

## 5V,15kV ESD-protected RS485 transceiver

### 1. Features

- ESD Protection for RS-485 I/O Pins
- 15kV—Human Body Model
- 15kV—IEC61000-4-2, Air-Gap Discharge
- 8kV—IEC61000-4-2, Contact Discharge
- 5V Supply Voltage Range
- Enhanced Slew-Rate Limiting Facilitates Error-Free Data Transmission
- 1uA Low-Current Shutdown Mode
- -7V to +12V Common-Mode Input Voltage Range
- Allows up to 256 Transceivers on the Bus
- Thermal Shutdown
- Current-Limiting for Driver Overload Protection
- Data transmission up to 2.5Mbps

## 2. Applications

- Telecommunications
- Low-Power RS-485 Transceivers
- Integrated Services Digital Networks
- Industrial-Control Local Area
   Networks
- Transceivers for EMI-Sensitive Applications
- Packet Switching
- Level Translators

## 3. Description

The MAX485EESA+T(ES) are 5V powered, ±15kV ESD-protected, slew-rate-limited differential transceivers which provide full RS485 compatibility. Each part contains one driver and one receiver, which is designed for data transmission with extended common mode range (-7V to 12V). The MAX485EESA+T(ES) features slew-rate-limited driver which minimizes EMI and reduces reflections resulted from improperly terminated cables.

The MAX485EESA+T(ES) also feature enhanced electrostatic discharge (ESD) protection. All of the transmitter outputs and receiver inputs are protected to ±15kV using IEC61000-4-2 Air-Gap Discharge, ±15kV using the Human Body Model and ±8kV using IEC61000-4-2 Contact Discharge.

Drivers are short circuit current limited. When the driver outputs are placed into a high-impedance state by thermal shutdown circuitry, drivers are protected against excessive power dissipation. And the fail-safe feature of the receiver input guarantees a logic-high output if both inputs are open, shorted or idle.

Both parts have power up/down mode, the glitch-free driver outputs permit live insertion or removal of the transceiver into/from the data bus. The CMOS design offers significant power savings without sacrificing ruggedness against overload or ESD damage. The typical quiescent current is only 300uA during operation and 1uA in shutdown mode. The MAX485EESA+T(ES) are intended for half-duplex communication and are available in SOP8 and DIP8 packages.



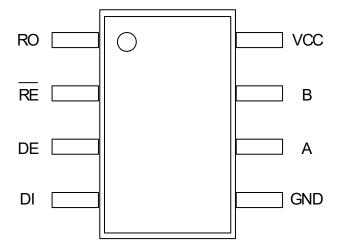
## 4. Device Information

Part Number	Operating Temperature	Mark Code	Package Type	Shipping Qty
MAX485EESA+T(ES)	-40°C to +85°C	MAX485EESA+T(ES)	SOP8	3000pcs/13 Inch Tape & Reel
MAX485EEPA+T(ES)	-40°C to +85°C	MAX485EEPA+T(ES)	DIP8	50pcs/Tube

## 5. Selection Guide

Part Number	Guarantee d Date Rate(Mbps	Low- Power Shutdow n	Slew- Rate Limite d	Driver/Reciev er Enable	Shutdown Current(u A)	Transceiver s On Bus	±15KV ESD Protectio
MAX485EESA+T(E S)	2.5	Yes	Yes	Yes	1	256	Yes

# 6. Pin Configuration



# 7. Absolute Maximum Ratings

Symbol	Parameters	Value	Unit
VCC	Supply Voltage	+7	V
	Control Input Voltage (/RE, DE)	-0.3V to (VCC + 0.3V)	٧



	Driver Input Voltage (DI)	-0.3V to (VCC + 0.3V)	V	
	Driver Output Voltage (A, B)	-7 to +12	V	
	Receiver Input Voltage (A, B)	-7 to +12	V	
	Receiver Output Voltage (RO)	-0.3V to (VCC + 0.3V)	V	
PD	Continuous Power Dissipation at TA = DIP8		727	mW
PD	70°C	471	IIIVV	
TA	Ambient Temperature		-40 to +85	°C
TSTG	Storage Temperature Range	-65 to 160	°C	
TL	Lead Temperature for Soldering 10 sec	+300	°C	

## 8. Electrical Characteristics

(VCC = 5V, TA = TMIN to TMAX, unless otherwise noted. Typical values are at TA = +25°C.)

Parameter	Symbols	Test Co	ondition	Min	Тур	Max	Unit					
	SUPPLY CURRENT											
Supply Current	Icc	No load, DI = GND or	DE=VCC, /RE=0V or VCC	0.15		1	mA					
		VCC	DE=0V, /RE=0V	0.15		1						
Supply Current in Shutdown Mode	Ishdn		VCC, DI=VCC			1	uA					
LOGIC												
Input High Voltage	V <sub>IH</sub>	DE, D	I, /RE	2.0			V					
Input Low Voltage	VIL	DE, D	I, /RE			0.8	V					
Logic Input Current	l <sub>IN1</sub>	DE, D	I, /RE			1	uA					
		DRI	VER									
Differential Driver Output	Vod	No Load RL=54 RL=60	VCC=5V VCC=5V VCC=5V	1.2 1.3		5	V					
Change in Magnitude of Driver Differential Output Voltage for Complementary Output States (Note 1)	ΔVod	RL=54 $\Omega$ or 100 $\Omega$				0.2	V					



		1		1		T	1
Driver Common-Mode	Voc	RL=54Ω	or 100 Ω			3	V
Output Voltage							
Change in Magnitude of Common-Mode Output Voltage (Note 1)	ΔVoc	RL=54Ω	or 100 Ω			0.2	V
Driver Short-Circuit		VOLIT	- = -7V			-250	
Output Current	Iosd		= 12V			+250	mA
			EIVER				
Receiver Differential Threshold Voltage	V <sub>TH</sub>	-7V≤VC	CM≪12V	-0.2	-0.05	0.2	V
Receiver Input Hysteresis	Δ <b>V</b> <sub>TH</sub>	VCN	1=0V		25		mV
Receiver Input Resistance	R <sub>IN</sub>	-7V≤VC	CM≤12V	96			kΩ
		DE=0V,	VIN = 12V			1	
Input Current (A, B)	l <sub>IN2</sub>	VCC=0V or 5V	VIN = -7V			-0.8	mA
Receiver Output High Voltage	V <sub>OH</sub>	IOUT=-1.5mA	, VID=200mV	Vcc-1.5			٧
Receiver Output Low Voltage	VoL	IOUT=2.5mA	, VID=200mV			0.4	V
Three-State (High Impedance) Output Current at Receiver	l <sub>ozr</sub>	0V≶VOU	JT≪VCC			1	uA
Receiver Short-Circuit Output Current	Iosr	0V≪VRO≪VCC		±20		±60	mA
		ESD PRO	TECTION				
		Human B	ody Model		±15		
ESD Protection for A, B			0-4-2 Air narge		±15		kV
		IEC61000-	4-2 Contact harge		±8		
		_ = :55:	1		l		

# **Driver Switching Characteristics**

Parameter	Symbol	Test Conditions	Min	Тур	Max	Unit
Maximum Data Rate	fMAX			2500		kbps
Driver Differential Output Delay	too	RL=60Ω	20	50	100	ns



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Driver Differential Output Transition Time	tтр	RL=60Ω	20	50	100	ns	
Driver Propagation Delay, Low-to- High Level	tplH	RL=27Ω	25	55	100	ns	
Driver Propagation Delay, High- to-Low Level	tPHL	RL=27Ω	25	55	100	ns	
tplн – tpнl   Driver Propagation Delay Skew (Note 2)	tpds	RL=27Ω		2	10	ns	
Driver-Output Enable/Disable Times							
Driver Output Enable Time to Low Level	tpzL	RL=110Ω		60	100	ns	
Driver Output Enable Time to High Level	tpzh	RL=110Ω		60	100	ns	
Driver Output Disable Time from High Level	tphz	RL=110Ω		60	100	ns	
Driver Output Disable Time from Low Level	tPLZ	RL=110Ω		60	100	ns	
Driver Output Enable Time from Shutdown to Low Level	tpsl	RL=110Ω		500	800	ns	
Driver Output Enable Time from Shutdown to High Level	tрsн	RL=110Ω		500	800	ns	

# Receiver Switching Characteristics

 $(VCC = 5V, TA = +25^{\circ}C.)$ 

Parameter	Symbol	Test Conditions	Min	Тур	Max	Unit
Time to Shutdown	tshon	Note 3	50	200	600	ns
Receiver Propagation Delay, Low-to-High		VID=0 to				
Level	trplh	3.0V,		100	200	ns
Level		C <sub>L</sub> =15pF				
Receiver Propagation Delay, High-to-Low		VID=0 to				
Level	trphl	3.0V,		100	200	ns
Level		C <sub>L</sub> =15pF				
LtDDLU tDDUL   Desciver Propagation		VID=0 to				
tRPLH – tRPHL   Receiver Propagation Delay Skew	trpds	3.0V,			30	ns
Delay Skew		CL=15pF				
Receiver Output Enable Time to Low Level	tprzl	CL=15pF		20	100	ns



Receiver Output Enable Time to High Level	tprzh	CL=15pF	20	100	ns
Receiver Output Disable Time from High Level	tprhz	CL=15pF	30	200	ns
Receiver Output Disable Time from Low Level	tprlz	CL=15pF	30	200	ns
Receiver Output Enable Time from Shutdown to Low Level	tprsl	CL=15pF	20	100	ns
Receiver Output Enable Time from Shutdown to High Level	tprsh	CL=15pF	20	100	ns

Note 1:  $\Delta V_{OD}$  and  $\Delta V_{OC}$  are the changes in  $V_{OD}$  and  $V_{OC}$ , respectively, when the DI input changes state.

Note 2: Measured on | tplh (A)- tphl (A)| and | tplh (B)- tphl (B)|.

Note 3: The transceivers are put into shutdown by bringing /RE high and DE low. If the inputs are in this state for less than 80ns, the parts are guaranteed not to enter shutdown. If the inputs are in this state for at least 300ns, the parts are guaranteed to have entered shutdown. See Low-Power Shutdown Mode section.

# 9. Typical Operating Characteristics

(VCC = 5V, TA=+25°C, unless otherwise noted.)

## **Pin Description**

Pin Number	Symbol	Function
1	RO	Receiver Output. If A>B by -50mV, RO will be high; if A <b 200mv,="" be="" by="" low.<="" ro="" td="" will=""></b>
2	RE	Receiver Output Enable. RO is enabled when $\overline{RE}$ is low; RO is high impedance when RE is high. Drive $\overline{RE}$ high and DE low to enter low-power shutdown mode.
3	DE	Driver Output Enable. The driver outputs are enabled by bringing DE high. They are high impedance when DE is low. If $\overline{RE}$ is high and DE is low, the device will enter a low-power shutdown mode. If the driver outputs are enabled, the parts function as line drivers. While they are high impedance, they function as line receivers if $\overline{RE}$ is low.
4	DI	Driver Input. A low on DI forces output A low and output B high. Similarly, a high on DI forces output A high and output B low.
5	GND	Ground
6	Α	Non-inverting Receiver Input and Non-inverting Driver Output
7	В	Inverting Receiver Input and Inverting Driver Output.

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8	Vcc	Positive Supply: 5V

## **RS-485 Communication Function Table**

## Table1. Transmitting

INPUTS			OUTPUTS		
RE	DE	DI	В	A	MODE
Х	1	1	0	1	Normal
X	1	0	1	0	Normal
0	0	X	High-Z	High-Z	Normal
1	0	Х	High-Z	High-Z	Shutdown

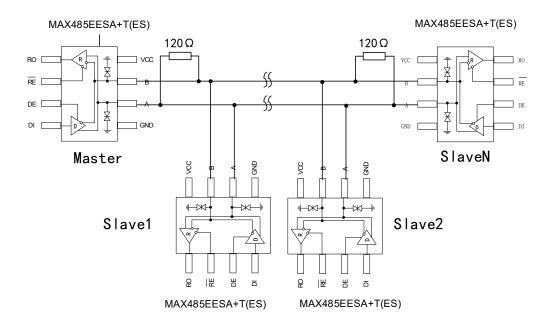
## Table2. Receiving

INPUTS			OUTPUTS	MODE	
RE	DE	A, B	RO	MODE	
0	Х	>-50mV	1	Normal	
0	X	<-200mV	0	Normal	
0	X	Inputs Open	1	Normal	
1	0	X	High-Z	Shutdown	

X=Don't care; High-Z=High impedance

## 10. Tipical Operating Circuit





## 11. Detail Description

The MAX485EESA+T(ES) are low-power transceivers for RS-485 communications. MAX485EESA+T(ES) realizes error-free data transmission up to 2.5Mbps. The MAX485EESA+T(ES) are half-duplex. Driver Enable (DE) and Receiver Enable (/RE) pins are included on the MAX485EESA+T(ES). When disabled, the driver and receiver outputs are high impedance.

### Fail-Safe

The MAX485EESA+T(ES) guarantees a logic-high receiver output when the receiver inputs are shorted or open, or when they are connected to a terminated transmission line with all drivers disabled. This is done by setting the receiver threshold between -50mV and -200mV. If the differential receiver input voltage (A-B) is greater than or equal to -50mV, RO is logic high. If A-B is less than or equal to -200mV, RO is logic low. In the case of a terminated bus with all transmitters disabled, the receiver's differential input voltage is pulled to 0V by the termination. With the receiver thresholds of the MAX485EESA+T(ES), this results in a logic high with a 50mV minimum noise margin. Unlike previous fail-safe devices, the -50mV to -200mV threshold complies with the ±200mV EIA/TIA-485 standard.

#### ±15kV ESD Protection

As with all ElecSuper devices, ESD-protection structures are incorporated on all pins to protect against electrostatic discharges encountered during handling and assembly. The driver outputs and receiver inputs of the MAX485EESA+T(ES) have extra protection against static electricity. ElecSuper's engineers have developed state-of-the-art structures to protect these pins against ESD of ±15kV without damage. The ESD-protected pins are tested with reference to the ground pin in a power-down condition. They are tested to ±15kV using the Human Body Model.

#### **Applications Information**

#### 256 Transceivers on the Bus

The standard RS-485 receiver input impedance is  $12k\Omega$  (one unit load), and the standard driver can drive up to 32 unit loads. The ElecSuper family of transceivers have a 1/8 unit load receiver input impedance ( $96k\Omega$ ), allowing up to 256 transceivers to be connected in parallel on one communication line. Any combination of these devices and/or other RS-485 transceivers with a total of 32 unit loads or less can be connected to the line.

#### **Reduced EMI and Reflections**

The MAX485EESA+T(ES) are slew-rate-limited, minimizing EMI and reducing reflections caused by improperly terminated cables. In general, a transmitter's rise time relates directly to the length of an unterminated stub, which can be driven with only minor waveform reflections. The following equation expresses this relationship conservatively:

Length=tRISE/(10×1.5ns/ft)

Where tRISE is the transmitter's rise time. A system can work well with longer unterminated stubs, even with severe reflections, if the waveform settles out before the UART samples them.

#### **Low-Power Shutdown Mode**

Low-power shutdown mode is initiated by bringing both /RE high and DE low. In shutdown, the device typically draws only 1uA of supply current. /RE and DE may be driven simultaneously; the parts are guaranteed not to enter shutdown if /RE is high and DE is low for less than 50ns. If the inputs are in this state for at least 600ns, the parts are guaranteed to enter shutdown. Enable times tPZH and tPZL in the Switching Characteristics tables assume the part was not in a low-power shutdown state. Enable times tPSH and tPSL assume the parts were shut down. It takes drivers and receivers longer to become enabled from low-power shutdown mode (tPSH, tPSL) than from driver/receiver-disable mode (tPZH, tPZL).

### **Driver Output Protection**

Two mechanisms prevent excessive output current and power dissipation caused by faults or bus contention. First, a foldback current limit on the output stage, provides immediate protection against short circuits over the whole common-mode voltage range. Second, a thermal shutdown circuit, forces the driver outputs into a high-impedance state if the die temperature becomes excessive.

#### **Propagation Delay**

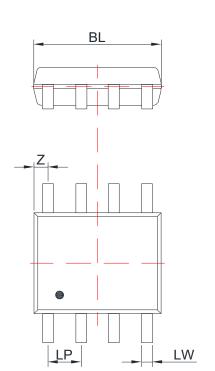
Skew time is simply the difference between the low-to-high and high-to-low propagation delay. Small driver/receiver skew times help maintain a symmetrical mark-space ratio (50% duty cycle). The driver skew times 12ns for the MAX485EESA+T(ES).

### **Typical Applications**

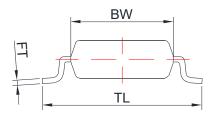


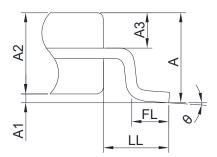
The MAX485EESA+T(ES) transceivers are designed for bidirectional data communications on multipoint bus transmission lines. To minimize reflections, the line should be terminated at both ends in its characteristic impedance, and stub lengths of the main line should be kept as short as possible. The partially slew-rate-limited MAX485EESA+T(ES) are more tolerant of imperfect termination.

## 12. Package Information







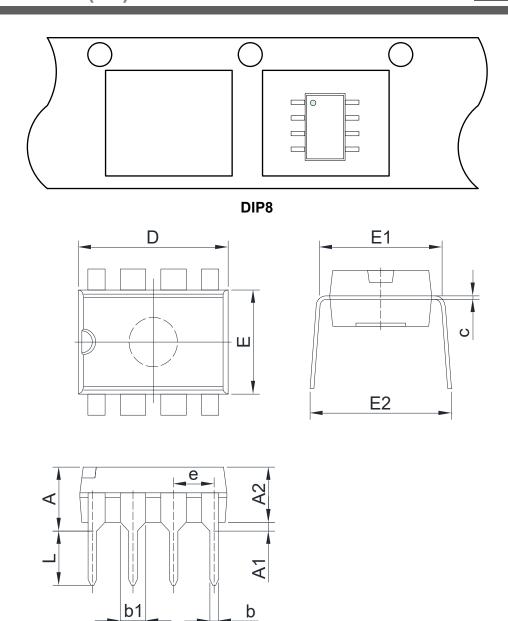


Units:milimeter

Symbol	Dimensions		Cymahal	Dimensions	
	Min.	Max.	Symbol	Min.	Max.
А	1.35	1.75	FL-L	0.40	1.27
A1	0.10	0.25	LP-e	1.27BSC	
A2	1.25	1.65	LL 无	0.90	1.10
<b>A3</b> 无	0.600	0.65	LW-b	0.30	0.51
BL-D	4.70	5.10	TL-E1	5.80	6.20
BW-E	3.80	4.00	Z无	0.50	0.55
FT-C	0.15	0.25	θ	0°	8°

## **Tape and Reel Orientation**





Symbol	Millimeters		Carrala a 1	Millimeters	
	Min	Max	Symbol	Min	Max
A	3.71	4.80	D	9.00	9.50
A1	0.38	-	Е	6.20	6.60
A2	3.20	3.60	E1	7.32	7.92
b	0.38	0.57	E2	8.40	9.05
b1	1.52 BSC		e	2.54 TYP	
c	0.20	0.36	L	3.00	3.60



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