

## ISL32490E, ISL32492E, ISL32493E, ISL32495E, ISL32496E, ISL32498E

±60V Fault Protected, 5V, RS-485/RS-422 Transceivers with ±25V CMR and ESD Protection

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The <u>ISL32490E</u>, <u>ISL32492E</u>, <u>ISL32493E</u>, <u>ISL32495E</u>, <u>ISL32496E</u>, and <u>ISL32498E</u> are fault protected, 5V powered, differential transceivers that exceed the RS-485 and RS-422 standards for balanced communication. The RS-485 transceiver pins (driver outputs and receiver inputs) are fault protected up to  $\pm 60$ V and are protected against  $\pm 16.5$ kV ESD strikes without latch-up. Additionally, the extended Common-Mode Range (CMR) allows these transceivers to operate in environments with common-mode voltages up to  $\pm 25$ V (>2x the RS-485 requirement), making this fault protected RS-485 family one of the most robust on the market.

The transmitters (Tx) deliver an exceptional 2.5V (typical) differential output voltage into the RS-485 specified 54 $\Omega$  load. This yields better noise immunity than standard RS-485 ICs, or allows up to six 120 $\Omega$  terminations in star network topologies.

The receiver (Rx) inputs feature a full fail-safe design that ensures a logic high Rx output if the Rx inputs are floating, shorted, or on a terminated but undriven (idle) bus. The Rx outputs have high drive levels; typically, 15mA at  $V_{OL} = 1V$  (for opto-coupled, isolated applications).

Half duplex (Rx inputs and Tx outputs multiplexed together) and full duplex pinouts are available. See <u>Table 1 on page 3</u> for key features and configurations by device number.

For fault protected or wide common-mode range RS-485 transceivers with cable invert (polarity reversal) pins, see the ISL32483E datasheet.

### **Related Literature**

- · For a full list of related documents, visit our website:
  - <u>ISL32490E</u>, <u>ISL32492E</u>, <u>ISL32493E</u>, <u>ISL32495E</u>, <u>ISL32496E</u>, and <u>ISL32498E</u> device pages

### **Features**

- Fault protected RS-485 bus pins . . . . . . . . up to ±60V
- Extended CMR ..... ±25V (more than twice the range required for RS-485)
- ±16.5kV HBM ESD protection on RS-485 bus pins
- 1/4 unit load for up to 128 devices on the bus
- High transient overvoltage tolerance..... ±80V
- Full fail-safe (open, short, terminated) RS-485 receivers
- High Rx I<sub>OL</sub> for opto-couplers in isolated designs
- Hot plug circuitry; Tx and Rx outputs remain three-state during power-up/power-down
- Choice of RS-485 data rates. . . . . . . . 250kbps to 15Mbps
- Low quiescent supply current...... 2.3mA
- Ultra low shutdown supply current......10μA

### **Applications**

- · Utility meters/automated meter reading systems
- · High node count RS-485 systems
- PROFIBUS and RS-485 based field bus networks, and factory automation
- · Security camera networks
- . Building lighting and environmental control systems
- · Industrial/process control networks

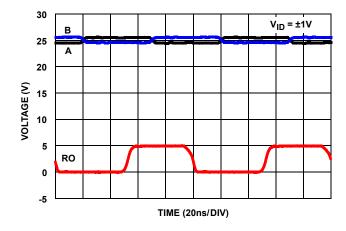


FIGURE 1. EXCEPTIONAL Rx OPERATES AT >15Mbps EVEN WITH A ±25V COMMON-MODE VOLTAGE

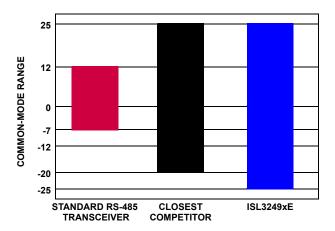


FIGURE 2. ISL3249xE DELIVERS SUPERIOR COMMON-MODE RANGE vs STANDARD RS-485 DEVICES

## **Typical Operating Circuits**

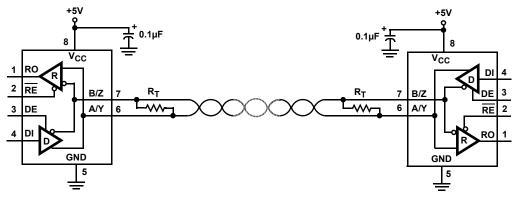


FIGURE 3. ISL32492E, ISL32495E, ISL32498E HALF DUPLEX EXAMPLE

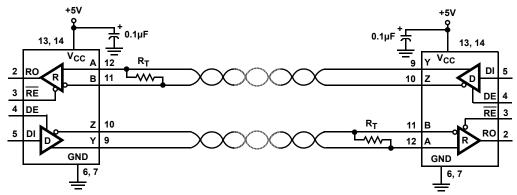


FIGURE 4. ISL32490E, ISL32493E, ISL32496E FULL DUPLEX EXAMPLE (SOIC PIN NUMBERS SHOWN)

## **Ordering Information**

PART NUMBER (Notes 2, 3)	PART MARKING	TEMP. RANGE (°C)	TAPE AND REEL (Units) (Note 1)	PACKAGE (RoHS COMPLIANT)	PKG. DWG. #
ISL32490EIBZ	ISL32490 EIBZ	-40 to +85	-	14 Ld SOIC	M14.15
ISL32490EIBZ-T	ISL32490 EIBZ	-40 to +85	2.5k	14 Ld SOIC	M14.15
ISL32490EIBZ-T7A	ISL32490 EIBZ	-40 to +85	250	14 Ld SOIC	M14.15
ISL32490EIUZ	2490E	-40 to +85	-	10 Ld MSOP	M10.118
ISL32490EIUZ-T	2490E	-40 to +85	2.5k	10 Ld MSOP	M10.118
ISL32490EIUZ-T7A	2490E	-40 to +85	250	10 Ld MSOP	M10.118
ISL32492EIBZ	32492 EIBZ	-40 to +85	-	8 Ld SOIC	M8.15
ISL32492EIBZ-T	32492 EIBZ	-40 to +85	2.5k	8 Ld SOIC	M8.15
ISL32492EIBZ-T7A	32492 EIBZ	-40 to +85	250	8 Ld SOIC	M8.15
ISL32492EIUZ	2492E	-40 to +85	-	8 Ld MSOP	M8.118
ISL32492EIUZ-T	2492E	-40 to +85	2.5k	8 Ld MSOP	M8.118
ISL32492EIUZ-T7A	2492E	-40 to +85	250	8 Ld MSOP	M8.118
ISL32493EIBZ	ISL32493 EIBZ	-40 to +85	-	14 Ld SOIC	M14.15
ISL32493EIBZ-T	ISL32493 EIBZ	-40 to +85	2.5k	14 Ld SOIC	M14.15
SL32493EIBZ-T7A	ISL32493 EIBZ	-40 to +85	250	14 Ld SOIC	M14.15

## Ordering Information (Continued)

PART NUMBER (Notes 2, 3)	PART MARKING	TEMP. RANGE (°C)	TAPE AND REEL (Units) (Note 1)	PACKAGE (RoHS COMPLIANT)	PKG. DWG. #
ISL32493EIUZ	2493E	-40 to +85	-	10 Ld MSOP	M10.118
ISL32493EIUZ-T	2493E	-40 to +85	2.5k	10 Ld MSOP	M10.118
ISL32493EIUZ-T7A	2493E	-40 to +85	250	10 Ld MSOP	M10.118
ISL32495EIBZ	32495 EIBZ	-40 to +85	-	8 Ld SOIC	M8.15
ISL32495EIBZ-T	32495 EIBZ	-40 to +85	2.5k	8 Ld SOIC	M8.15
ISL32495EIBZ-T7A	32495 EIBZ	-40 to +85	250	8 Ld SOIC	M8.15
ISL32495EIUZ	2495E	-40 to +85	-	8 Ld MSOP	M8.118
ISL32495EIUZ-T	2495E	-40 to +85	2.5k	8 Ld MSOP	M8.118
ISL32495EIUZ-T7A	2495E	-40 to +85	250	8 Ld MSOP	M8.118
ISL32496EIBZ	ISL32496 EIBZ	-40 to +85	-	14 Ld SOIC	M14.15
ISL32496EIBZ-T	ISL32496 EIBZ	-40 to +85	2.5k	14 Ld SOIC	M14.15
ISL32496EIBZ-T7A	ISL32496 EIBZ	-40 to +85	250	14 Ld SOIC	M14.15
ISL32496EIUZ	2496E	-40 to +85	-	10 Ld MSOP	M10.118
ISL32496EIUZ-T	2496E	-40 to +85	2.5k	10 Ld MSOP	M10.118
ISL32496EIUZ-T7A	2496E	-40 to +85	250	10 Ld MSOP	M10.118
ISL32498EIBZ	32498 EIBZ	-40 to +85	-	8 Ld SOIC	M8.15
ISL32498EIBZ-T	32498 EIBZ	-40 to +85	2.5k	8 Ld SOIC	M8.15
ISL32498EIBZ-T7A	32498 EIBZ	-40 to +85	250	8 Ld SOIC	M8.15
ISL32498EIUZ	2498E	-40 to +85	-	8 Ld MSOP	M8.118
ISL32498EIUZ-T	2498E	-40 to +85	2.5k	8 Ld MSOP	M8.118
ISL32498EIUZ-T7A	2498E	-40 to +85	250	8 Ld MSOP	M8.118

### NOTES:

- 1. See TB347 for details about reel specifications.
- These Pb-free plastic packaged products employ special Pb-free material sets, molding compounds/die attach materials, and 100% matte tin plate
  plus anneal (e3 termination finish, which is RoHS compliant and compatible with both SnPb and Pb-free soldering operations). Pb-free products are
  MSL classified at Pb-free peak reflow temperatures that meet or exceed the Pb-free requirements of IPC/JEDEC J STD-020.
- 3. For Moisture Sensitivity Level (MSL), see the <u>ISL32490E</u>, <u>ISL32492E</u>, <u>ISL32493E</u>, <u>ISL32495E</u>, <u>ISL32496E</u>, and <u>ISL32498E</u> device information pages. For more information about MSL, see <u>TB363</u>.

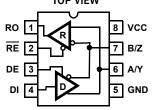
### **TABLE 1. SUMMARY OF FEATURES**

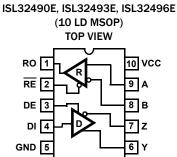
PART NUMBER	HALF/FULL DUPLEX	DATA RATE (Mbps)	SLEW-RATE LIMITED?	EN PINS?	HOT PLUG?	QUIESCENT I <sub>CC</sub> (mA)	LOW POWER SHUTDOWN?	PIN COUNT
ISL32490E	Full	0.25	Yes	Yes	Yes	2.3	Yes	10, 14
ISL32492E	Half	0.25	Yes	Yes	Yes	2.3	Yes	8
ISL32493E	Full	1	Yes	Yes	Yes	2.3	Yes	10, 14
ISL32495E	Half	1	Yes	Yes	Yes	2.3	Yes	8
ISL32496E	Full	15	No	Yes	Yes	2.3	Yes	10, 14
ISL32498E	Half	15	No	Yes	Yes	2.3	Yes	8



## **Pin Configurations**

ISL32492E, ISL32495E, ISL32498E (8 LD MSOP, 8 LD SOIC) TOP VIEW





ISL32490E, ISL32493E, ISL32496E
(14 LD SOIC)
TOP VIEW

NC 1 14 VCC
RO 2 13 VCC
RE 3 11 B
DI 5 10 Z
GND 6 9 Y
GND 7 8 NC

NOTE: Evaluate creepage and clearance requirements at your maximum fault voltage before using small pitch packages such as MSOP.

## **Pin Descriptions**

PIN NAME	8 LD PIN#	10 LD PIN #	14 LD PIN #	FUNCTION
RO	1	1	2	Receiver output. If A-B $\geq$ -10mV, R0 is high; if A-B $\leq$ -200mV, R0 is low; if A and B are unconnected (floating), shorted together, or connected to an undriven, terminated bus, R0 is high.
RE	2	2	3	Receiver output enable. RO is enabled when $\overline{\text{RE}}$ is low; RO is high impedance when $\overline{\text{RE}}$ is high. Internally pulled low.
DE	3	3	4	Driver output enable. The driver outputs, Y and Z, are enabled by bringing DE high. They are high impedance when DE is low. Internally pulled high.
DI	4	4	5	Driver input. A low on DI forces output Y low and output Z high. A high on DI forces output Y high and output Z low.
GND	5	5	6, 7	Ground connection.
A/Y	6	-	-	$\pm 60V$ fault and $\pm 16.5$ kV HBM ESD protected RS-485/RS-422 level, non-inverting receiver input and non-inverting driver output. Pin is an input if DE = 0; pin is an output if DE = 1.
B/Z	7	-	-	$\pm 60$ V fault and $\pm 16.5$ kV HBM ESD protected RS-485/RS-422 level, inverting receiver input and inverting driver output. Pin is an input if DE = 0; pin is an output if DE = 1.
Α	-	9	12	±60V fault and ±15kV HBM ESD protected RS-485/RS-422 level, non-inverting receiver input.
В	-	8	11	±60V fault and ±15kV HBM ESD protected RS-485/RS-422 level, inverting receiver input.
Υ	-	6	9	±60V fault and ±15kV HBM ESD protected RS-485/RS-422 level, non-inverting driver output.
Z	-	7	10	±60V fault and ±15kV HBM ESD protected RS-485/RS-422 level, inverting driver output.
VCC	8	10	13, 14	System power supply input (4.5V to 5.5V).
NC	-	-	1, 8	No internal connection.

## **Truth Tables**

TRANSMITTING								
INPUTS			OUTPUTS					
RE	DE	DI	Z	Y				
Х	1	1	0	1				
Х	1	0	1	0				
0	0	Х	High-Z	High-Z				
1	0	Х	High-Z (see Note)	High-Z (see Note)				

NOTE: Low Power Shutdown Mode (see Note 11 on page 9).

	RECEIVING								
	INPUTS		OUTP	JT					
RE	DE Half Duplex	DE Full Duplex	A-B	RO					
0	0	Х	V <sub>AB</sub> ≥ -0.01V	1					
0	0	Х	-0.01V > V <sub>AB</sub> > -0.2V	Undetermined					
0	0	Х	V <sub>AB</sub> ≤ -0.2V	0					
0	0	Х	Inputs Open/Shorted	1					
1	0	0	Х	High-Z (see Note)					
1	1	1	х	High-Z					

NOTE: Low Power Shutdown Mode (see Note 11 on page 9).



### **Absolute Maximum Ratings**

VCC to Ground 7V
Input Voltages
DI, DE, RE0.3V to (V <sub>CC</sub> + 0.3V)
Input/Output Voltages
A/Y, B/Z, A, B, Y, Z
A/Y, B/Z, A, B, Y, Z (Transient Pulse Through $100\Omega$ , (Note 15) $\pm 80V$
RO0.3V to (V <sub>CC</sub> +0.3V)
Short-Circuit Duration
Y, Z Indefinite
ESD Rating see <u>"ESD PERFORMANCE" on page 6</u>
Latch-Up (Tested per JESD78, Level 2, Class A) +125°C

### **Thermal Information**

Thermal Resistance (Typical)	$\theta_{JA}$ (°C/W)	$\theta_{JC}(^{\circ}C/W)$
8 Ld MSOP Package (Notes 4, 5)	140	40
8 Ld SOIC Package (Notes 4, 5)	108	47
10 Ld MSOP Package (Notes 4, 5)	135	50
<b>14</b> Ld SOIC Package (Notes 4, 5)	88	39
Maximum Junction Temperature (Plastic Pack	(age)	+150°C
Maximum Storage Temperature Range	6	5°C to +150°C
Pb-Free Reflow Profile		See <u>TB493</u>

### **Recommended Operating Conditions**

Supply Voltage (V <sub>CC</sub> )	5V
Temperature Range	
Bus Pin Common-Mode Voltage Range	25V to +25V

CAUTION: Do not operate at or near the maximum ratings listed for extended periods of time. Exposure to such conditions can adversely impact product reliability and result in failures not covered by warranty.

#### NOTES:

- 4.  $\theta_{JA}$  is measured with the component mounted on a high-effective thermal conductivity test board in free air. See <u>TB379</u> for details.
- 5. For  $\theta_{\mbox{\scriptsize JC}},$  the "case temp" location is taken at the package top center.

**Electrical Specifications**  $V_{CC} = 4.5V$  to 5.5V; unless otherwise specified. Typical values are at  $V_{CC} = 5V$ ,  $T_A = +25$ °C (Note 6). Boldface limits apply across the operating temperature range, -40°C to +85°C.

PARAMETER	SYMBOL	TEST CONDITIONS	TEMP (°C)	MIN ( <u>Note 14</u> )	TYP	MAX ( <u>Note 14</u> )	UNIT
DC CHARACTERISTICS			<b>'</b>	I		"	1
Driver Differential V <sub>OUT</sub> (No load)	V <sub>OD1</sub>		Full	-	-	v <sub>cc</sub>	V
Driver Differential V <sub>OUT</sub> (Loaded,	V <sub>OD2</sub>	R <sub>L</sub> = 100Ω (RS-422)	Full	2.4	3.2	-	V
Figure 5A)		R <sub>L</sub> = 54Ω (RS-485)	Full	1.5	2.5	v <sub>cc</sub>	V
		$R_L = 54\Omega (PROFIBUS, V_{CC} \ge 5V)$	Full	2.0	2.5		
		$R_L$ = 21Ω (Six 120Ω terminations for star configurations, $V_{CC} \ge 4.75V$ )	Full	0.8	1.3	-	٧
Change in Magnitude of Driver Differential V <sub>OUT</sub> for Complementary Output States	ΔV <sub>OD</sub>	$R_L = 54\Omega \text{ or } 100\Omega \text{ (Figure 5A)}$ Full -		-	0.2	V	
Driver Differential V <sub>OUT</sub> with	V <sub>OD3</sub>	$R_L = 60\Omega, -7V \le V_{CM} \le 12V$	Full	1.5	2.1	v <sub>cc</sub>	V
Common-Mode Load ( <u>Figure 5B</u> )		$R_L = 60\Omega$ , $-25V \le V_{CM} \le 25V (V_{CC} \ge 4.75V)$	Full	1.7	2.3		
		$R_L = 21\Omega$ , $-15V \le V_{CM} \le 15V (V_{CC} \ge 4.75V)$	Full	0.8	1.1	-	V
Driver Common-Mode V <sub>OUT</sub>	v <sub>oc</sub>	$R_L = 54\Omega$ or $100\Omega$	Full	-1	-	3	V
( <u>Figure 5</u> )		$R_L = 60\Omega$ or $100\Omega$ , $-20V \le V_{CM} \le 20V$	Full	-2.5	-	5	V
Change in Magnitude of Driver Common-Mode V <sub>OUT</sub> for Complementary Output States	ΔV <sub>OC</sub>	$R_L = 54\Omega$ or $100\Omega$ (Figure 5A)	Full	-	-	0.2	V
Driver Short-Circuit Current	I <sub>OSD</sub>	DE = $V_{CC}$ , -25V $\leq V_0 \leq 25V$ ( <u>Note 8</u> )	Full	-250	1	250	mA
	I <sub>OSD1</sub>	At first foldback, 22V ≤ V <sub>0</sub> ≤ -22V	Full	-83	1	83	mA
	l <sub>OSD2</sub>	At second foldback, 35V ≤ V <sub>0</sub> ≤ -35V	Full	-13	-	13	mA
Logic Input High Voltage	V <sub>IH</sub>	DE, DI, RE	Full	2.5	1	-	V
Logic Input Low Voltage	V <sub>IL</sub>	DE, DI, RE	Full	-	1	0.8	v
Logic Input Current	I <sub>IN1</sub>	DI	Full	-1	-	1	μΑ
		DE, RE	Full	-15	6	15	μΑ



**Electrical Specifications**  $V_{CC} = 4.5V$  to 5.5V; unless otherwise specified. Typical values are at  $V_{CC} = 5V$ ,  $T_A = +25$  °C (Note 6). Boldface limits apply across the operating temperature range, -40 °C to +85 °C. (Continued)

PARAMETER	SYMBOL	TE	ST CONDITIONS	TEMP (°C)	MIN ( <u>Note 14</u> )	TYP	MAX (Note 14)	UNIT
Input/Output Current (A/Y, B/Z)	I <sub>IN2</sub>	DE = 0V, V <sub>CC</sub> = 0V	V <sub>IN</sub> = 12V	Full	-	110	250	μΑ
		or 5.5V	V <sub>IN</sub> = -7V	Full	-200	-75	-	μΑ
			V <sub>IN</sub> = ±25V	Full	-800	±240	800	μΑ
			V <sub>IN</sub> = ±60V ( <u>Note 16</u> )	Full	-6	±0.5	6	mA
Input Current (A, B)	I <sub>IN3</sub>	V <sub>CC</sub> = 0V or 5.5V	V <sub>IN</sub> = 12V	Full	-	90	125	μΑ
(Full Duplex Versions Only)			V <sub>IN</sub> = -7V	Full	-100	-70	-	μΑ
			V <sub>IN</sub> = ±25V	Full	-500	±200	500	μΑ
			V <sub>IN</sub> = ±60V ( <u>Note 16</u> )	Full	-3	±0.4	3	mA
Output Leakage Current (Y, Z)	I <sub>OZD</sub>	$\overline{RE} = 0V, DE = 0V,$	V <sub>IN</sub> = 12V	Full	-	20	200	μΑ
(Full Duplex Versions Only)		V <sub>CC</sub> = 0V or 5.5V	V <sub>IN</sub> = -7V	Full	-100	-5	-	μΑ
			V <sub>IN</sub> = ±25V	Full	-500	±40	500	μΑ
			V <sub>IN</sub> = ±60V ( <u>Note 16</u> )	Full	-3	±0.1	3	mA
Receiver Differential Threshold Voltage	V <sub>TH</sub>	-25V ≤ V <sub>CM</sub> ≤ 25V		Full	-200	-100	-10	mV
Receiver Input Hysteresis	$\Delta V_{TH}$	-25V ≤ V <sub>CM</sub> ≤ 25V		25	-	25	-	mV
Receiver Output High Voltage	V <sub>OH</sub>	$I_0 = -2mA, V_{ID} = -10mV$ $I_0 = -8mA, V_{ID} = -10mV$		Full	V <sub>CC</sub> - 0.5	4.75	-	V
				Full	2.8	4.2	-	V
Receiver Output Low Voltage	V <sub>OL</sub>	I <sub>O</sub> = 6mA, V <sub>ID</sub> = -20	0mV	Full	-	0.27	0.4	V
Receiver Output Low Current	l <sub>OL</sub>	V <sub>O</sub> = 1V, V <sub>ID</sub> = -200	Full	15	22	-	mA	
Three-state (High Impedance) Receiver Output Current	l <sub>OZR</sub>	$0V \le V_0 \le V_{CC}$		Full	-1	0.01	1	μΑ
Receiver Short-Circuit Current	I <sub>OSR</sub>	$OV \le V_O \le V_{CC}$		Full	± <b>12</b>	-	± <b>110</b>	mA
SUPPLY CURRENT	1			"				
No Load Supply Current (Note 7)	Icc	$DE = V_{CC}, \overline{RE} = 0V c$	r V <sub>CC</sub> , DI = OV or V <sub>CC</sub>	Full	-	2.3	4.5	mA
Shutdown Supply Current	I <sub>SHDN</sub>	$DE = OV, \overline{RE} = V_{CC}, I$	OI = OV or V <sub>CC</sub>	Full	-	10	50	μΑ
ESD PERFORMANCE	!					•		
RS-485 Pins (A, Y, B, Z, A/Y, B/Z)		Human Body	Half duplex	25	-	±16.5	-	kV
		Model, from bus pins to GND	Full duplex	25	-	±15	-	kV
All Pins		Human Body Model	, per JEDEC	25	-	±8	-	kV
		Machine Model		25	-	±700	-	V
DRIVER SWITCHING CHARACTERISTI	│ CS (250kbps \	│ /ersions - ISL32490E,	ISL32492E)					
Driver Differential Output Delay	t <sub>PLH</sub> , t <sub>PHL</sub>	$R_D = 54\Omega$ ,	No CM load	Full	-	320	450	ns
		C <sub>D</sub> = 50pF ( <u>Figure 6</u> )	-25V ≤ V <sub>CM</sub> ≤ 25V	Full	-	-	1000	ns
Driver Differential Output Skew	tskew	$R_D = 54\Omega$	No CM load	Full	_	6	30	ns
	SKEW	$C_D = 50pF$	-25V ≤ V <sub>CM</sub> ≤ 25V	Full	-	_	50	ns
Data Different (1.1.D)		( <u>Figure 6</u> )						
Driver Differential Rise or Fall Time	t <sub>R</sub> , t <sub>F</sub>	$R_D = 54\Omega$ , $C_D = 50pF$ (Figure 6)	No CM load -25V ≤ V <sub>CM</sub> ≤ 25V	Full	400 300	-	1200 1350	ns
Maximum Data Rate	f <sub>MAX</sub>	C <sub>D</sub> = 820pF ( <u>Figure</u>	<u>Q</u> \	Full	0.25	1.5	_	Mbps



**Electrical Specifications**  $V_{CC} = 4.5V$  to 5.5V; unless otherwise specified. Typical values are at  $V_{CC} = 5V$ ,  $T_A = +25$  °C (Note 6). Boldface limits apply across the operating temperature range, -40 °C to +85 °C. (Continued)

PARAMETER	SYMBOL	TEST CONDITIONS		TEMP (°C)	MIN (Note 14)	ТҮР	MAX (Note 14)	UNIT
Driver Enable to Output High	<sup>t</sup> zH	SW = GND (Figure 7), (Note 9)			-	-	1200	ns
Driver Enable to Output Low	t <sub>ZL</sub>	SW = V <sub>CC</sub> ( <u>Figure 7</u> )	, ( <u>Note 9</u> )	Full	-	-	1200	ns
Driver Disable from Output Low	t <sub>LZ</sub>	SW = V <sub>CC</sub> ( <u>Figure 7</u> )		Full	-	•	120	ns
Driver Disable from Output High	t <sub>HZ</sub>	SW = GND (Figure 7	)	Full	-	•	120	ns
Time to Shutdown	tSHDN	( <u>Note 11</u> )		Full	60	160	600	ns
Driver Enable from Shutdown to Output High	t <sub>ZH</sub> (SHDN)	SW = GND ( <u>Figure 7</u>	), ( <u>Notes <b>11</b>, <b>12</b>)</u>	Full	-	-	2500	ns
Driver Enable from Shutdown to Output Low	t <sub>ZL(SHDN)</sub>	SW = V <sub>CC</sub> ( <u>Figure 7</u> )	( <u>Notes 11</u> , <u>12</u> )	Full	-	-	2500	ns
DRIVER SWITCHING CHARACTERISTI	CS (1Mbps Vei	rsions - ISL32493E, IS	L32495E)					
<b>Driver Differential Output Delay</b>	t <sub>PLH</sub> , t <sub>PHL</sub>	$R_D = 54\Omega$ ,	No CM load	Full	-	70	125	ns
		C <sub>D</sub> = 50pF ( <u>Figure 6</u> )	-25V ≤ V <sub>CM</sub> ≤ 25V	Full	-	-	350	ns
Driver Differential Output Skew	tSKEW	$R_D = 54\Omega$ ,	No CM load	Full	-	4.5	15	ns
		C <sub>D</sub> = 50pF ( <u>Figure 6</u> )	-25V ≤ V <sub>CM</sub> ≤ 25V ( <u>Note 17</u> )	Full	-	-	25	ns
Driver Differential Rise or Fall Time	t <sub>R</sub> , t <sub>F</sub>		No CM load	Full	70	170	300	ns
		C <sub>D</sub> = 50pF ( <u>Figure 6</u> )	-25V ≤ V <sub>CM</sub> ≤ 25V	Full	70	1	550	ns
Maximum Data Rate	f <sub>MAX</sub>	C <sub>D</sub> = 820pF ( <u>Figure</u>	<u>8</u> )	Full	1	4	-	Mbps
Driver Enable to Output High	t <sub>ZH</sub>	SW = GND (Figure 7	SW = GND ( <u>Figure 7</u> ), ( <u>Note 9</u> )		-	-	350	ns
Driver Enable to Output Low	t <sub>ZL</sub>	SW = V <sub>CC</sub> ( <u>Figure 7</u> ), ( <u>Note 9</u> )		Full	-	-	300	ns
Driver Disable from Output Low	t <sub>LZ</sub>	SW = V <sub>CC</sub> ( <u>Figure 7</u> )		Full	-	-	120	ns
Driver Disable from Output High	t <sub>HZ</sub>	SW = GND (Figure 7	)	Full	-	-	120	ns
Time to Shutdown	t <sub>SHDN</sub>	( <u>Note 11</u> )		Full	60	160	600	ns
Driver Enable from Shutdown to Output High	t <sub>ZH(SHDN)</sub>	SW = GND ( <u>Figure 7</u>	), ( <u>Notes 11, 12</u> )	Full	-	-	2000	ns
Driver Enable from Shutdown to Output Low	tzl(SHDN)	SW = V <sub>CC</sub> ( <u>Figure 7</u> ),	(Notes 11, 12)	Full	-	-	2000	ns
DRIVER SWITCHING CHARACTERISTIC	CS (15Mbps V	ersions - ISL32496E, I	SL32498E)		I			1
Driver Differential Output Delay	t <sub>PLH</sub> , t <sub>PHL</sub>	$R_D = 54\Omega$ ,	No CM load	Full	-	21	45	ns
		C <sub>D</sub> = 50pF ( <u>Figure 6</u> )	-25V ≤ V <sub>CM</sub> ≤ 25V	Full	-		80	ns
Driver Differential Output Skew	tskew	$R_D = 54\Omega$ ,	No CM load	Full	-	3	6	ns
		C <sub>D</sub> = 50pF ( <u>Figure 6</u> )	-25V ≤ V <sub>CM</sub> ≤ 25V	Full	-	-	7	ns
Driver Differential Rise or Fall Time	t <sub>R</sub> , t <sub>F</sub>	$R_D = 54\Omega$ ,	No CM Load	Full	5	17	30	ns
		C <sub>D</sub> = 50pF ( <u>Figure 6</u> )	-25V ≤ V <sub>CM</sub> ≤ 25V	Full	5	-	30	ns
Maximum Data Rate	f <sub>MAX</sub>	C <sub>D</sub> = 470pF ( <u>Figure 8</u> )		Full	15	25	-	Mbps
Driver Enable to Output High	t <sub>ZH</sub>	SW = GND ( <u>Figure 7</u>	), ( <u>Note 9</u> )	Full	-	-	100	ns
Driver Enable to Output Low	t <sub>ZL</sub>	SW = V <sub>CC</sub> ( <u>Figure 7</u> )	, ( <u>Note 9</u> )	Full	-	-	100	ns
Driver Disable from Output Low	t <sub>LZ</sub>	SW = V <sub>CC</sub> ( <u>Figure 7</u> )		Full	-	•	120	ns
Driver Disable from Output High	t <sub>HZ</sub>	SW = GND (Figure 7	)	Full	-	•	120	ns
Time to Shutdown	t <sub>SHDN</sub>	( <u>Note 11</u> )		Full	60	160	600	ns



**Electrical Specifications**  $V_{CC} = 4.5V$  to 5.5V; unless otherwise specified. Typical values are at  $V_{CC} = 5V$ ,  $T_A = +25$  °C (Note 6). Boldface limits apply across the operating temperature range, -40 °C to +85 °C. (Continued)

PARAMETER	SYMBOL	TEST CONDITIONS	TEMP (°C)	MIN ( <u>Note 14</u> )	TYP	MAX ( <u>Note 14</u> )	UNIT
Driver Enable from Shutdown to Output High	t <sub>ZH</sub> (SHDN)	SW = GND (Figure 7), (Notes 11, 12)	Full	-	-	2000	ns
Driver Enable from Shutdown to Output Low	<sup>t</sup> ZL(SHDN)	SW = V <sub>CC</sub> ( <u>Figure 7</u> ), ( <u>Notes 11</u> , <u>12</u> )	Full	-	-	2000	ns
RECEIVER SWITCHING CHARACTERIS	TICS (250kbp	s Versions - ISL32490E, ISL32492E)		1			.1
Maximum Data Rate	f <sub>MAX</sub>	-25V ≤ V <sub>CM</sub> ≤ 25V ( <u>Figure 9</u> )	Full	0.25	5	-	Mbps
Receiver Input to Output Delay	t <sub>PLH</sub> , t <sub>PHL</sub>	-25V ≤ V <sub>CM</sub> ≤ 25V ( <u>Figure 9</u> )	Full	-	200	280	ns
Receiver Skew   tPLH - t <sub>PHL</sub>	t <sub>SKD</sub>	(Figure 9)	Full	-	4	10	ns
Receiver Enable to Output Low	t <sub>ZL</sub>	$R_L = 1k\Omega$ , $C_L = 15pF$ , $SW = V_{CC}$ (Figure 10), (Note 10)	Full	-	-	50	ns
Receiver Enable to Output High	<sup>t</sup> zH	$R_L = 1k\Omega$ , $C_L = 15pF$ , $SW = GND$ (Figure 10), (Note 10)	Full	-	-	50	ns
Receiver Disable from Output Low	t <sub>LZ</sub>	$R_L = 1k\Omega$ , $C_L = 15pF$ , $SW = V_{CC}$ ( <u>Figure 10</u> )	Full	-	-	50	ns
Receiver Disable from Output High	t <sub>HZ</sub>	$R_L = 1k\Omega$ , $C_L = 15pF$ , SW = GND ( <u>Figure 10</u> )	Full	-	ı	50	ns
Time to Shutdown	tSHDN	( <u>Note 11</u> )	Full	60	160	600	ns
Receiver Enable from Shutdown to Output High	t <sub>ZH(SHDN)</sub>	$R_L = 1k\Omega$ , $C_L = 15pF$ , $SW = GND$ (Figure 10), (Notes 11, 13)	Full	-	-	2000	ns
Receiver Enable from Shutdown to Output Low	<sup>t</sup> ZL(SHDN)	$R_L = 1k\Omega$ , $C_L = 15pF$ , $SW = V_{CC}$ (Figure 10), (Notes 11, 13)	Full	-	-	2000	ns
RECEIVER SWITCHING CHARACTERIS	TICS (1Mbps \	/ersions - ISL32493E, ISL32495E)				1	
Maximum Data Rate	f <sub>MAX</sub>	-25V ≤ V <sub>CM</sub> ≤ 25V ( <u>Figure 9</u> )	Full	1	15	-	Mbps
Receiver Input to Output Delay	t <sub>PLH</sub> , t <sub>PHL</sub>	-25V ≤ V <sub>CM</sub> ≤ 25V ( <u>Figure 9</u> )	Full	-	90	150	ns
Receiver Skew   t <sub>PLH</sub> - t <sub>PHL</sub>	t <sub>SKD</sub>	(Figure 9)	Full	-	4	10	ns
Receiver Enable to Output Low	t <sub>ZL</sub>	$R_L = 1k\Omega$ , $C_L = 15pF$ , $SW = V_{CC}$ (Figure 10), (Note 10)	Full	-	-	50	ns
Receiver Enable to Output High	<sup>t</sup> zH	$R_L = 1k\Omega$ , $C_L = 15pF$ , $SW = GND$ (Figure 10), (Note 10)	Full	-	-	50	ns
Receiver Disable from Output Low	t <sub>LZ</sub>	$R_L = 1k\Omega$ , $C_L = 15pF$ , $SW = V_{CC}$ ( <u>Figure 10</u> )	Full	-	-	50	ns
Receiver Disable from Output High	t <sub>HZ</sub>	$R_L = 1k\Omega$ , $C_L = 15pF$ , SW = GND ( <u>Figure 10</u> )	Full	-	ı	50	ns
Time to Shutdown	t <sub>SHDN</sub>	(Note 11)	Full	60	160	600	ns
Receiver Enable from Shutdown to Output High	t <sub>ZH(SHDN)</sub>	$R_L = 1k\Omega$ , $C_L = 15pF$ , $SW = GND$ (Figure 10), (Notes 11, 13)	Full	-	-	2000	ns
Receiver Enable from Shutdown to Output Low	tzl(SHDN)	$R_L = 1k\Omega$ , $C_L = 15pF$ , $SW = V_{CC}$ (Figure 10), (Notes 11, 13)	Full	-	-	2000	ns
RECEIVER SWITCHING CHARACTERIS	TICS (15Mbps	Versions - ISL32496E, ISL32498E)				•	
Maximum Data Rate	f <sub>MAX</sub>	-25V ≤ V <sub>CM</sub> ≤ 25V ( <u>Figure 9</u> )	Full	15	25	-	Mbps
Receiver Input to Output Delay	t <sub>PLH</sub> , t <sub>PHL</sub>	-25V ≤ V <sub>CM</sub> ≤ 25V ( <u>Figure 9</u> )	Full	-	35	70	ns
Receiver Skew   t <sub>PLH</sub> - t <sub>PHL</sub>	t <sub>SKD</sub>	(Figure 9)	Full	-	4	10	ns
Receiver Enable to Output Low	t <sub>ZL</sub>	$R_L = 1k\Omega$ , $C_L = 15pF$ , $SW = V_{CC}$ (Figure 10), (Note 10)	Full	-	•	50	ns
Receiver Enable to Output High	t <sub>ZH</sub>	$R_L = 1k\Omega$ , $C_L = 15pF$ , SW = GND ( <u>Figure 10</u> ), ( <u>Note 10</u> )	Full	-	,	50	ns
Receiver Disable from Output Low	t <sub>LZ</sub>	$R_L = 1k\Omega$ , $C_L = 15pF$ , $SW = V_{CC}$ (Figure 10)	Full	-	-	50	ns
Receiver Disable from Output High	t <sub>HZ</sub>	$R_L = 1k\Omega$ , $C_L = 15pF$ , SW = GND ( <u>Figure 10</u> )	Full	-	-	50	ns
Time to Shutdown	t <sub>SHDN</sub>	(Note 11)	Full	60	160	600	ns



**Electrical Specifications**  $V_{CC} = 4.5V$  to 5.5V; unless otherwise specified. Typical values are at  $V_{CC} = 5V$ ,  $T_A = +25$ °C (Note 6). Boldface limits apply across the operating temperature range, -40°C to +85°C. (Continued)

PARAMETER	SYMBOL	TEST CONDITIONS	TEMP (°C)	MIN ( <u>Note 14</u> )	TYP	MAX ( <u>Note 14</u> )	UNIT
Receiver Enable from Shutdown to Output High	tzh(SHDN)	$R_L = 1k\Omega$ , $C_L = 15pF$ , $SW = GND$ (Figure 10), (Notes 11, 13)	Full	-	-	2000	ns
Receiver Enable from Shutdown to Output Low	t <sub>ZL(SHDN)</sub>	$R_L = 1k\Omega$ , $C_L = 15pF$ , $SW = V_{CC}$ (Figure 10), (Notes 11, 13)	Full	-	-	2000	ns

#### NOTES:

- 6. All currents into device pins are positive; all currents out of device pins are negative. All voltages are referenced to device ground unless otherwise specified.
- 7. Supply current specification is valid for loaded drivers when DE = 0V.
- 8. Applies to peak current. See "Typical Performance Curves" beginning on page 11 for more information.
- 9. Keep  $\overline{RE} = 0$  to prevent the device from entering shutdown.
- 10. The RE signal high time must be short enough (typically <100ns) to prevent the device from entering shutdown.
- 11. Transceivers are put into shutdown by bringing RE high and DE low. If the inputs are in this state for fewer than 60ns, the parts are ensured not to enter shutdown. If the inputs are in this state for at least 600ns, the parts are ensured to enter shutdown. See "Low Power Shutdown Mode" on
- 12. Keep  $\overline{RE} = V_{CC}$ , and set the DE signal low time >600ns to ensure that the device enters shutdown.
- 13. Set the  $\overline{RE}$  signal high time >600ns to ensure that the device enters shutdown.
- 14. Compliance to datasheet limits is assured by one or more methods: production test, characterization, and/or design.
- 15. Tested according to TIA/EIA-485-A, Section 4.2.6 (±80V for 15µs at a 1% duty cycle).
- 16. See "Caution" statement following "Absolute Maximum Ratings" on page 5.
- 17. This parameter is not production tested.

### **Test Circuits and Waveforms**

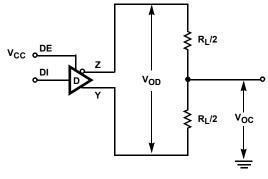


FIGURE 5A.  $V_{OD}$  AND  $V_{OC}$ 

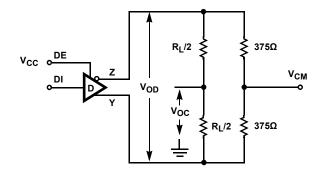
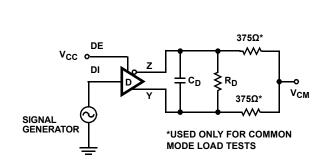


FIGURE 5B.  $V_{\mbox{\scriptsize OD}}$  and  $V_{\mbox{\scriptsize OC}}$  with common-mode load

FIGURE 5. DC DRIVER TEST CIRCUITS

## Test Circuits and Waveforms (Continued)



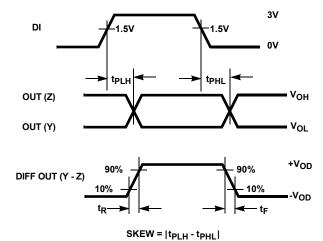
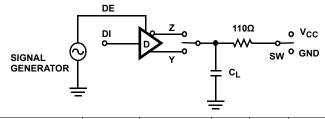


FIGURE 6A. TEST CIRCUIT

FIGURE 6B. MEASUREMENT POINTS

FIGURE 6. DRIVER PROPAGATION DELAY AND DIFFERENTIAL TRANSITION TIMES



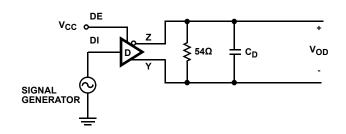
PARAMETER	OUTPUT	RE	DI	sw	C <sub>L</sub> (pF)
t <sub>HZ</sub>	Y/Z	Х	1/0	GND	50
t <sub>LZ</sub>	Y/Z	Х	0/1	$v_{cc}$	50
t <sub>ZH</sub>	Y/Z	0 ( <u>Note 9</u> )	1/0	GND	100
t <sub>ZL</sub>	Y/Z	0 ( <u>Note 9</u> )	0/1	$v_{cc}$	100
t <sub>ZH(SHDN)</sub>	Y/Z	1 ( <u>Note 12</u> )	1/0	GND	100
tzl(SHDN)	Y/Z	1 ( <u>Note 12</u> )	0/1	v <sub>cc</sub>	100

3V DE (Note 11) 0V tzH, tzH(SHDN) tHZ OUTPUT HIGH (Note 11)  $v_{OH}$ OH - 0.5V OUT (Y, Z) 0V tzL, tzL(SHDN) (Note 11) vcc OUT (Y, Z)  $v_{\text{OL}}$ **OUTPUT LOW** 

FIGURE 7A. TEST CIRCUIT

FIGURE 7B. MEASUREMENT POINTS

FIGURE 7. DRIVER ENABLE AND DISABLE TIMES



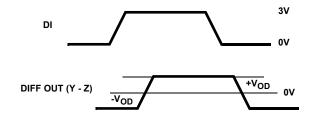
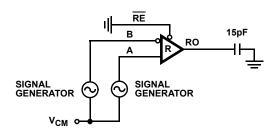


FIGURE 8A. TEST CIRCUIT

FIGURE 8B. MEASUREMENT POINTS

FIGURE 8. DRIVER DATA RATE

## Test Circuits and Waveforms (Continued)



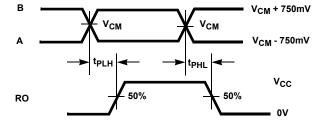
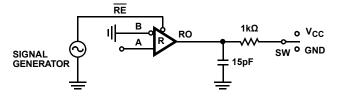


FIGURE 9A. TEST CIRCUIT

FIGURE 9B. MEASUREMENT POINTS

FIGURE 9. RECEIVER PROPAGATION DELAY AND DATA RATE



PARAMETER	DE	A	sw
t <sub>HZ</sub>	0	+1.5V	GND
t <sub>LZ</sub>	0	-1.5V	V <sub>CC</sub>
t <sub>ZH</sub> ( <u>Note 10</u> )	0	+1.5V	GND
t <sub>ZL</sub> ( <u>Note 10</u> )	0	-1.5V	V <sub>CC</sub>
t <sub>ZH</sub> (SHDN) ( <u>Note 13</u> )	0	+1.5V	GND
t <sub>ZL</sub> (SHDN) ( <u>Note 13</u> )	0	-1.5V	v <sub>cc</sub>

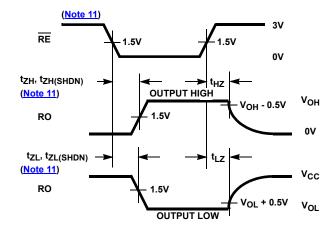


FIGURE 10A. TEST CIRCUIT

FIGURE 10B. MEASUREMENT POINTS

FIGURE 10. RECEIVER ENABLE AND DISABLE TIMES

## Typical Performance Curves $v_{CC}$ = 5V, $T_A$ = +25°C; unless otherwise specified.

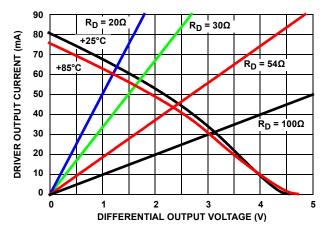


FIGURE 11. DRIVER OUTPUT CURRENT vs DIFFERENTIAL OUTPUT VOLTAGE

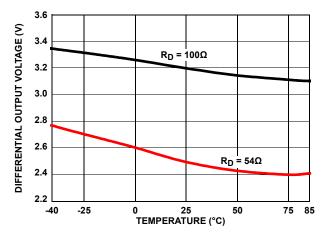


FIGURE 12. DRIVER DIFFERENTIAL OUTPUT VOLTAGE vs TEMPERATURE

## Typical Performance Curves $v_{CC} = 5V$ , $T_A = +25$ °C; unless otherwise specified. (Continued)

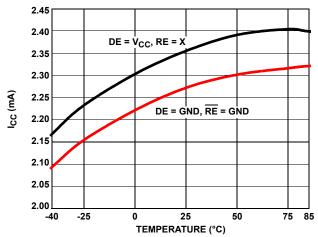


FIGURE 13. SUPPLY CURRENT vs TEMPERATURE

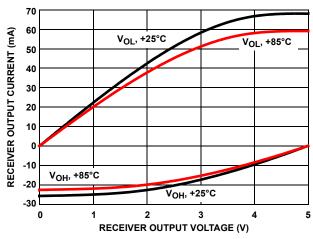


FIGURE 14. RECEIVER OUTPUT CURRENT VS RECEIVER OUTPUT VOLTAGE

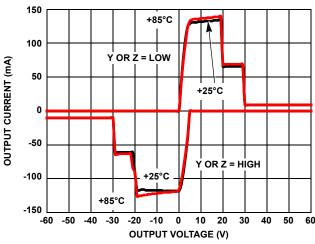


FIGURE 15. DRIVER OUTPUT CURRENT vs SHORT-CIRCUIT VOLTAGE

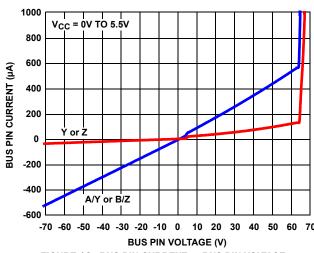


FIGURE 16. BUS PIN CURRENT vs BUS PIN VOLTAGE

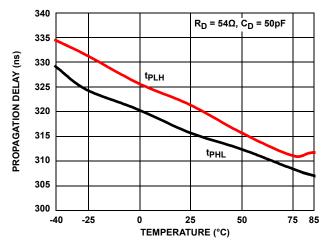


FIGURE 17. DRIVER DIFFERENTIAL PROPAGATION DELAY vs TEMPERATURE (ISL32490E, ISL32492E)

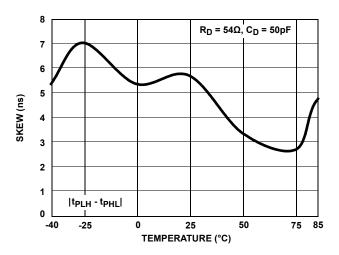


FIGURE 18. DRIVER DIFFERENTIAL SKEW vs TEMPERATURE (ISL32490E, ISL32492E)



## Typical Performance Curves $v_{CC}$ = 5V, $T_A$ = +25 °C; unless otherwise specified. (Continued)

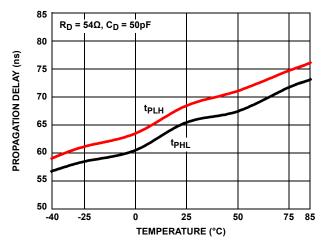


FIGURE 19. DRIVER DIFFERENTIAL PROPAGATION DELAY vs TEMPERATURE (ISL32493E, ISL32495E)

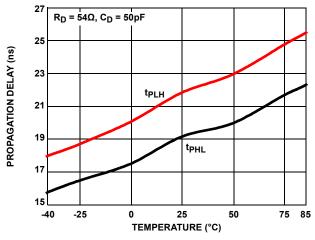


FIGURE 21. DRIVER DIFFERENTIAL PROPAGATION DELAY vs TEMPERATURE (ISL32496E, ISL32498E)

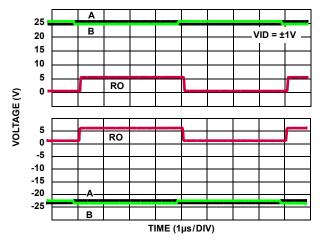


FIGURE 23. RECEIVER PERFORMANCE WITH ±25V CMV (ISL32490E, ISL32492E)

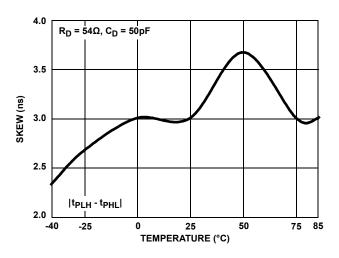


FIGURE 20. DRIVER DIFFERENTIAL SKEW vs TEMPERATURE (ISL32493E, ISL32495E)

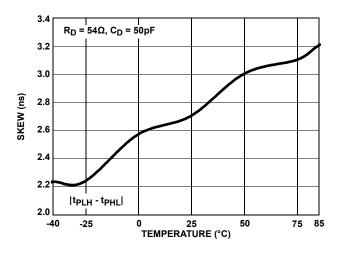


FIGURE 22. DRIVER DIFFERENTIAL SKEW vs TEMPERATURE (ISL32496E, ISL32498E)

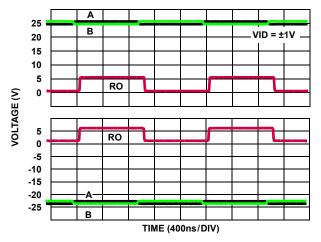


FIGURE 24. RECEIVER PERFORMANCE WITH ±25V CMV (ISL32493E, ISL32495E)



## Typical Performance Curves $v_{CC}$ = 5V, $T_A$ = +25 °C; unless otherwise specified. (Continued)

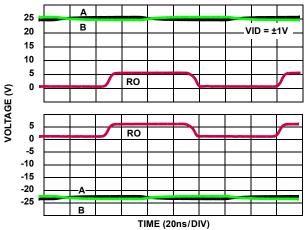


FIGURE 25. RECEIVER PERFORMANCE WITH ±25V CMV (ISL32496E, ISL32498E)

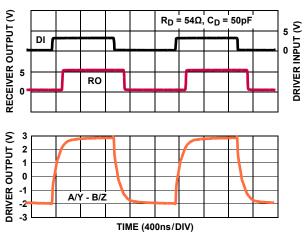


FIGURE 27. DRIVER AND RECEIVER WAVEFORMS (ISL32493E, ISL32495E)

## **Application Information**

RS-485 and RS-422 are differential (balanced) data transmission standards used for long haul or noisy environments. RS-422 is a subset of RS-485, so RS-485 transceivers are also RS-422 compliant. RS-422 is a point-to-multipoint (multidrop) standard that allows only one driver and up to 10 receivers on each bus, assuming one-unit load devices. RS-485 is a true multipoint standard that allows up to 32 one-unit load devices (any combination of drivers and receivers) on each bus. To allow for multipoint operation, the RS-485 specification requires that drivers must handle bus contention without sustaining any damage.

Another important advantage of RS-485 is the extended Common-Mode Range (CMR), which specifies that the driver outputs and receiver inputs withstand signals that range from +12V to -7V. RS-422 and RS-485 are intended for runs as long as 4000ft; thus, the wide CMR is necessary to handle ground potential differences and voltages induced in the cable by external fields.

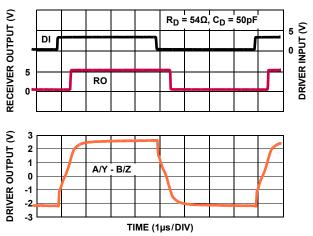


FIGURE 26. DRIVER AND RECEIVER WAVEFORMS (ISL32490E, ISL32492E)

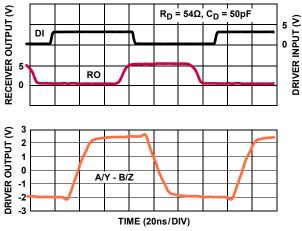


FIGURE 28. DRIVER AND RECEIVER WAVEFORMS (ISL32496E, ISL32498E)

The ISL3249xE is a family of ruggedized RS-485 transceivers that improves on the RS-485 basic requirements and increases system reliability. The CMR increases to  $\pm 25$ V, while the RS-485 bus pins (receiver inputs and driver outputs) include fault protection against voltages and transients up to  $\pm 60$ V. Additionally, larger than required differential output voltages (VOD) increase noise immunity, while the  $\pm 16.5$ kV built-in ESD protection complements the fault protection.

### **Receiver (Rx) Features**

These devices use a differential input receiver for maximum noise immunity and CMR. Input sensitivity is greater than ±200mV as required by the RS-422 and RS-485 specifications.

The receiver input (load) current surpasses the RS-422 specification of 3mA and is four times lower than the RS-485 Unit Load (UL) requirement of 1mA maximum. Therefore, these products are known as one-quarter UL transceivers, and there can be up to 128 of these devices on a network while still complying with the RS-485 loading specification.

The receiver (Rx) functions with common-mode voltages as great as  $\pm 25$ V, making them ideal for industrial or long networks where induced voltages are a realistic concern.

All the receivers include a full fail-safe function that ensures a high-level receiver output if the receiver inputs are unconnected (floating), shorted together, or connected to a terminated bus with all the transmitters disabled (that is, an idle bus).

Rx outputs feature high drive levels (typically 22mA at  $V_{OL} = 1V$ ) to ease the design of optically coupled isolated interfaces.

Receivers easily meet the data rates supported by the corresponding driver, and all receiver outputs are three-statable using the active low RE input.

The Rx in the 250kbps and 1Mbps versions includes noise filtering circuitry to reject high-frequency signals. The 1Mbps version typically rejects pulses narrower than 50ns (equivalent to 20Mbps), while the 250kbps Rx rejects pulses below 150ns (6.7Mbps).

### **Driver (Tx) Features**

The RS-485/RS-422 driver is a differential output device that delivers at least 1.5V across a  $54\Omega$  load (RS-485) and at least 2.4V across a  $100\Omega$  load (RS-422). The drivers feature low propagation delay skew to maximize bit width and minimize EMI, and all drivers are three-statable using the active high DE input.

The 250kbps and 1Mbps driver outputs are slew rate limited to minimize EMI and reflections in unterminated or improperly terminated networks. The ISL32496E and ISL32498E driver outputs are not limited; thus, faster output transition times allow data rates of at least 15Mbps.

### High Overvoltage (Fault) Protection Increases Ruggedness

Note: The available smaller pitch package (MSOP) may not meet the Creepage and Clearance (C&C) requirements for ±60V levels. Determine C&C requirements before selecting a package type.

The  $\pm 60V$  fault protection (referenced to the IC GND) on the RS-485 pins makes these transceivers some of the most rugged on the market. This level of protection makes the ISL3249xE perfect for applications where power (such as 24V and 48V supplies) must be routed in the conduit with the data lines, or for outdoor applications where large transients are likely to occur. When power is routed with the data lines, even a momentary short between the supply and data lines destroys an unprotected device. The  $\pm 60V$  fault levels of this family are at least five times higher than the levels specified for standard RS-485 ICs. The ISL3249xE protection is active whether the Tx is enabled or disabled, and even if the IC is powered down, or VCC and Ground are floating.

If transients or voltages (including overshoots and ringing) greater than  $\pm 60 \text{V}$  are possible, additional external protection is required.

## Widest Common-Mode Voltage (CMV) Tolerance Improves Operating Range

RS-485 networks operating in industrial complexes or over long distances are susceptible to large CMV variations. Either of these operating environments can suffer from large node-to-node ground potential differences or CMV pickup from external electromagnetic sources, and devices with only the minimum required +12V to -7V CMR can malfunction. The ISL3249xE's extended ±25V CMR is the widest available, allowing operation in environments that would overwhelm lesser transceivers. Additionally, the Rx does not phase invert (erroneously change state), even with CMVs of ±40V or differential voltages as large as 40V

## $\label{eq:local_problem} \textbf{High V}_{\textbf{OD}} \ \textbf{Improves Noise Immunity and } \\ \textbf{Flexibility}$

The ISL3249xE driver design delivers larger differential output voltages ( $V_{OD}$ ) than the RS-485 standard requires or than most RS-485 transmitters can deliver. The typical  $\pm 2.5 \text{V}_{OD}$  provides more noise immunity than networks built using many other transceivers.

Another advantage of the large  $V_{OD}$  is the ability to drive more than two bus terminations, which allows for using the ISL3249xE in star and other multi-terminated, nonstandard network topologies. Figure 11 on page 11 details the transmitter's  $V_{OD}$  vs  $I_{OUT}$  characteristic and includes load lines for four  $(30\Omega)$  and six  $(20\Omega)$  120 $\Omega$  terminations. Figure 11 shows that the driver typically delivers  $\pm 1.3$ V into six terminations, and the "Electrical Specifications" on page 5 ensures a  $V_{OD}$  of  $\pm 0.8$ V at  $21\Omega$  across the full temperature range. The RS-485 standard requires a minimum 1.5V  $V_{OD}$  into two terminations, but the ISL3249xE devices deliver RS-485 voltage levels with two to three times the number of terminations.

### **Hot Plug Function**

When a piece of equipment powers up, there is a period of time when the processor or ASIC driving the RS-485 control lines (DE,  $\overline{\text{RE}}$ ) is unable to ensure that the RS-485 Tx and Rx outputs are kept disabled. If the equipment is connected to the bus, a driver activating prematurely during power-up may crash the bus. To avoid this scenario, the ISL3249xE devices incorporate a hot plug function. Circuitry monitoring  $V_{CC}$  ensures that the Tx and Rx outputs remain disabled during power-up and power-down if VCC is less than  $\approx 3.5 \text{V}$ , regardless of the state of DE and RE. The disabled Tx and Rx outputs allow the processor/ASIC to stabilize and drive the RS-485 control lines to the proper states. Figure 29 illustrates the power-up and power-down performance of the ISL3249xE compared to an RS-485 IC without the hot plug feature.



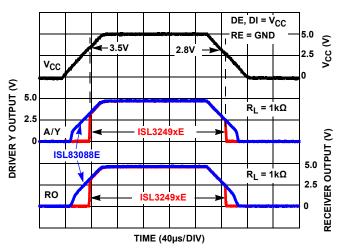


FIGURE 29. HOT PLUG PERFORMANCE (ISL3249xE) vs ISL83088E WITHOUT HOT PLUG CIRCUITRY

### **ESD Protection**

All pins on these devices include Class 3 (>8kV) Human Body Model (HBM) ESD protection structures that can survive ESD events commonly seen during manufacturing. Even so, the RS-485 pins (driver outputs and receiver inputs) incorporate more advanced structures, allowing them to survive ESD events in excess of ±16.5kV HBM (±15kV for the full-duplex versions). The RS-485 pins are particularly vulnerable to ESD strikes because they typically connect to an exposed port on the exterior of the finished product. Touching the port pins or connecting a cable can cause an ESD event that can destroy unprotected ICs. The new ESD structures protect the device whether or not it is powered up, and without interfering with the exceptional ±25V CMR. The built-in ESD protection minimizes the need for board-level protection structures (for example, transient suppression diodes) and the associated undesirable capacitive load they present.

### **Data Rate, Cables, and Terminations**

RS-485 and RS-422 are intended for network lengths up to 4000ft, but the maximum system data rate decreases as the transmission length increases. Devices operating at 15Mbps can be used at lengths up to 150ft (46m), but the distance can be increased to 328ft (100m) by operating at 10Mbps. The ISL32493E and ISL32495E can operate at the full data rate of 1Mbps with lengths up to 800ft (244m). Jitter is the limiting parameter at these faster data rates, so employing encoded data streams (for example, Manchester coded or Return-to-Zero) can allow increased transmission distances. The ISL32490E and ISL32492E can operate at 115kbps or less at the full 4000ft (1220m) distance, or at 250kbps for lengths up to 3000ft (915m). DC cable attenuation is the limiting parameter, so using better quality cables (such as 22 AWG) may allow increased transmission distance.

Use a twisted pair cable for RS-485/RS-422 networks. Twisted pair cables tend to pick up noise and other electromagnetically induced voltages as common-mode signals that are effectively rejected by the differential receivers in these ICs.

Note: Proper termination is imperative to minimize reflections when using the 15Mbps ISL32496E and ISL32498E devices. Short networks using the 250kbps ISL32490E and ISL32492E versions do not need to be terminated; however, terminations are recommended unless power dissipation is an overriding concern.

In point-to-point or point-to-multipoint networks (single driver on bus, such as RS-422), terminate the main cable in its characteristic impedance (typically  $120\Omega$ ) at the end farthest from the driver. In multireceiver applications, keep stubs connecting receivers to the main cable as short as possible. Multipoint (multidriver) systems require that the main cable be terminated in its characteristic impedance at both ends. Keep stubs connecting a transceiver to the main cable as short as possible.

### **Built-in Driver Overload Protection**

The RS-485 specification requires that drivers survive worst-case bus contentions undamaged. These transceivers meet this requirement using driver output short-circuit current limits and on-chip thermal shutdown circuitry.

The driver output stages incorporate a double foldback, short-circuit current limiting scheme, which ensures that the output current never exceeds the RS-485 specification, even at the common-mode and fault condition voltage range extremes. The first foldback current level ( $\approx$ 70mA) is set to ensure that the driver never folds back when driving loads with CMVs up to  $\pm$ 25V. The very low second foldback current setting ( $\approx$ 9mA) minimizes power dissipation if the Tx is enabled when a fault occurs.

In the event of a major short-circuit condition, the ISL3249xE's thermal shutdown feature disables the drivers whenever the die temperature becomes excessive. Thermal shutdown eliminates the power dissipation, allowing the die to cool. The drivers automatically re-enable after the die temperature drops about  $+15\,^{\circ}$ C. If the contention persists, the thermal shutdown/re-enable cycle repeats until the fault is cleared. Receivers stay operational during thermal shutdown.

### **Low Power Shutdown Mode**

These BiCMOS transceivers all use a fraction of the power required by competitive devices, but they also include a shutdown feature that reduces the already low quiescent  $I_{CC}$  to a  $10\mu A$  trickle. These devices enter shutdown whenever the receiver and driver are simultaneously disabled ( $\overline{RE} = V_{CC}$  and DE = GND) for a period of at least 600ns. Disabling both the driver and the receiver for fewer than 60ns ensures that the transceiver does not enter shutdown.

Receiver and driver enable times increase when the transceiver enables from shutdown. See <a href="Notes 9">Notes 9</a> through <a href="13">13</a> on <a href="page 9">page 9</a> for more information.

### **Die Characteristics**

### **SUBSTRATE POTENTIAL (POWERED UP):**

**GND** 

### PROCESS:

Si Gate BiCMOS



**Revision History** The revision history provided is for informational purposes only and is believed to be accurate, but not warranted. Please visit our website to make sure you have the latest revision.

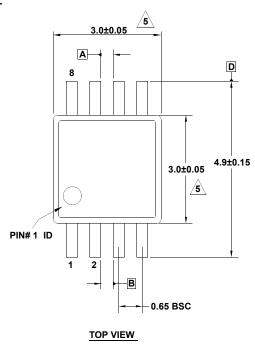
DATE	REVISION	CHANGE
Feb 8, 2019	FN7765.6	Updated links throughout document.  Updated ordering information table by adding all tape and reel information and updating notes.  Updated last sentence in the "High Overvoltage (Fault) Protection Increases Ruggedness" section.  Removed About Intersil section.  Updated disclaimer.
Sep 18, 2017	FN7765.5	Added Related Literature section. Updated Receiving Truth Table on page 3. Applied Intersil A Renesas Company template.
Apr 20, 2015	FN7786.4	DRIVER SWITCHING CHARACTERISTICS (250kbps Versions; ISL32490E, ISL32492E) Changed MAX limit from "1200" to "1350" in "Driver Differential Rise or Fall Time" on page 6 that has -25V ≤ V <sub>CM</sub> ≤ 25V for test condition.  DRIVER SWITCHING CHARACTERISTICS (1Mbps Versions; ISL32493E, ISL32495E) Changed MAX limit from "400" to "550" in "Driver Differential Rise or Fall Time" on page 7 that has -25V ≤ V <sub>CM</sub> ≤ 25V for test condition.
Oct 14, 2014	FN7786.3	On page 7, added "Note 17" reference to the Driver Differential Output Test condition. On page 9, added Note 17, "This parameter is not production tested." On page 19 replaced M10.118 POD with latest revision.
Mar 7, 2012	FN7786.2	Updated Figure 16 on page 12 to show Pos breakdown between 60V and 70V.  Updated Theta JA in "Thermal Information" on page 5 for 8 Ld SOIC from 116 to 108.  Updated Package Outline Drawing on page 21. Changed Note 1 "1982" to "1994".
Nov 11, 2011	FN7786.1	Added 10 to "Pin Count" for ISL32490E, ISL32493E, ISL32496E in the Summary of Features table.  Added 10 Ld MSOP option for ISL32490E, ISL32493E, ISL32496E in the "Ordering Information" table.  Added 10 Ld MSOP pinout to "Pin Configurations" for ISL32490E, ISL32493E, ISL32496E.  Added 10 Ld Pin # column in the "Pin Description" table.  Added "(SOIC pin numbers shown)" in the "Typical Operating Circuits".  Added 10 Ld MSOP information in the "Thermal Resistance" section.  Added 10 Ld MSOP package outline drawing.  M8.118 on page 18- Corrected lead width dimension in side view 1 from "0.25 - 0.036" to "0.25 - 0.36"  M8.15 on page 21- In Typical Recommended Land Pattern, changed the following:  2.41(0.095) to 2.20(0.087)  0.76 (0.030) to 0.60(0.023)  0.200 to 5.20(0.205)
Jan 18, 2011	FN7786.0	Initial release

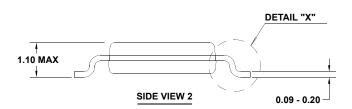
## **Package Outline Drawings**

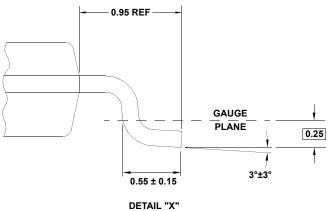
For the most recent package outline drawing, see M8.118.

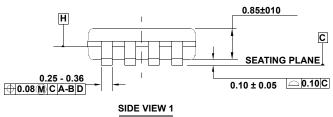
### M8.118

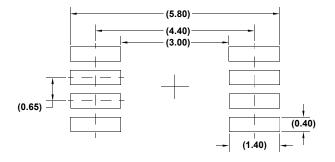
8 LEAD MINI SMALL OUTLINE PLASTIC PACKAGE Rev 4, 7/11











TYPICAL RECOMMENDED LAND PATTERN

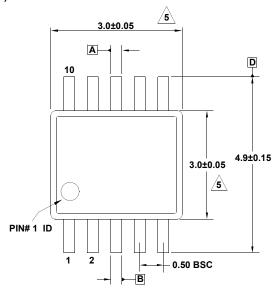
- 1. Dimensions are in millimeters.
- Dimensioning and tolerancing conform to JEDEC MO-187-AA and AMSEY14.5m-1994.
- Plastic or metal protrusions of 0.15mm max per side are not included.
- Plastic interlead protrusions of 0.15mm max per side are not included.
- 5. Dimensions are measured at Datum Plane "H".
- 6. Dimensions in ( ) are for reference only.

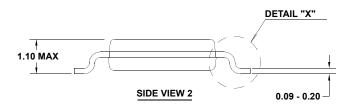
### M10.118

### 10 LEAD MINI SMALL OUTLINE PLASTIC PACKAGE

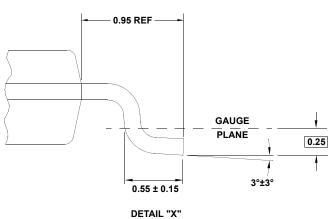
Rev 1, 4/12

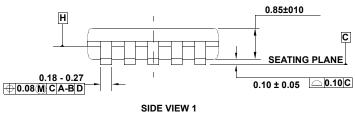
For the most recent package outline drawing, see M10.118.

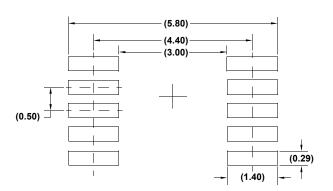




**TOP VIEW** 







TYPICAL RECOMMENDED LAND PATTERN

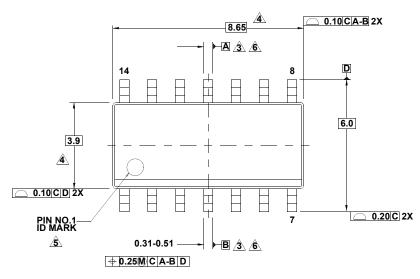
- 1. Dimensions are in millimeters.
- Dimensioning and tolerancing conform to JEDEC MO-187-BA and AMSEY14.5m-1994.
- Plastic or metal protrusions of 0.15mm max per side are not included.
- 4. Plastic interlead protrusions of 0.15mm max per side are not included.
- 5. Dimensions are measured at Datum Plane "H".
- 6. Dimensions in ( ) are for reference only.

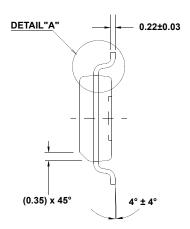
### M14.15

## 14 LEAD NARROW BODY SMALL OUTLINE PLASTIC PACKAGE

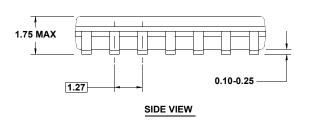
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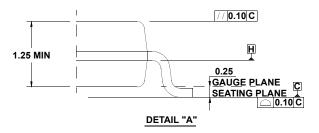
Rev 1, 10/09

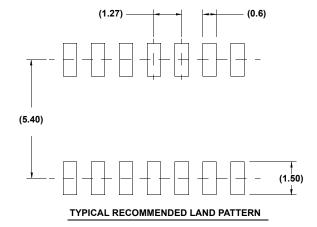




TOP VIEW



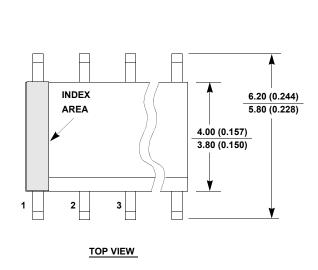


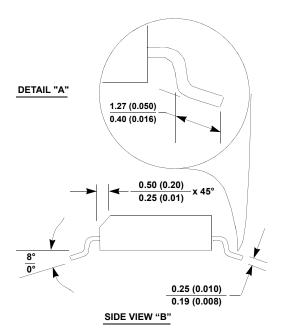


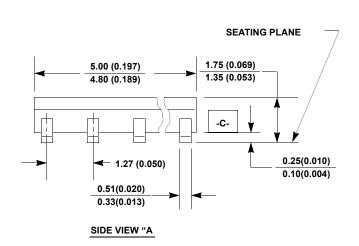
- Dimensions are in millimeters.
   Dimensions in ( ) for Reference Only.
- 2. Dimensioning and tolerancing conform to AMSEY14.5m-1994.
- 3. Datums A and B to be determined at Datum H.
- 4. Dimension does not include interlead flash or protrusions. Interlead flash or protrusions shall not exceed 0.25mm per side.
- 5. The pin #1 indentifier may be either a mold or mark feature.
- Does not include dambar protrusion. Allowable dambar protrusion shall be 0.10mm total in excess of lead width at maximum condition.
- 7. Reference to JEDEC MS-012-AB.

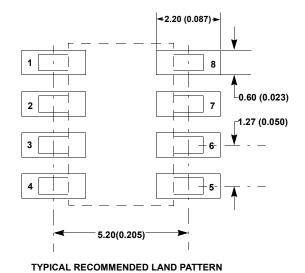
# M8.15 8 LEAD NARROW BODY SMALL OUTLINE PLASTIC PACKAGE Rev 4, 1/12

For the most recent package outline drawing, see M8.15.









- 1. Dimensioning and tolerancing per ANSI Y14.5M-1994.
- Package length does not include mold flash, protrusions or gate burrs.
   Mold flash, protrusion and gate burrs shall not exceed 0.15mm (0.006 inch) per side.
- Package width does not include interlead flash or protrusions. Interlead flash and protrusions shall not exceed 0.25mm (0.010 inch) per side.
- 4. The chamfer on the body is optional. If it is not present, a visual index feature must be located within the crosshatched area.
- 5. Terminal numbers are shown for reference only.
- The lead width as measured 0.36mm (0.014 inch) or greater above the seating plane, shall not exceed a maximum value of 0.61mm (0.024 inch).
- 7. Controlling dimension: MILLIMETER. Converted inch dimensions are not necessarily exact.
- 8. This outline conforms to JEDEC publication MS-012-AA ISSUE C.

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(Rev.4.0-1 November 2017)

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