

# **Product Specification**

# XBLW GT4428

Dual 2A Ultra-high-speed Power Switching Driver











### **Descriptions**

XBLW GT4428 is a power switching driver. It has matched rise and fall times when charging and discharging the gate. This device is highly latch-up resistant under any conditions within their power and voltage ratings. It is not subject to damage when up to 5V of noise spiking (of either polarity) occurs on the ground pin. The GT4428 can accept, without damage or logic upset, up to 500 mA of reverse current (of either polarity) being forced back into their outputs. All terminals are fully protected against Electrostatic Discharge (ESD) up to 2.0 kV.



#### **Feature**

- Latch-Up Protected: Withstands 0.5A Reverse Current
- Input Logic Protection Down To -10V
- Low Output Impedance
- Single Chip Integrated Two-Way Drive
- Output Peak Current: 2A
- Input Supply Voltage Operating Range: 4.5V~25V
- The Maximum Input Voltage up to 5V
- High Capacity Load Drive Capability: 1000 pF in 25ns
- Matched Rise And Fall Times
- Short Delay Times: 40ns
- Wide Temperature Range: -40°C~125°C
- Chip Turn-On/Turn-Off Delay Characteristics --T<sub>on</sub>/T<sub>off</sub> = 70ns/70ns
- Compliant With RoSH Standard, Adopting SOP-8 Package
- Output A out of phase with input A and Output B in phase with input B

### **Applications**

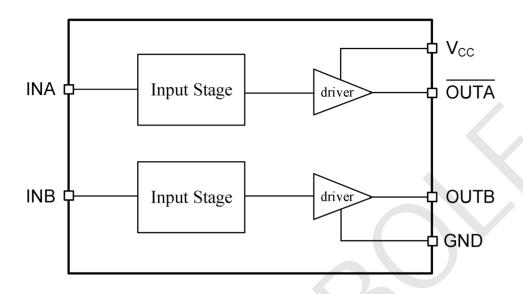
- Switch Mode Power Supplies & Switching Converters
- Line Drivers
- Pulse Transformer Drive
- Driving MOSFETs and IGBTs
- Motor Control
- Pulse Generator
- Power Switch
- DC-DC Converters
- Switching Amplifier Class D

### **Ordering Information**

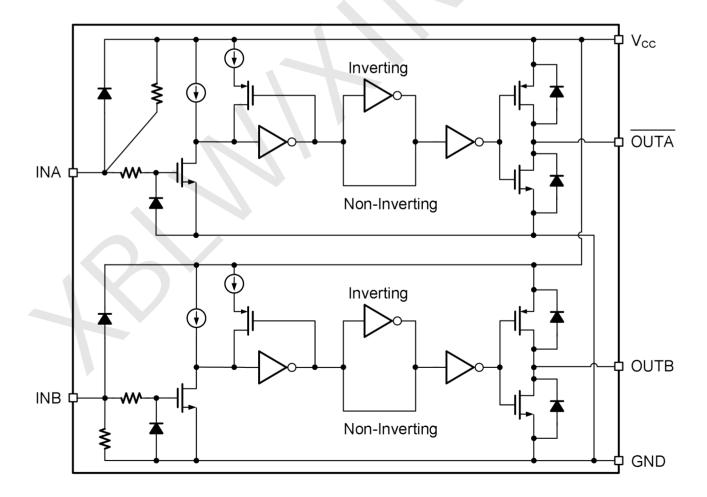
Product Model	Package Type	Marking	Packing	Packing Qty	Input/Output Phase
XBLW GT4428DTR	SOP-8	GT4428	Tape	3000Pcs/Reel	Output A out of phase with input A and Output B in phase with input B



# **Simplified Diagram**

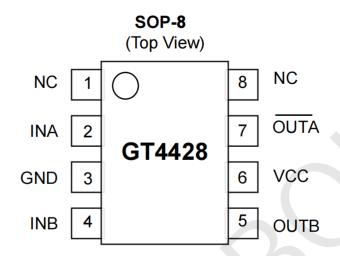


# **Function Diagram**





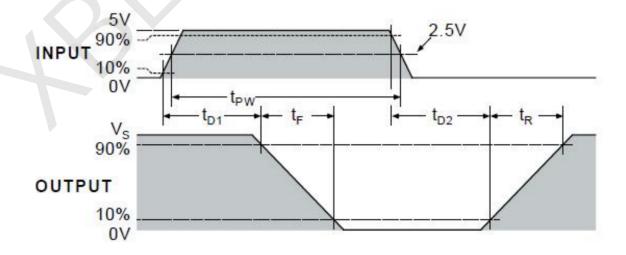
# **Pin Configurations**



# **Pin Description**

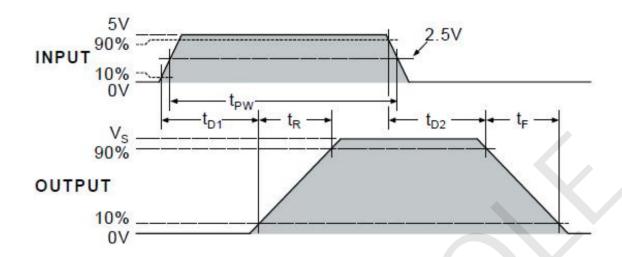
No.	Name	Function
1	NC	No Internal Connection
2	INA	Input A
3	GND	Ground
4	INB	Input B
5	OUTB	Output B
6	Vcc	Power Supply
7	OUTA	Output A
8	NC	No Internal Connection

# **Function Description**



Input/output (A-channel inversion) waveform diagram





Input/output (B channel in-phase) waveform diagram

### **Product Specifications**

#### **Limit Operating Range**

Exceeding the limit maximum rating may cause permanent damage to the device. The rated values of all voltage parameters are referenced to GND, and the current parameters are referenced to the positive input, and the ambient temperature is  $25^{\circ}$ C.

Symbol	Definition	Min.	Max.	Unit
Vcc	Power Supply	_	25	
V <sub>IN</sub>	Logical Input Voltage (INA/INB)	- 10	Vcc+0.3	V

#### **ESD Rating**

Symbol	Definition	Min.	Max.	Unit
	НВМ	_	2000	V
ESD	MM	_	500	V

#### **Rated Power**

Symbol	Definition	Min.	Max.	Unit
PD	SOIC Package Power (T <sub>A</sub> ≤70°C)	_	470	mVV

#### Thermal information

Symbol	Definition	Min.	Max.	Unit
TJ	Junction Temperature		+150	
Ts	Storage Temperature	-45	+150	°C



#### **Recommended Operating Range**

For proper operation, the device should be used under the following recommended conditions. The rated values of all voltage parameters are referenced to GND, and the current parameters are referenced to input positive current and the ambient temperature is 25°C.

Symbol	Definition	Min.	Max.	Unit
Vcc	Power Supply	4.5	20	V
Tc	Test Ambient Temperature	-40	125	°C

### **Electrical Characteristics**

Unless otherwise specified, T<sub>A</sub> =25 °C, 4.5 V ≤ Vcc ≤ 18 V.

Symbol	Definition	Min.	Тур.	Max.	Unit
V <sub>IH</sub>	Logic '1', High Input Voltage	2.4		_	V
VIL	Logic '0', Low Input Voltage			0.8	V
I <sub>IN</sub>	Input Current (0V≤V <sub>IN</sub> ≤Vcc)	<u> </u>	_	200	μA
V <sub>OH</sub>	High Output Voltage	Vcc-0.025			V
$V_{OL}$	Low Output Voltage	_	-	0.025	V
R <sub>OH</sub>	High Voltage, Output Resistance (Vcc= 18V, lo= 100mA)	_	4	8	Ω
RoL	Low Voltage, Output Resistance (Vcc= 18V, lo= 100mA)		2	4	Ω
I <sub>PK</sub>	Peak Output Current	_	2	_	Α
I <sub>REV</sub>	Latch-Up Protection Withstand Reverse Current (Duty Cycle ≤2%, t≤300us, Vcc= 18V)		>0.5		Α
$t_{R}$	Rise Time (Vcc= 18V, C <sub>LOAD</sub> = 100pF)	_	_	30	ns
t <sub>F</sub>	Fall Time (Vcc= 18V, C <sub>LOAD</sub> = 100pF)			30	ns
ton	Turn On Delay Time (Vcc= 18V, C <sub>LOAD</sub> = 100pF)			70	ns
t <sub>OFF</sub>	Turn Off Delay Time (Vcc= 18V, C <sub>LOAD</sub> = 100pF)			70	ns
I <sub>Q1</sub>	Power Supply Current (V <sub>INA</sub> = V <sub>INB</sub> = a Logic-High)	_	_	6	mA
I <sub>Q0</sub>	Supply Current (V <sub>INA</sub> = V <sub>INB</sub> = a Logic-Low)	_	_	1	mA



### **Chip Operating Logic**

The GT4428 signal input Pin (INA, INB) adopts the level trigger mode, that is, if the voltage value meets the logic requirements, the chip can work normally, as shown in the following table.

Input	Δnd	<b>Output</b>	Logic	Table
IIIPUL	Allu	Output	LOGIC	Iabic

INPUT		OU	TPUT
INA	INB	OUTA	OUTB
L	L	Н	Ĺ
Н	Н	L	Н
L	Н	Н	Н
Н	L	L	L
Note: H represents high level	L represents low level		

#### Signal input port

The GT4428 includes two independent signal input pins to receive control signals from the master controller without mutual interference. These two pins are designed with a high reliability. They can accept, without damage or logic upset, up to 500 mA of reverse current (of either polarity) being forced back into their outputs. At the same time, the input port has the ability to directly process -10V voltage, which can still ensure the safe operation of the chip under the influence of large noise wave,increasing the stability of chip.

It is not recommended to adjust the output waveform by adjusting the slope or delay of the input pin waveform during designation. If the rise and fall time of power needs to be adjusted, it is recommended to add an additional resistance between the output pin and the power pin. The GT4428 signal input pin has a Pull-up resistance for Vcc, so it is recommended to short this pin to Vcc when not in use.

#### **Output port**

The output A of GT4428 is out of phase with input A, and the output B is in phase with input B. It can be used to d rive P-type or N-type MOSFETs. Each output port can provide a peak pull-up or pull-down current of 2A, and its hi gh-speed and high current characteristics can be used to drive MOSFETs in high-frequency application designs.

# **Application Information**

The high-speed and high-current characteristics of GT4428 can be used in high-frequency power supplies and other power supplies. Typical applications include that the power of the PWM output stage of the main control IC is often not enough to drive the MOSFET at the power end, so a high-power driver stage chip is required between the main control IC and the MOSFET to drive the Voltage gate of the MOSFET to ensure that the MOSFET works in a stable state.

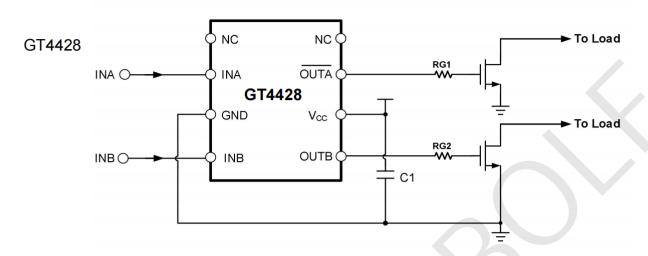
#### **Application Recommendations**

In the high-frequency and high-power application environment, it is particularly important to ensure the stable operation of the chip. Therefore, the following suggestions are put forward for the application of GT4428:

- 1) During the switching process, GT442 8will output a switching current with a peak value of 2A, and with the increase of frequency, the requirements for Vcc stability are more stringent. Therefore, during design, an electrolytic capacitor with a large capacitance can be selected to stabilize the Vcc voltage, and in order to cope with the high-frequency characteristics, a low ESR/ESL capacitor (ceramic capacitor or chip capacitor) can be used in parallel. Physically, the capacitor should be as close as possible to both ends of Vcc and GND.
- 2) The output pin is also a part of the power circuit. In order to ensure the flatness of the output waveform, the output pin should be designed with the power pin and the gates of the MOSFETs are placed as close together as possible. In addition, additional resistance can be designed outside of OUT to make the operating waveform more stable.



#### **Typical Application Circuit**



Typical application circuit diagram

#### **PCB Layout Guide**

In order to achieve the best performance of the high speed low side door driver. It is recommended to pay attention to the following points:

- 1) A low ESR/ESL capacitor must be tightly connected to the IC between the Vcc and GND pins to support the high peak current drawn from the VDD during MOSFET ON.
- 2) Grounding considerations:
- The primary goal of designing the ground connection is to limit the loop of MOSFET gate charge and discharge to the smallest possible area. In this way, the loop inductance is reduced, which can effectively avoid noise problems on the MOSFET gate. At the same time, the gate driver chip should be as close as possible to the MOSFET.
- Star point grounding is a good way to reduce noise coupling from one current loop to another. The ground single point of the driver is connected to other circuit nodes such as the source of the power MOSFET and the ground of the PWM controller. The connection path must be as short as possible to reduce inductance and as wide as possible to reduce resistance.
- Adopting a ground plane to shield noise. Since the fast rise and fall time of OUT may destroy the input signal during the transition, the input signal can be guaranteed not to be disturbed by shielding the noise through the ground plane. The ground plane must not be a conduction path for any current loop, and the ground plane must be connected to the star point to establish ground potential. In addition to shielding against noise, the ground plane also helps to dissipate heat.
- 3) In a noisy environment, to prevent output failure caused by noise, an unused PIN can be connect to VDD or GND.
- 4) Separate power circuit and signal circuit, such as output and input signals.



# **Package Information**

• SOP-8

	Dimensions In	Millimeters		Dimonoion	s In Inches
Size	Min(mm)	Max (mm)	Size	Min(in)	Max(in)
ymbol			Symbol .		
A	1. 350	1. 750	A	0. 053	0.069
A1	0. 100	0. 250	A1	0.004	0.010
A2	1. 350	1.550	A2	0. 053	0.061
b	0.330	0.510	b	0. 013	0. 020
c	0.170	0. 250	С	0.006	0. 010
D	4.700	5. 100	D	0. 185	0. 200
Е	3.800	4.000	Е	0.150	0. 157
E1	5. 800	6. 200	E1	0.228	0. 224
e	1. 2	70 (BSC)	е	0.	050 (BSC)
L	0.400	1. 270	L	0.016	0.050
θ	0°	8°	θ	0°	8°
EI		e			
C.A.					



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