



Dual Bidirectional Motor Driver

Overview

The LB1649 is a dual bidirectional motor driver. Since each channel has a 2-input logic circuit and performs bidirectional driving and braking functions, it is capable of direct driving 2pcs. of motor of various types rated at 6 to 24V.

The output voltage can be varied by using external zener diodes.

It is especially suited for dual motor drive (reel motor, loading motor, cassette motor in VCR) and for stepping motor drive.

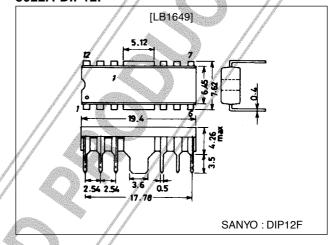
Features

- With power transistor for motor drive contained, capable of withstanding dash current of 1A max.
- Performs braking function at the motor stop mode.
- Contains elements to absorb motor dash current.
- Input connectable direct to MOS LSI.
- Minimun number of external parts required.
- Wide operating voltage range.

Package Dimensions

unit:mm

3022A-DIP12F



Specifications

Absolute Maximum Ratings at Ta = 25°C

	- 1			
Paramete	er 🥼	Symbol Conditions	Ratings	Unit
Maximum supply voltage		V _{CC} max	25	V
Input voltage		V _{IN}	25	V
Output current			±1	Α
Allowable power dissipation	-// *	Pd max	1.9	W
Operating temperature	// 60	Topr	-25 to +75	°C
Storage temperature	7/	Tstg	-55 to +125	°C

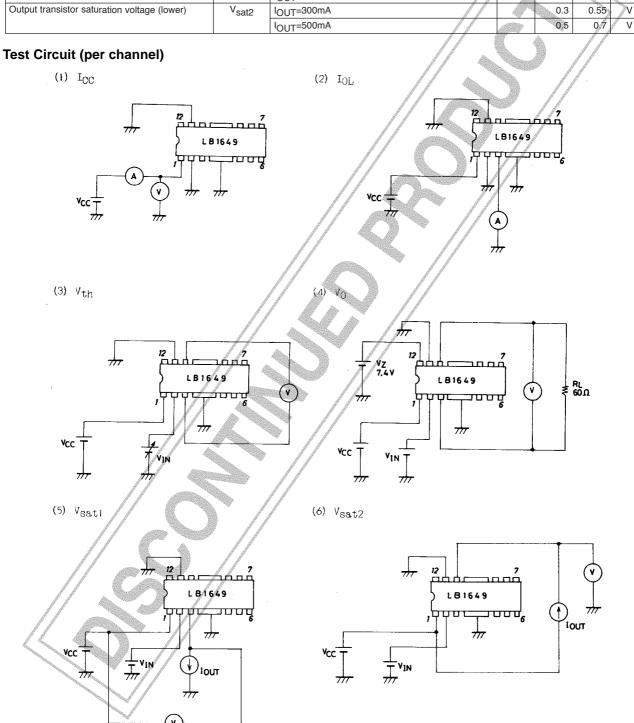
Allowable Operating Conditions at Ta = 25°C

	Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage		V _{CC}		7 to +25	٧

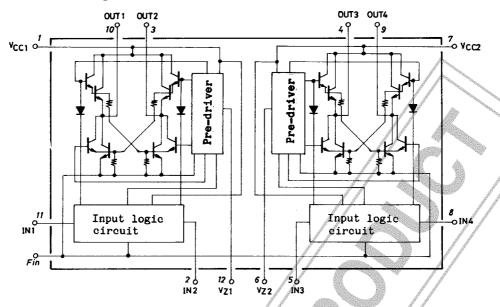
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Electrical Characteristics at Ta = 25 $^{\circ}$ C, V_{CC} =12V, per channel

Parameter	Symbol	Conditions		Ratings		
Farameter	Symbol	Conditions		typ	max	Unit
Current drain	Icc	Braking mode, R _L =∞, per channel		7.0	10.0	mA
Output leakage current	loL	Braking mode, R _L =∞, per channel	p ^a	40	120	μΑ
Input threshold voltage	V _{th}	R _L =∞	/ 0.9	1.05	1.20	V
Output voltage	VO	R _L =60Ω, V _Z =7.4V	6.	7.2	7.5	V
Output transistor saturation voltage (upper)	V _{sat1}	I _{OUT} =300mA		1.9	2.3	V
		I _{OUT} =500mA		2.0	2.4	V
Output transistor saturation voltage (lower)	V _{sat2}	I _{OUT} =300mA		0.3	0.55	V
		I _{OUT} =500mA	(50)	0.5	0.7	₹ V



Equivalent Circuit Block Diagram



Truth Table of Logic Circuit

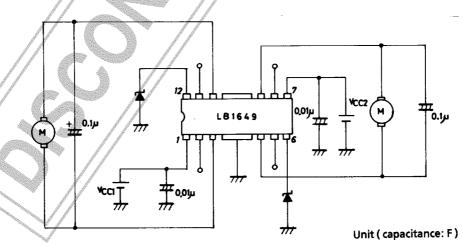
IN1	IN2	OUT1	OUT2	IN3	IN4	OUT3	OUT4
0	0	L	L	0	0	L/	/L
1	0	Н	L	1	0	H	L
0	1	L	Н	0	1	/L/	Н
1	1	L	L	1	1	L	L

Note : A capacitor of $0.01\mu F$ or greater must be connected across $V_{CC}1,2$ and GND.

	INPUT			OUT	PUT	Z Z	MC	DE
IN1	IN2, 3	IN4	OUT1	OUT2	OUT3	OUT4	M1//	M2
0	0	0	L	/ //	L	٦	Brake	Brake
1	0	0	H /	/ L	¹ L	L	Forward/reverse	Brake
0	1	1	J	″ н ⁴	Ļ	L	Reverse/forward	Brake
1	1	0	/ L/	L-	Ŧ	L	Brake	Forward/reverse
0	0	1	L	L	L	H	Brake	Reverse/forward
1	1	1//	L	L	Ĺ	L	Brake	Brake

The remaining input states 1, 0, 1 and 0, 1, 0 are not inhibinted.

Sample Application Circuit



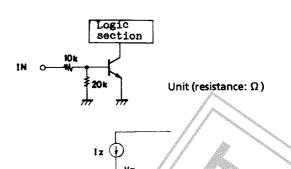
Input Circuit

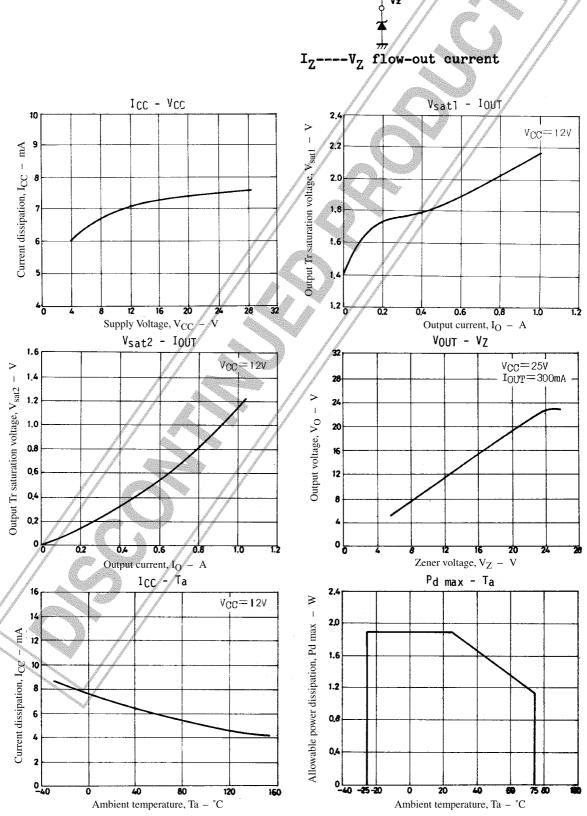
The input circuit is shown right

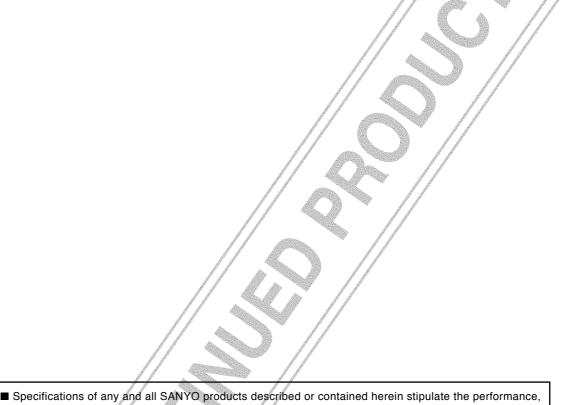
 $V_Z \, pin$

Zener voltage	VZ pin voltage vaule
≥5.6V	small
<5.6V	large*

^{*} Susceptible to V_Z pin flow-out current change.







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