t <sub>CPR</sub>   typ.   t <sub>CPRL</sub>   200   t <sub>CPRH</sub>   200   t <sub>DROS</sub>   200   t <sub>DROH</sub>   200   t <sub>CPX</sub>   typ.   t <sub>CPXL</sub>   80   t <sub>CPXL</sub>   125   t <sub>SI</sub>   55   t <sub>DRIS</sub>   25   t <sub>DRIH</sub>   25	PCM 30   min.   max.   tcpr   typ. 488   tcpr   200     tcpr   200     tcpr   200     tcpr   488   tcpr   488   tcpr   80   300   tcpr   125   350   tsi   55   67   tdpr   25   tdpr	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	PCM 30         PCM 24           min.         max.         min.         max.           t <sub>CPR</sub> typ. 488         typ. 648           t <sub>CPRL</sub> 200         260           t <sub>CPRH</sub> 200         260           t <sub>DROS</sub> 200         260           t <sub>CPX</sub> typ. 488         typ. 648           t <sub>CPXL</sub> 80         300         100         430           t <sub>CPXH</sub> 125         350         170         500           t <sub>SI</sub> 55         67         75         87           t <sub>DRIS</sub> 25         25         25           t <sub>DRIH</sub> 25         25         25

## **Microprocessor Interface**

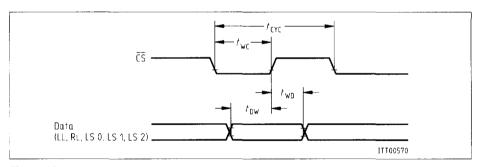


Figure 15 Timing of the Microprocessor Interface

Parameter	Symbol	Lin	nit Values	Unit
		min.	max.	
CS pulse width	t <sub>wc</sub>	60		ns
Data set up time to CS	$t_{\sf DW}$	35		ns
Data hold time from CS	t <sub>WD</sub>	10		ns
Cycle Time	$t_{CYC}$	120		ns

## **XTAL Timing**

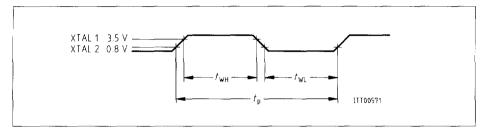


Figure 16 Timing of XTAL1/XTAL2

## **Clock Timing Parameter Values**

Parameter	Symbol	Limit Values			Unit	Mode
		min.	typ.	max.		
Clock period of crystal/clock	t <sub>P</sub>		30.5		ns	CEPT
	$t_{P}$		40.5		ns	T1
High phase of crystal/clock	t <sub>wh</sub>	10			ns	CEPT
	t <sub>WH</sub>	14			กร	T1
Low phase of crystal/clock	t <sub>WL</sub>	10			ns	CEPT
	t <sub>WL</sub>	14			ns	T1

## Ternary Interface - Receiver

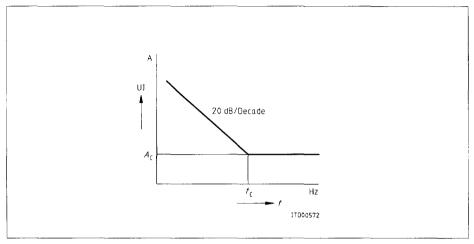


Figure 17 IPAT® Receive Jitter Tolerance

Parameter	Symbol	Limit Values		Unit	Mode
		min.	max.		
Corner frequency	f <sub>c</sub>	40 30		kHz kHz	CEPT T1
Corner amplitude	$A_{C} \ A_{C}$	0.43 0.43		UI UI	CEPT T1

#### Ternary Interface - Transmitter

The IPAT meets both CCITT and T1 pulse template requirements.

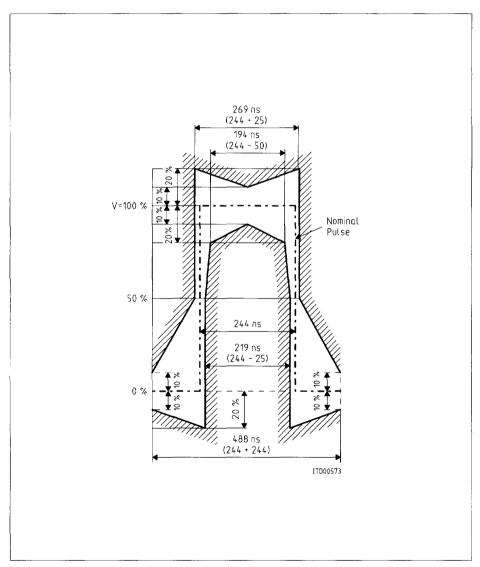


Figure 18
Pulse Template at the Transmitter Output for CEPT Applications

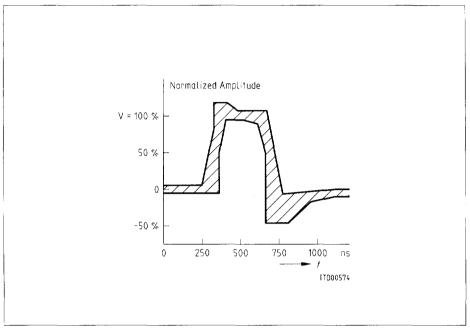


Figure 19
T1 Pulse Shape at the Cross Connect Point

Table 4
T1 Pulse Template Corner Points at the Cross Connect Point

Maximum Curve	Minimum Curve
( 0, 0.05)	( 0, - 0.05)
( 250, 0.05)	( 350, – 0.05)
( 325, 0.80)	( 350, 0.50)
( 325, 1.15)	( 400, 0.95)
( 425, 1.15)	( 500, 0.95)
(500, 1.05)	( 600, 0.90)
(675, 1.05)	( 650, 0.50)
( 725, – 0.07)	( 650, - 0.45)
(1100, 0.05)	( 800, – 0.45)
(1250, 0.05)	( 925, – 0.20)
	(1100, - 0.05)
	(1250, – 0.05)

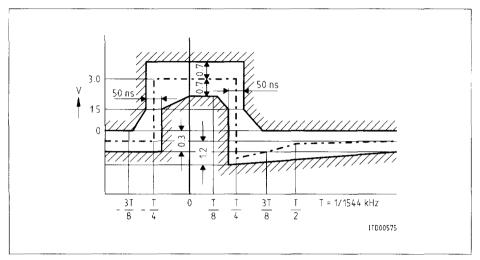


Figure 20 Pulse Shape at NTT Interface

### Overvoltage Tolerance

To prevent the IPAT from being damaged by overvoltage (i.e. from lightning), external devices like diodes or resistors have to be connected to one or both sides of the line interface transformers. Thus, overvoltage peaks are cut off. However, some residual overvoltage may remain.

The IPAT simplifies the task of designing external protection circuits. Its transmitter exhibits a low line impedance so that reasonable external resistors can be connected to the line outputs. **Figure 8** with the element values of **table 3** shows how an overvoltage protection against residual overvoltages at the ternary interface can be accomplished. The solution shown also meets the stated return loss requirements.

A similar consideration applies to the receiver. The resistors  $R_2$  of **figure 6** provide protection against residual overvoltages by attenuating voltages of both polarities across RL1 and RL2.

The maximum input current allowed to reach the IPAT pins under overvoltage conditions is given as a function of the width of a rectangular input current pulse according to **figure 21**. **Figure 22** shows the curve of the maximum allowed input current across the pins RL1 and RL2, **figure 23** across the pins XL1 and XL2.

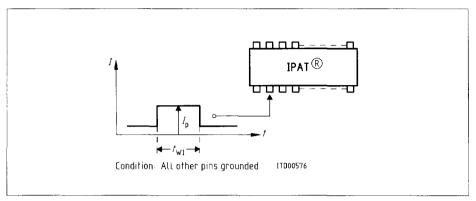


Figure 21
Measurement of Overvoltage Stress

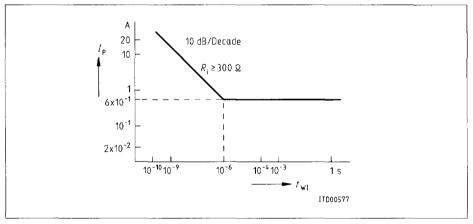


Figure 22
Tolerated Input Current at the RL1, RL2 Pins

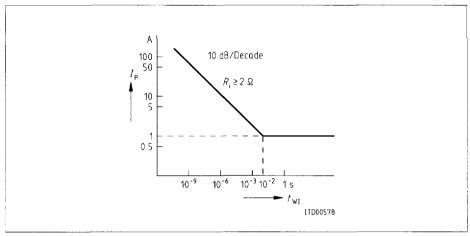


Figure 23
Tolerated Input Current at the XL1, XL2 Pins

### **Application Notes**

The high transmitter output currents of up to 160 mA require a careful consideration of the on board power supply and ternary interface output line routing.

#### **Modification List**

#### IPAT® Data Sheet 9/90

Power supply current:
 The values of I<sub>CC</sub> in DC Characteristics in the data sheet IPAT 1/90 are replaced by:

Parameter	Symbol	Limit Values		Unit	Test Condition	
		min.	max.			
Operational power supply current	I <sub>cc</sub>	40 55	110 190	mA mA	CEPT applications T1 applications min. value for all zeros, max. value for all ones and max. line length	

#### IPAT® Data Sheet 12/90

Absolute Maximum Ratings

#### IPAT® Data Sheet 11/91

- Dual Rail Interface Timing Parameter Values
- Transmitter and receiver configuration for ICOT cable