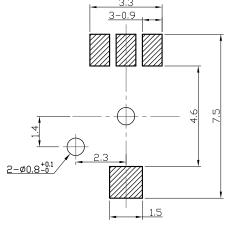


轴芯齿形详图

注: △-□为重点管控尺寸。

SW CIRCUIT



P.C.B MOUNTING DETAIL

03			水水 深圳市亚特联科技有限公司			
02			: 統則市业特联科技有限公司 SHENZHEN YATELIAN TECHNOLOGY CO., LTD			
01			NAME	VE0/000V4 10 0V000 B/0 04		
00			INVINIT	YE0602SV1-L9. 2K0	38-262-01	
NO	DATE	DESCRIPTION	DDAWING NO	YE0602-1		
SCALE		TOLERANCE	DRAWING NO	120002-1		
UNIT	mm	L≤10 ±0.3	DRAWN BY	CHECK BY	APPROVED BY	
1		$10 \le L \le 30 \pm 0.5$				
🕀 -		30 < L≤100 ±1.0	Julie	Henry	Levin	
	1	ANGLE $\pm 5^{\circ}$				



1. 一般事项General

1-1: 适用规格Scope

本规格书适用于电子设备用微小电流回路06型回转式编码器。

This specification applies to 6mm size low-profile rotary encoder (incremental type) for

microscopic current circuits used in electronic equipment.

1-2: 标准状态 Standard atmospheric conditions

除另有规定外,测量应在以下状态下进行:

Unless otherwise specified, the standard range of atmospheric conditions for making measurements and test is as following limits:

温 度 Ambient temperature : 15℃ to 35℃

相对湿度 Relative humidity : 25 % to 85%

气 压 Air pressure : 86KPa to 106 Kpa

1-3: 使用温度范围

Operating temperature range : -30° C to $+80^{\circ}$ C

1-4: 保存温度范围

Storage temperature range : -40~% to +85~%

2. 构造Construction

2-1: 尺寸Dimensions

见所附成品图Refer to attached drawing

3. 额定值 Rating

3-1: 额定电压

Rated voltage : DC. 5V

3-2: 最大额定电流(阻抗负载)

Maximum operating current (resistive load)

各相导线 Each lead: 0.5mA(Max 5mA;Min 0.5mA)

公共导线 Common lead: 1mA(Max 10mA;Min 1mA)

4. 使用注意事项 Application Notes

4-1: 不要在高温、多湿及腐蚀性气体环境中保管。

During operation storage in high temperature and in corrosive gas. should be avoided.

4-2: 对编码器脈冲数的处理、设计时,要充分考虑速度、脈冲调制时间和杂音干扰等因素。

As design of the pulse count process. Care should be taken with operational speed.

4-3:本制品在卡点上使A相在OFF 状态下比较安定,软件设计时以A相为标准

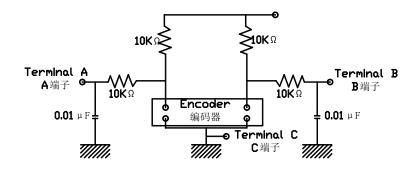
With this part detent positions we always be aligned with a-off phase. Therefore Make the a phase the reference at the soft ware design stage.

4-4: 编码器的脤冲数处理电路建议附加滤波电路(图1)。

The circuit of the pulsecount process should be adding filter as figure(fig.1).

4-5: 本制品本体若接触水分则对脤冲波形能产生异常影响,避免直接接触水分。

This product when touching wet or water can be influence the pulse wave.





项 目 Item		A 件 Conditions			规 格 Specifications	
1.6m		Conditions Specifications AB两个信号的相位差输出波型详见Fig.2;虚线表示带卡点装置的上擎子处位置				
		2 phase-different signals (signal A,signal B)Details shown in fig.2;The broken line shows detent position				
		知的回转方向 Shaft rotational signal signal		输 出 波 型 Output		
		direction	5151141		Fig.2	
5-1	输出信号 Output signal forma	顺时针方向 C.W.	A(A~C端子间) A(Terminal A~C)	0FF 0N		
			B(B~C端子间) B(Terminal B~C)	0FF 0N		
		逆时针方向 C.C.W.	A(A~C端子间) A(Terminal A~C)	0FF 0N		
			B(B~C端子间) B(Terminal B~C)	0FF		
5-2	分解能力	回转360°的输出脉沿			6个脉冲/360°(Fig.2)	
	Resolution	Number of pulses in 3			6 pulses/360° for each phase	
5–3	开关特性 Switching Characteristics	下图Fig.3所示回路,轴以360°/s的速度回转测定 Measurement shall be made under the condition as follows Shaft rotational speed: 360°/s Test circuit: Fig.3 图3 fig. 3 图4fig. 4 ISV Terminal B B H H H ISV ISV ISV ISV ISV ISV				
5-3-1	振荡 Chattering	的通过时间应符合规定 Specified by the signal's passage time from 1.5V to 3.5V			t1,t3 ≤ 3ms 带卡点时,在卡点位置上的B信号振荡 无规定 On the case within detent,B Signal will be irregular oscillation.	
5-3-2	滑动杂音 (突跳) Sliding noise (Bounce)	編码 ON 部份的1.5V以上的电压变动时间在振荡t1,t3之间会产生 1ms以上1.5 V以下的ON部份。另外,如果各突跳1.5V以下的范围 在1ms以上时,则判定为另一个突跳。 Specified by the time of voltage change exceed 1.5V in code-ON area. When the bounce has code-ON time Less than 1mS between chattering (t1 or t3),the voltage change shall be regarded as a part of chattering. When the code-ON time between 2 bounces is less than 1mS,they are regarded as 1 linked bounce.				



	AEI →1 → →	编码OFF部份的电压变动	3.5V以上
5-3-3	滑动杂音 Sliding noise		
	Shame noise	The voltage change in code-OFF area.	3.5V Min
		以固定的速度(360°/s)操作轴进行回转。 Measurement shaft be made under the condition which the shaft is	
		rotated in constant speed. 图5 fig. 5	
		T	
	相位差		见(Fig.5) in (Fig.5)
5-4	Phase difference	A信号(A−C间)	T1 \times T2 \times T3 \times T4 \geq 6ms
		B信号(B-C间)	
		Signal B	
		T1 T2 T3 T4	
	耐电压	在端子和支架间施加AC.300V电压1分钟。	不得有绝缘破坏
5-5		A voltage of 300VAC. shaft be applied for 1 min between individual	Without arcing or breakdown.
		terminals and frame.	
		在端子和支架间施加DC.250V 1mA	端子和轴间电阻50MΩ以上
5-6	绝缘阻抗 Insulation resistance	Measurement shaft be made under the condition which a voltage of	Between individual terminals and
	insulation resistance	250V DC. is applied between individual terminals and frame.	bushing:50MΩ Min.
6. 机械性的	L ₩ Mechanical d	characteristics	5
O. 1/10/04/12/1	全回转角度	MAI 40 001 15 0105	360°(无止挡点)
6-1	Total rotational		360°(Endless)
	angle 卡点出脱力矩 Detent torque	L	
6-2		Only suitable for C.C, equipment.	1~4mN.m(10~40gf.cm)
	定位点数及位置	只适用于附卡点装置	12点定位(间隔角度30°±3°)
6-3	Number and	Only suitable for C.C, equipment.	12 detents(Step angle: 30°±3°)
	Position of detent	在轴端,沿轴向施加20N(2kgf)的推力和拉力各5秒钟。	
	轴的推拉强度	, , ,	产品不可散开,轴向虚位间隙0.4mm以
6-4	r usir puir strengtii	(在PCB焊锡后)	The product can not be disperse,
	shaft	Push and pull static load of 20N shall be applied to the shaft in	Shaft play in axial direction 0.4mmMax;
		the axial direction for 5s.(After installing)	
		端子前端的任意方向施加3N(0.3Kgf)的静负荷力1分钟。	端子不得有明显松动及接触不良,
6-5	端子强度	A static load of 3N shall be applied to the tip of terminals for 1 min in	但允许变形。
	Terminal strength	any direction.	Without excessive play in terminal
			or poor contact.
6-6		在轴前端2mm处,沿径向瞬间施加3N (0.3 Kgf)的力。	1*L/30mm p-p 以下(L: 指安装平面
	轴摆动	A momentary load of 50N shall be applied at the point 5mm from	到轴的柄端的距离.)
	Shaft wobble	the tip of the shaft in a direction perpendicular to the axis of shaft.	1* L/30mm p-p Max L:Distance between
			mounting surface and measuring pointon
			the shaft
6-7	轴的回转方向摆动 Shaft play in	用角度板测定	5°以下
0 1	rotational wobble	Testing by angle board.	5°Max
	轴向间隙	在轴上施加5N(50gf)的推力或拉力.	0.3mm 以下
6-8	Shaft play in axial	The pull / push load of 5N(50gf) shall be imposed on the shaft.	0.3mm Max.
	direction	r - r - r - r - r - r - r - r - r - r -	



7. 耐久性	能 Endurance ch	aracteristics		
项 目 Item		条件 Conditions	规格 Specifications	
		在无负荷条件下轴以600~1000/h速度回转30,000周。	振荡: t1,t2≦3ms	
7–1	回转寿命	The shaft of encoder shall be rotated to 30,000 cycles at a speed	Chattering $t1,t2 \le 3ms$	
	D 4 4: 11:0	of 600~1000/h without electrical load, after which measurements	卡点出脱力矩-30%~+10%	
		shall be made.	Detent torque -30%~+10%	
	耐湿性	温度40±2℃、湿度90~95%的恒温恒湿槽中放置96±4小时后,		
		在常温、常湿中放置1.5小时后测试。		
5 0		The encoder shall be stored at temperature of $40\pm2^{\circ}\mathrm{C}$ with relative	应满足初期规格。	
7–2	Damp heat	humidity of 90% to 95% for 96±4 in a thermostatic chamber .And then	Specifications in clause	
		the encoder shall be subjected to standard atmospheric conditions for 1.5H.		
		After which measurements shall be made.		
		温度85±3℃的恒温箱中放置96±4小时,常温、常湿		
	71.44 M.	放置1.5小时后测量。	应满足初期规格。	
7-3	耐热性 Dry heat	The encoder shall be stored at a temperature of 85±3°C for 96±4H in a	Specifications in clause	
		thermostatic chamber. And then the encoder shall be subjected to standard		
		atmospheric conditions for 1.5H. After witch measurement shaft be made.		
		温度-40±3℃的恒温箱中放置96±4小时,常温、常湿		
		放置1.5小时后测量	应满足初期规格。	
7-4	低温特性 Cold	The encoder shall be stored at a temperature of -40±3℃ for 96±4H in a	Specifications in clause	
		thermostatic chamber. And then the encoder shall be subjected to standard		
		atmospheric conditions for 1.5H. After witch measurement shaft be made.		
		预热: PBC板表面温度180±3℃以下,时间2分钟以内.		
7-5	预先加热 Preheat	Preating must be finished within 2 minutes to reach Max.180±3 ℃ of copper		
	Treneat	foil surface after a PCB is placed a reflow soldering furnance.		
		焊接温度250℃以下,仅允许时间3±1秒以内.	•	
		Soldering temperature is only allowed within 3±1s at Max.250 ℃		
		of copper foil surface after preheating. Q 300—	N O I 4	
		in and	250°C Max 3±1s	
7-6	焊接加热 Soldering Heat	of copper foil surface after preheating. © 300 at 200 100 100	180°C	
		를 100 /		
		Room	Time(s)	
		temperature2±0.3minutes	30±10Seconds Max	
		3-4min Ma	X	
	允许焊锡过程次数 Allowable	2次以下		
7-7		2 times max		
	Process			



推动开关部份 Push Switch Portion

备注:以下规格适用于YE06编码器带开关系列

Note:The following specification is only suitable for the one type with switch of YEO6 encoder series

1. 额定值 Rating

1-1: 额定电压

Rated voltage : DC 5V

1-2: 最大额定电流(阻抗负载)

DESCRIPTION

DATE

Maximum operating current (resistive load): 10 mA Max

2. 电气性能Electrical characteristics

项 目 Item		条 件 Conditions			规 格 Specifications			
0 1	接触电阻	用DC 5V 1mA 电压测定			100mΩMax			
2-1	Contact resistance	Voltage test at DC 5V 1mA.				100ms2Max		
2-2	振荡	以1秒钟1往复(OFF-ON-OFF)回转运转			10ms以下			
	Bouncing	shaft shall be Rotated at 1 cycles/sec(OFF-ON-OFF)			10ms Max			
		在端子与安装板间施加DC.250V 1mA			在端子安装板间50MΩ以上			
2-3	绝缘电阻 Insulation resistance	Measurement shall be made under the Condition which a voltage			Between individual Terminals and			
	111541441011 14515441144	250V DC 1mA Is applied between individual Terminals and tracked			bracket 50MΩ Min.			
		在端子和安装板间施加AC300V电压1分钟			不得有绝缘破坏			
2-4	耐电压 Dielectric strength	A voltage of 300V AC shall be applied for 1 minute between				Without arcing or Breakdown.		
	Biolocure strength	individual terminals and bushing and plank.						
机械性	能Mechanical ch	aracteristics						
	五分子的 停下机					单极单投(推ON)		
3-1	开关电路、接点数 Switch circuit and Number of pulse				Single pole and single			
						throw(push on)		
3-2	开关移动量 Travel of switch				0.1+0.1/-0mm			
开关动作力 在轴方向施加的按压力 Operating force of switch Push static load to the shaft in the axial direction					250±100gf			
耐久性	能 Endurance ch	aracteristics						
	在无负荷条件下沿轴向施以200gf以下的力,以600次/小时的速度按压,				接触电阻:200mΩ以下			
4-1	寿命特性 Operating life	连续运转20,000往复。				Contact resistance: 200mΩ Max.		
		The encoder's shall shall be rotated to 20,000 cycles at a speed of 600/h				开关动作力:-30%~+10%。		
		without electrical load.			Operating force of switch:-30% +10%			
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			DSGD.	CHKD.	APPD.	DOCUMENT NO.文号:		
			Julie	Hanry	Levin	YE06		
		2021/7/16	Julie	Henry	LEVIII	版本号: 00		

文控编号: