# HAF SERIES

# Honeywell Zephyr™ Digital Airflow Sensors

High Accuracy: 10 SLPM, 15 SLPM, 20 SLPM, 50 SLPM, 100 SLPM, 200 SLPM, 300 SLPM

#### **DESCRIPTION**

Honeywell Zephyr™ HAF Series sensors provide a digital interface for reading airflow over specified full-scale flow and compensated temperature ranges. The thermally isolated heater and temperature sensing elements help these sensors provide a fast response to air or gas flow. Zephyr sensors are designed to measure mass flow of air and other non-corrosive gases. Standard flow ranges are 10 SLPM, 15 SLPM, 20 SLPM, 50 SLPM, 100 SLPM, 200 SLPM and 300 SLPM, with custom flow ranges available. The sensors are fully calibrated and temperature compensated with an onboard Application Specific Integrated Circuit (ASIC). The HAF Series >10 SLPM is compensated over the calibrated temperature range of 0°C to  $50^{\circ}$ C [ $32^{\circ}$ F to  $122^{\circ}$ F]. The stateof-the-art ASIC-based compensation provides digital (I2C) outputs with a response time of 1 ms. These sensors operate on the heat transfer principle to measure mass airflow. They consist of a microbridge Microelectronic and Microelectromechanical System (MEMS) with temperature-sensitive resistors deposited with thin films of platinum and silicon nitride. The MEMS sensing die is located in a precise and carefully designed airflow channel to provide repeatable response to flow. Zephyr sensors provide the customer with enhanced reliability, high accuracy, repeatable measurements and the ability to customize sensor options to meet many specific application needs. The combination of rugged housings with a stable substrate makes these products extremely robust. They are designed and manufactured according to ISO 9001 standards.

#### **FEATURES**

- Fast response time (1 ms) allows the customer's application to respond quickly to a change in airflow, important in critical medical (e.g., anesthesia) and industrial (e.g., fume hood) applications.
- High stability reduces errors due to thermal effects and null shift, providing accurate readings over time and often eliminating the need for system calibration after PCB mount and periodically over time.
- High sensitivity at very low flows provides a fast response time at the onset or cessation of flow.
- High 12-bit resolution increases the ability to sense small airflow changes, allowing customers to more precisely control their application.
- Wide airflow range: The industry's broadest airflow range measures mass flow with standard flow ranges of 0 to 10, 0 to 15, 0 to 20, 0 to 50, 0 to 100, 0 to 200 and 0 SLPM to 300 SLPM, or custom flow ranges, increasing the options to integrate the sensor into the application.
- Choice of port styles: Manifold mount, 22 mm OD tapered male fitting, and G 3/8 female threaded fitting provide flexibility to choose the pneumatic connection that is best for the customer's application.
- Linear output provides a more intuitive sensor signal than the raw output of basic airflow sensors, which can help reduce production costs, design, and implementation time.
- Wide supply voltage range (3 Vdc to 10 Vdc) provides a flexible regulated power circuit which allows the designer the flexibility to choose the supply voltage that works best in the system.
- ASIC-based I2C digital output simplifies integration to microprocessors or microcontrollers, reducing PCB complexity and component count.
- RoHS-compliant materials Meet Directive 2002/95/EC..
- CE & UKCA certified







#### **POTENTIAL APPLICATIONS**

- Medical: Anesthesia delivery machines, ventilators, ventricular assist devices (heart pumps), spirometers, laparoscopy
- Industrial: Analytic instrumentation (spectrometry, chromatrography), air-to-fuel ratio, fuel cells, fume hoods, gas leak detection, process control gas monitoring, vacuum pump monitoring



PORTFOLIO
The Honeywell Zephyr Digital

Airflow Sensors join an extensive line of airflow sensors for potential use in medical, industrial, and consumer applications.

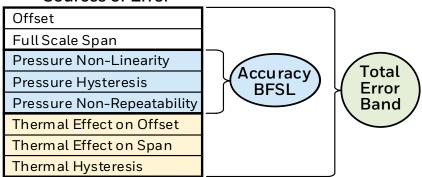


HAF SERIES High Accuracy: 10, 15, 20, 50, 100, 200, 300 SLPM

#### FIGURE 1. TOTAL ERROR BAND VS. ACCURACY

Other airflow sensor manufacturers only report on accuracy, while Honeywell reports Total Error Band.

#### Sources of Error



#### **HIGH ACCURACY**

Ideal for use in demanding applications that require high accuracy.

- -0%FS to 14.3%FS = 0.5%FS
- -14.3%FS to 100%FS = 3.5%reading

#### **TOTAL ERROR BAND (TEB)\***

Honeywell specifies TEB, the most comprehensive, clear, and meaningful measurement that provides the sensor's true accuracy (see Figure 1). TEB allows for precise airflow measurement, often ideal for demanding applications with high accuracy requirements for precise airflow measurement.

- 10, 15, 20, 50, 100, 200 SLPM:
  - -0%FS to 12.5%FS = 0.5%FS
  - -12.5%FS to 100%FS = 4.0%reading
- 300 SLPM only:
  - -0%FS to 12.5%FS = 0.5%FS
  - -12.5%FS to 66.7%FS = 4.0%reading
  - -66.7%FS to 100%FS = 7.0%reading

TABLE 1. ABSOLUTE MAXIMUM RATINGS'										
CHARACTERISTIC	PARAMETER									
Supply voltage	-0.3 Vdc to 11.0 Vdc									
Voltage on digital I/O output pins	-0.3 Vdc to 3.0 Vdc <sup>2</sup>									
Storage temperature range	-40°C to 100°C [-40°F to 212°F]									
Maximum flow change	10,000 SLPM/s									
Maximum common mode pressure	4 bar   60 psi at 25°C [77°F]									
Maximum flow	350 SLPM									

<sup>&</sup>lt;sup>1</sup>Absolute maximum ratings are the extreme limits that the device will withstand without damage to the device. However, the electrical and mechanical characteristics are not guaranteed as the maximum limits (above recommended operating conditions) are approached, nor will the device necessarily operate at absolute maximum ratings.

<sup>2</sup>Digital I/O pins are diode protected at this voltage up to 2 mA. Digital bus voltage may exceed this value if the maximum digital bus current is limited to 2 mA or less. The maximum bus current is generally determined by the bus pull-up resistors

## **CAUTION**

#### **IMPROPER USE**

Do not use these products to sense liquid flow.

Failure to comply with these instructions may result in product damage.

## **CAUTION**

#### **PRODUCT DAMAGE**

Do not dissamble these products.

Failure to comply with these instructions may result in product damage.

HAF SERIES High Accuracy: 10, 15, 20, 50, 100, 200, 300 SLPM

CHARACTERISTIC	PARAMETER
Supply voltage	3 Vdc to 10 Vdc
Supply current	20 mA max.
Power: 3 Vdc 10 Vdc	60 mW max. 200 mW max.
Calibrated temperature range <sup>1</sup>	0°C to 50°C [32°F to 122°F]
Operating temperature range	-20°C to 70°C [-4°F to 158°F]
Full scale (FS) flow <sup>2</sup>	10, 15, 20, 50, 100, 200, 300 SLPM
Calilbrated flow range	0 to 10, 0 to 15, 0 to 20, 0 to 50, 0 to 100, 0 to 200, 0 SLPM to 300 SLPM
Calibration gas	clean, dry air
Accuracy <sup>3</sup> 0%FS to 14.3%FS 14.3%FS to 100%FS	0.5%FS 3.5%reading
Total Error Band: <sup>4</sup> 10, 15, 20, 50, 100, 200 SLPM: 0%FS to 12.5%FS 12.5%FS to 100%FS 300 SLPM only: 0%FS to 12.5%FS 12.5%FS to 66.7%FS 66.7%FS to 100%FS	0.5%FS 4.0%reading 0.5%FS 4.0%reading 7.0%reading
Null accuracy <sup>5</sup>	±0.5%FS
Flow response time <sup>6</sup>	1 ms
Narm up time <sup>7</sup>	35 ms
Resolution: 10 SLPM 15 SLPM 20 SLPM 50 SLPM 100 SLPM 200 SLPM 300 SLPM	0.002 SLPM 0.003 SLPM 0.003 SLPM 0.008 SLPM 0.015 SLPM 0.029 SLPM 0.043 SLPM
Proof pressure	10.3 bar   150 psig
Burst pressure	13.7 bar   200 psig
Bus standards <sup>8</sup>	I <sup>2</sup> C fast mode (up to 400 kHz)
Reverse polarity protection	no

<sup>&</sup>lt;sup>1</sup>Custom and extended temperature compensated ranges are possible. Contact Honeywell for details.

<sup>&</sup>lt;sup>2</sup> Honeywell standard for mass flow rate units is SLPM, which has reference conditions of 0°C and 1 atm. Custom units are given as LPM with listed reference conditions at the first mention.

<sup>&</sup>lt;sup>3</sup>Accuracy is the maximum deviation in output from nominal over the entire calibrated flow range at 25°C. Errors include Offset, Full Scale Span, Linearity, Flow Hysteresis, and Repeatability.

 $<sup>^4</sup>$ Total Error Band (TEB) is the maximum deviation in output from nominal over the entire calibrated flow range and temperature range. Total Error Band includes all Accuracy errors, as well as all temperature effects over the compensated temperature range, including Temperature Offset, Temperature Span and Thermal Hysteresis.

<sup>&</sup>lt;sup>5</sup> Null Accuracy is the maximum deviation in output from nominal at null flow over the entire calibrated temperature range.

<sup>6</sup> Response time: time to electrically respond to any mass flow change at the microbridge airflow transducer (response time of the transducer may be affected by the pneumatic interface).

<sup>&</sup>lt;sup>7</sup>Warm-up time: time to the first valid flow measurement after power is applied.

<sup>&</sup>lt;sup>8</sup> Refer to the Technical Note "I<sup>2</sup>C Communications with Honeywell Digital Airflow Sensors" for I<sup>2</sup>C protocol information.

**HONEYWELL ZEPHYR™ DIGITAL AIRFLOW SENSORS HAF SERIES** High Accuracy: 10, 15, 20, 50, 100, 200, 300 SLPM

TABLE 3. ENVIRONMENTAL SPECIFICATIONS										
CHARACTERISTIC	PARAMETER									
Humidity	0% to 95% RH, non-condensing									
Shock	30 g, 6 ms									
Vibration	1,33 g at 10 Hz to 500 Hz									
ESD	ESD IEC6100-4-2 air discharge up to 8 kV, or direct contact discharge up to 4 kV									
Radiated immunity:	Level 3 from 80 MHz to 1000 MHz per IEC61000-4-3									
20,50,100,200,300 SLPM	1 m shielded cable with 3 cm exposed leads at connector									
10, 15 SLPM	1 m shielded cable with 3 cm exposed leads at connector and 280 Ohm at MHz ferrite bead									

TABLE 4. MATERIALS SPECIFICATIONS										
CHARACTERISTIC	PARAMETER									
Wetted materials	glass reinforced (GR) thermoplastic polymer, gold, silicon, silicon dioxide, silicon nitride, epoxy, PCB epoxy composite									
Housing	GR thermoplastic polymer									
Substrate	PCB									
Adhesives	ероху									
Electronic components	silicon, gold									
Compliance	RoHS, WEEE									

TABLE 5. RECOMMENDED MOUNTING AND IMPLEMENTATION										
CHARACTERISTIC	PARAMETER									
Mounting screw size	10-32									
Mounting screw torque	1,13 N m [20 in-lb]									
Electrical connection	6 pin SIP connector									
Pneumatic connection	manifold mount, 22 mm OD tapered male fitting, G 3/8 female threaded fitting									

HAF SERIES High Accuracy: 10, 15, 20, 50, 100, 200, 300 SLPM

#### FIGURE 2. NOMENCLATURE AND ORDER GUIDE<sup>1</sup>

For example, HAFUHM0020L4AXT defines a Honeywell Zephyr™ Airflow Sensor, unidirectional flow, long port, manifold mount, 20 SLPM, I<sup>2</sup>C output with custom 0x49 address, 10% to 90% transfer function, 3 Vdc to 10 Vdc supply voltage.

<b>HAF</b> Product Series	<b>U</b> Flow Direction	<b>HM</b> Port Style	<b>0020</b> Flow Range	<b>L</b> Unit	4 Output Format	<b>A</b> Transfer Function	X Reserved for Future Use	<b>T</b> Supply Voltage
HAF Series— High Accuracy Airflow Sensor –	<b>U</b> Unidirectional	HM Manifold mount	0010 10 0015 15	<b>L</b> SLPM	2 Digital I <sup>2</sup> C address: 0x29  3 Digital I <sup>2</sup> C address: 0x39	<b>A</b> 10% to 90% of input	X xxxxx	T 3 Vdc to 10 Vdc
		22 mm OD tapered male fitting per ISO 5356	0020 20 0050 50		4 Digital I <sup>2</sup> C address: 0x49  5 Digital I <sup>2</sup> C address: 0x59			
		G 3/8 female threaded fitting per ISO 1179	0100 100 0200 200 0300 300		6 Digital I <sup>2</sup> C address: 0x69  7 Digital I <sup>2</sup> C address: 0x79			

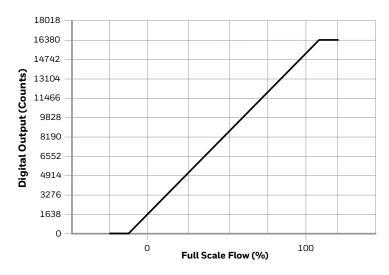
<sup>&</sup>lt;sup>1</sup>Apart from the general configuration required, other customer-specific requirements are also possible. Please contact Honeywell.

#### FIGURE 3. ALL AVAILABLE STANDARD CONFIGURATIONS



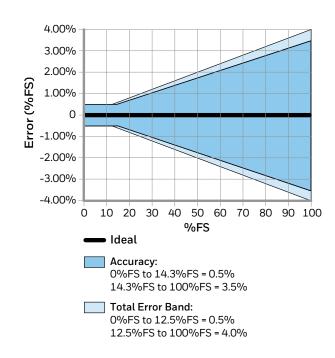
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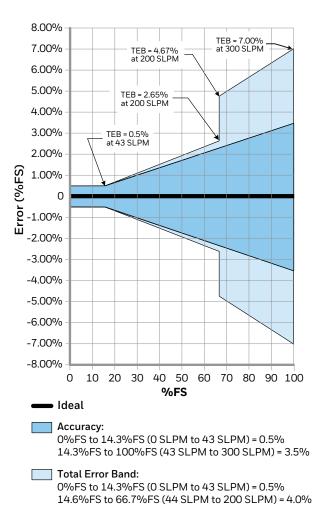
#### FIGURE 4. NOMINAL DIGITAL OUTPUT: 10, 15, 20, 50, 100, 200, 300 SLPM



### FIGURE 5. ACCURACY AND TOTAL ERROR BAND 10, 15, 20, 50, 100, 200 SLPM

# 300 SLPM only

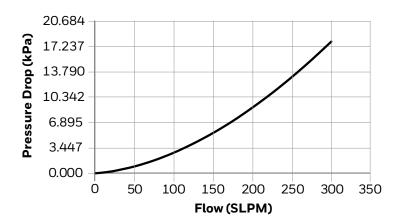




66.7%FS to 100%FS (200 SLPM to 300 SLPM) = 7.0%

HAF SERIES High Accuracy: 10, 15, 20, 50, 100, 200, 300 SLPM

#### FIGURE 6. FLOW VS PRESSURE DROP: 10, 15, 20, 50, 100, 200, 300 SLPM



Flow	Турі	Typical Pressure Drop										
(SLPM)	mbar	inH <sub>2</sub> O	kPa									
0	0.000	0.000	0.000									
1	0.103	0.042	0.010									
2	0.206	0.082	0.021									
4	0.396	0.159	0.040									
8	0.803	0.322	0.080									
10	1.027	0.412	0.103									
12	1.279	0.513	0.128									
14	1.549	0.621	0.155									
15	1.686	0.676	0.169									
16	1.820	0.730	0.182									
18	2.126	0.853	0.213									
20	2.444	0.980	0.244									
25	3.320	1.332	0.332									
50	9.314	3.736	0.931									
75	17.553	3.736	1.755									
100	27.979	3.736	2.798									
125	40.533	3.736	4.053									
150	54.881	22.017	5.488									
175	71.158	28.546	7.116									
200	89.506	35.907	8.951									
225	109.363	43.873	10.936									
250	131.037	52.568	13.104									
275	154.389	61.936	15.439									
300	179.235	71.904	17.924									

TABLE 6. IDEAL TRANSFER FUNCTION										
ITEM EQUATION										
Digital Output Code	16384 * [0.1 + 0.8 * (Flow Applied/Full Scale Flow)]									

Flow Applied Full Scale Flow \* [(Digital Output Code/16384) - 0.1]/0.8

#### **Digital Interface**

For additional details on the use of Zephyr with digital output see the Technical Note "12C Communications with Honeywell Digital Airflow Sensors".

The sensor uses the I<sup>2</sup>C standard for digital communication with a slave address specified in the Nomenclature and Order Guide in Figure 2. Following sensor power-up, each of the first two read sequences shown in Figure 7 will respond with 2 bytes of the unique 4-byte Serial Number. The first read after power-up will respond with the two most significant bytes of the Serial Number, while the second read will respond with the two least significant bytes of the Serial Number. For reliable performance, allow sensor to be powered for the sensor startup time before performing the first read, then allow a 10 ms command response time before performing the second read.

Slave pulls SDA low

Master pulls SDA low Master NACK Master allows SDA to float high

HAF SERIES High Accuracy: 10, 15, 20, 50, 100, 200, 300 SLPM

#### FIGURE 7. SENSOR I2C READ AND WRITE SEQUENCES

Slave ACK

Master ACK

#### I<sup>2</sup>C Read: Slave responds to Master with data

									I	Data	Byt	e 0 (	(Mos	t Si	gnifi	cant	t)		Data	а Ву	te 1	(Le	east	Sig	nifi	cant	:)		
SDA	S	A6 A5	A4	A3	A2	<b>A1</b>	ΑO	1	SA	D7	D6	D5	D4	D3	D2	D1	DO	МА	D7	D6	D5	5 D	4 D	3	D2	D1	DO N	ΛN	S
SCL		ПП		П	П	$\prod$	П		П	П	$\prod$	П				П	П	П	П	П			1	1	П	$\prod$	П	П	
	I <sup>2</sup> C Read: Master sends data to Slave																												
	Command Byte																												
SDA	S	A6 A5	Α4	A3	A2	A1	ΑO	1	SA	D7	D6	D5	D4	D3	D2	D1	DO	SA	S										
SCL					П	П	П	П	П	П		П		П				П											
	Bit	Nar	ne		1	Des	scri	ptic	on																				
	S	Star	t cond	ditio	n	Mas	ster	oull	s SD	A fro	m h	nigh	to lo	ow w	vhile	SCI	L rer	mair	ns hi	igh									
	s	Stop	cond	ditio	n	Master allows SDA to float from low to high while SCL remains high																							
	Α6	Addı	ress b	oit		I <sup>2</sup> C Slave Address is the 7 Most Significant Bits for the first transmitted byte																							
	1	Read	d/writ	te bi	t	Rea	ead = 1, Write = 0																						
	D7	Data	bit			Rea	d = 1	L, W	rite =	0																			

After the power-up read sequence described above, the sensor will respond to each I<sup>2</sup>C read request with a 16-bit (2 byte) digital flow reading. Read requests taken faster than the Response Time (1 ms) are not guaranteed to return fresh data. The first two bits of each flow reading will be '00', while non-flow responses (such as error and status codes) will begin with '11'. There are several user commands available as shown in Table 8. Following an I<sup>2</sup>C write sequence of a user command, the sensor will respond to the next I<sup>2</sup>C read request with a 16-bit response. Possible responses to user commands can be seen in Table 9.

TABLE 8. USER COMMAND DESCRIPTIONS										
Command Byte (Hexadecimal)	Command Name	Command Description	Command Response Time (Max.)							
0x01	GetSerialNumber	Next two read requests will each return two bytes of the sensor's unique 4-byte Serial Number.	10 ms							
0x02	PowerOnReset	Force Power-On reset of sensor microcontroller.	20 ms							
0x03	Checksum	Calculates EEPROM Checksum and compares to production Checksum value. If the values match, the next read request will respond with 0xCCA5. Otherwise, the next read will respond with 0xCC90.	1 s							

TABLE 9. SENSOR RESPONSE DESCRIPTIONS									
Sensor Response (Hexadecimal)	Response Name	Response Description							
0xCCA5	POSACK	non-response command was executed successfully							
0xCC99	BadCommand	command byte was not recognized							
0xCC9A	BadParam	command sent with incorrect parameter bytes							
0xCC9B	Failure	command failed during execution							
0xCC90	BadChecksum	checksum did not match stored value							
OxCCBB	Busy	sensor is busy calculating the checksum value							

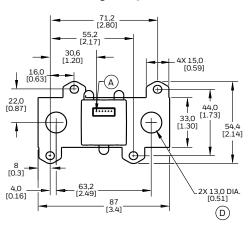
The maximum sink current on SCL or SDA is 2 mA. Therefore, if the pull-up resistors are biased by VDD, and if VDD reaches the maximum supply voltage of 6 V, then the pull-up resistors for SCL and SDA must be greater than 3.0 kOhm to limit the sink current to 2 mA. The typical value for SCL and SDA pull-up resistors is 4.7 kOhm (this value depends on the bus capacitance and the bus speed).

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## FIGURE 8. MOUNTING DIMENSIONS (FOR REFERENCE ONLY: MM [IN].)

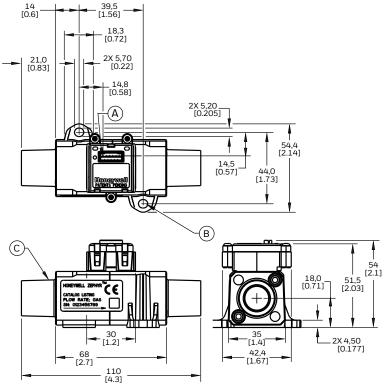
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#### **Mounting Footprint**

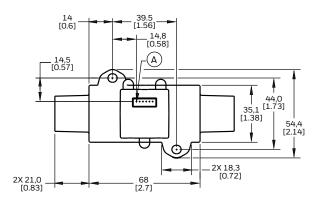


- (A) Pin 1.
- (B) 4X 10-32 pan head screws 1,13 N m [20 in-lb] torque.
- 2X Gland for O-Ring AS568-113, 13,94 mm ID x 2,62 mm [0.549 in ID x 0.103 in W. Two O-rings, AS568A-113 Durometer A65 to A80 Silicon or Viton, are required to seal sensor to manifold. O-rings are not included.
- (D) Flow channel.

Port Style: 22 mm OD Tapered Male Fitting per ISO 5356



#### **Mounting Footprint**

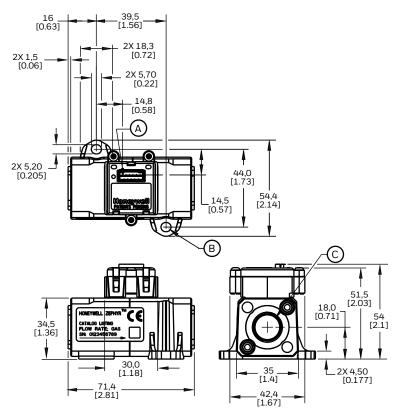


- (A) Pin 1.
- B 2X 10-32 pan head screws 1,13 N m [20 in-lb] torque.
  - 15 mm ID/22 mm OD tapered fitting per ISO 5356.

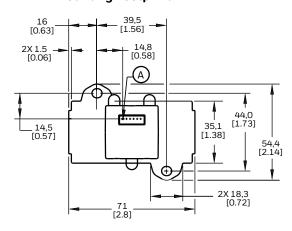
**HAF SERIES** High Accuracy: 10, 15, 20, 50, 100, 200, 300 SLPM

#### FIGURE 8. MOUNTING DIMENSIONS (FOR REFERENCE ONLY: MM [IN], CONTINUED.)

Port Style: G 3/8 Female Threaded Fitting per ISO 1179



#### **Mounting Footprint**



- (A) Pin 1.
- **(B)** 2X 10-32 pan head screws 1,13 N m [20 in-lb] torque.
- ISO 1179 G3/8, recommended torque is  $1,7 \pm 0,6$  N m [ $15 \pm 5$  in lb]. Electrical connector part number is JST (Japan Solderless Terminals) B6B-PH-K-S. Mating connector part numbers are JST PHR-6 (socket) and JST SPH-002T-P0.5L (crimp terminal).

TABLE 7. PINOUT (DIGITAL FUNCTION)													
Pin 1	Pin 2	Pin 3	Pin 4	Pin 5	Pin 6								
NC	SCL	VVDD	ground	SDA	NC								

#### **ADDITIONAL MATERIALS**

The following associated literature is available on the Honeywell web site at sps.honeywell.com/ast:

- Product line guide
- Product range guide
- Technical Information
  - I<sup>2</sup>C Communications with Honeywell Digital Airflow

#### Sensors

- Gas Media Compatibility and Correction Factors
- Application Specific Information

#### FOR MORE INFORMATION

Honeywell Advanced Sensing Technologies services its customers through a worldwide network of sales offices and distributors. For application assistance, current specifications, pricing or the nearest Authorized Distributor,

visit sps.honeywell.com/ast or call:

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#### WARRANTY/REMEDY

Honeywell warrants goods of its manufacture as being free of defective materials and faulty workmanship during the applicable warranty period. Honeywell's standard product warranty applies unless agreed to otherwise by Honeywell in writing; please refer to your order acknowledgment or consult your local sales office for specific warranty details. If warranted goods are returned to Honeywell during the period of coverage, Honeywell will repair or replace, at its option, without charge those items that Honeywell, in its sole discretion, finds defective. The foregoing is buyer's sole remedy and is in lieu of all other warranties, expressed or implied, including those of merchantability and fitness for a particular purpose. In no event shall Honeywell be liable for consequential, special, or indirect damages.

While Honeywell may provide application assistance personally, through our literature and the Honeywell web site, it is buyer's sole responsibility to determine the suitability of the product in the application.

Specifications may change without notice. The information we supply is believed to be accurate and reliable as of this writing. However, Honeywell assumes no responsibility for its use.

# **⚠ WARNING**PERSONAL INJURY

DO NOT USE these products as safety or emergency stop devices or in any other application where failure of the product could result in personal injury.

Failure to comply with these instructions could result in death or serious injury.

# **⚠ WARNING**MISUSE OF DOCUMENTATION

- The information presented in this product sheet is for reference only.
   Do not use this document as a product installation guide.
- Complete installation, operation, and maintenance information is provided in the instructions supplied with each product.

Failure to comply with these instructions could result in death or serious injury.

# Honeywell Advanced Sensing Technologies

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