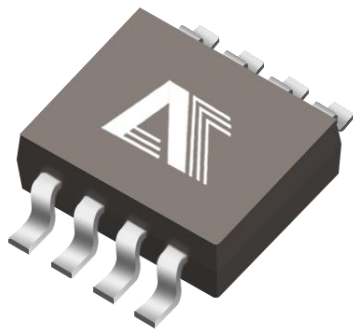




555Timer/Timer

NE555DR

Product Data Sheet

**AOTE DCC
RELEASE**

◆ Summary :

NE555 is a bipolar integrated circuit capable of generating high-precision timing pulses. The internal circuit consists of four parts: threshold comparison, trigger comparator, RS flip-flop, and output circuit. It can be composed of timing trigger circuits, pulse width modulation circuits, audio oscillators, and other circuits by connecting a small number of resistor capacitor devices externally. Widely used in fields such as toys, signal traffic, and automation control.

◆ Product features

- Encapsulation form: SOP-8
- Good timing accuracy
- Strong output driving capability
- Good temperature stability
- The maximum operating frequency can reach over 500kHz
- Compatible with TTL circuits
- The timing can range from microseconds to hours
(Can be precisely controlled through external resistors and capacitors)

◆ Applications

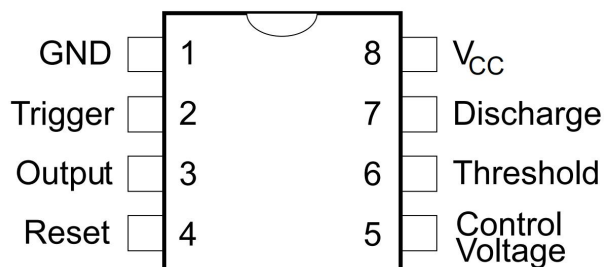
- Audio pulse generator, frequency divider
- Equipment timing, traffic light control, access control
- Pulse width modulation, pulse phase modulation
- industrial control

◆ Product ordering information

Product Name	Encapsulation	Print Name	Packaging	Packaging Quantity
NE555DR	SOP-8	NE555	tape	2500 pieces/plate

◆ Package form

SOP-8



◆ Pin Function Definition

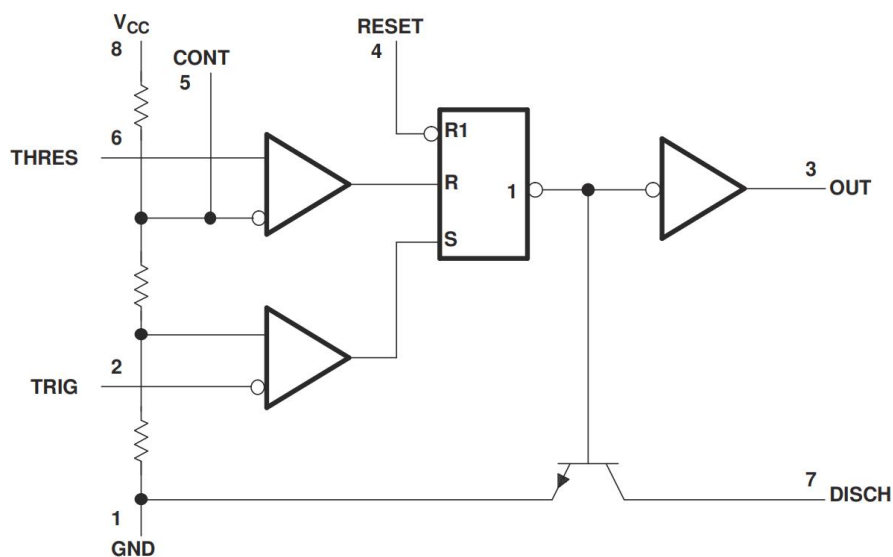
Pin number	Pin Definition	Pin Function Description
1	GND	Power ground
2	Trig	Trigger
3	Output	Output
4	Reset	Reset
5	Cont	Control voltage
6	Thres	Threshold
7	Disch	Discharge
8	VCC	Positive power supply

◆ Limiting parameters

Parameter	Symbol	limit value	Unit
Power supply voltage	V_{CC}	18	V
input voltage	V_I (thre,trig,cont,reset)	V_{CC}	V
Output Current	I_O	± 220	mA
Dissipated power	P_D	400	mW
Operating Temperature	T_A	$0 \sim 70$	$^{\circ}\text{C}$
Storage temperature	T_S	$-65 \sim 150$	$^{\circ}\text{C}$
Welding temperature, 10s	T_W	245	$^{\circ}\text{C}$

Note: The limit parameter refers to the limit value that cannot be exceeded under any conditions. If this limit is exceeded, it may cause physical damage such as product degradation; At the same time, it cannot be guaranteed that the chip can work normally when approaching the limit parameters.

◆ Block Diagram



◆ Recommended electrical parameters

Project	Symbol	Parameter value	Unit
Power supply voltage	V_{CC}	$4.5 \sim 15$	V
Maximum input voltage	$V_{th}, V_{trig}, V_{cont}, V_{reset}$	V_{CC}	V
Output Current	I_O	± 200	mA

◆ **Electrical characteristics** (TA=25 °C, unless otherwise specified)

Project	Symbol	Condition		Min	Typ	Max	Unit
Operating Voltage	VCC			4.5	-	15	V
operating current	ICC	VCC=5V, RL=∞, VO=VOL		-	3	6	mA
		VCC=5V, RL=∞, VO=VOH		-	1.5	5	mA
		VCC=15V, RL=∞, VO=VOL		-	8	15	mA
		VCC=15V, RL=∞, VO=VOH		-	6	13	mA
Control terminal voltage	VCL	VCC=15V		-	10.0	11	V
		VCC=5V		-	3.3	4	V
Threshold voltage terminal voltage	VTH	VCC=15V		-	10.0	11.2	V
		VCC=5V		-	3.3	4.2	V
Threshold voltage and current	ITH*note1	VCC=15V, VTH=0V		-	-	250	nA
Trigger terminal voltage	VTRIG	VCC=15V		-	5.0	5.6	V
		VCC=5V		-	1.6	2.2	V
Trigger terminal current	ITRIG	VCC=15V, VTRIG=0V		-	-	2	μA
Reset terminal high voltage	VRESETH	VCC=5V		1.5	-	VCC	V
Low voltage at reset terminal	VRESETL	VCC=5V		GND	-	0.5	V
Reset terminal current	IRESET	VRESET=0.4V, VCC=15V		-	0.13	0.4	mA
		VRESET=0V, VCC=15V		-	0.3	1.5	VmA
Output low voltage	VOL	VCC=15V, IL=-5mA		-	0.02	0.25	V
		VCC=15V, IL=-50mA		-	0.04	0.75	
		VCC=15V, IL=-100mA		-	2.0	2.5	
		VCC=15V, IL=-200mA		-	2.8	-	
		VCC=5V, IL=-5mA		-	0.08	0.35	
		VCC=5V, IL=-8mA		-	0.15	0.4	
Output high voltage	VOH	VCC=15V, IL=-100mA		12.75	13.3	-	V
		VCC=15V, IL=-200mA		-	12.2	-	
		VCC=5V, IL=-100mA		2.75	3.3	-	
Close the leakage current of the discharge tube	Idis (off)	VO=VOH, Vdis=10V		-	-	100	nA
Discharge tube saturation voltage	Vdis (sat)	VO=VOL	VCC=15V, Iids=15mA	-	140	480	mV
			VCC=5V, Iids=4.5mA	-	100	200	
Output rising edge time	tR	CL=15pF		-	80	3000	ns
Output falling edge time	tF	CL=15pF		-	50	300	ns

timing error (Monostable state)	TS ^{*note2}	R _A =2kΩ to 100kΩ C=0.1μF	V _{CC} =15V, initial error	-	1	-	%
	T _v		Drift with power supply voltage (4.5~15V)	-	0.1	-	%/V
	T _t		V _{CC} =15V, Drift with temperature (0~60°C)	-	150	-	ppm°C
timing error (Nonsteady state)	TS ^{*note2}	R _A , R _B =1kΩ To 100kΩ C=0.1μF	V _{CC} =15V, initial error	-	1	-	%
	T _v		Drift with power supply voltage (4.5~15V)	-	0.1	-	%/V
	T _t		V _{CC} =15V, Drift with temperature (0~60°C)	-	150	-	ppm°C

Notes:

At V_{CC}=15V, the maximum value of R_A+R_B is 10M Ω; At V_{CC}=5V, the maximum value of R_A+R_B is 3.4M Ω.

2. Timing error is defined as the difference between the measured value and the average value of the random sample. Meanwhile, timing errors are affected by errors in external capacitors and resistors.

◆ Typical application routes

Monostable state:

In monostable mode, when the input level reaches $1/3V_{CC}$, the circuit triggers the output high level and maintains $t=1.1 \cdot R_A \cdot C$ time before the output becomes low level. Within time t , regardless of the input level, the output state is not affected. The circuit and waveform are shown in Figures 3 and 4.

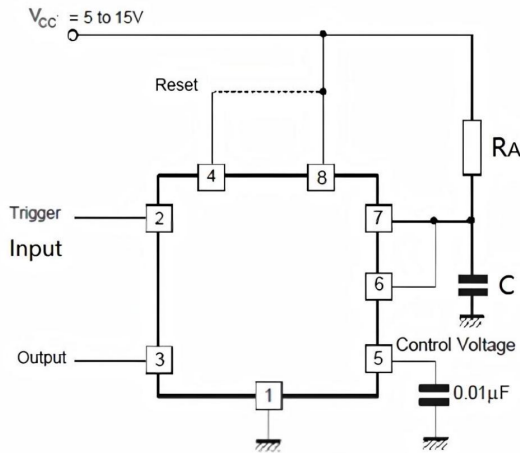


Figure 3 Single Steady State Circuit

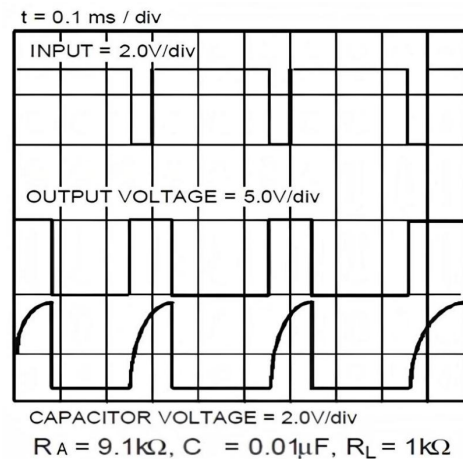


Figure 4 Single Steady State Waveform Diagram

Unstable state:

In non steady state mode, the circuit will automatically trigger and output a square wave multi harmonic oscillator. Its output square wave frequency and duty cycle can be adjusted by R_A , R_B , and C sizes. The triggering mode, charging and discharging time, and frequency are independent of the power supply voltage. The circuit and waveform are shown in Figures 5 and 6.

$$\text{Output high-level pulse width } t_h = 0.693 \cdot (R_A + R_B) \cdot C;$$

$$\text{Low level pulse width } t_l = 0.693 \cdot R_B \cdot C;$$

$$T = t_h + t_l = 0.693(R_A + 2R_B)C;$$

$$\text{Frequency } f = 1/T = 1.44 / (R_A \cdot C + 2R_B \cdot C); \text{ Duty cycle } D = t_h / T = R_B / (R_A + 2R_B)$$

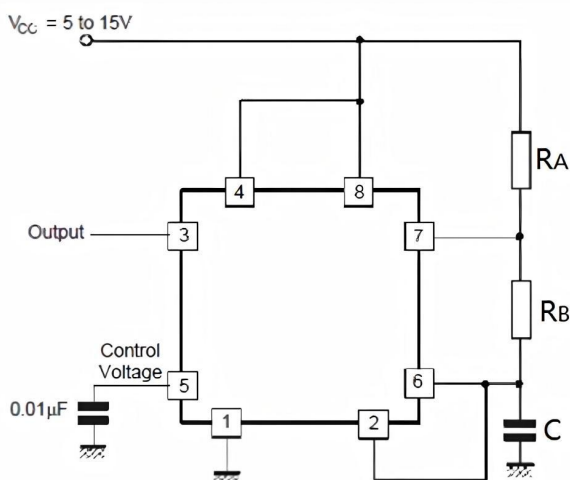


Figure 5, Non steady state Circuit

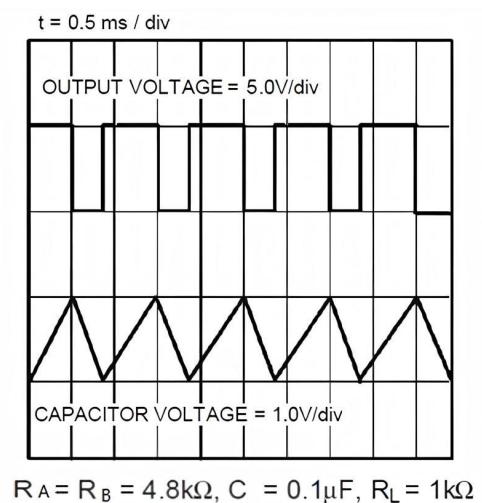


Figure 6, Non steady state waveform diagram

Pulse width modulation:

When the timer is connected in monostable mode and triggered by a continuous pulse train applied to pin 2, the output pulse width can be modulated by the signal applied to pin 5. Refer to Figures 7 and 8.

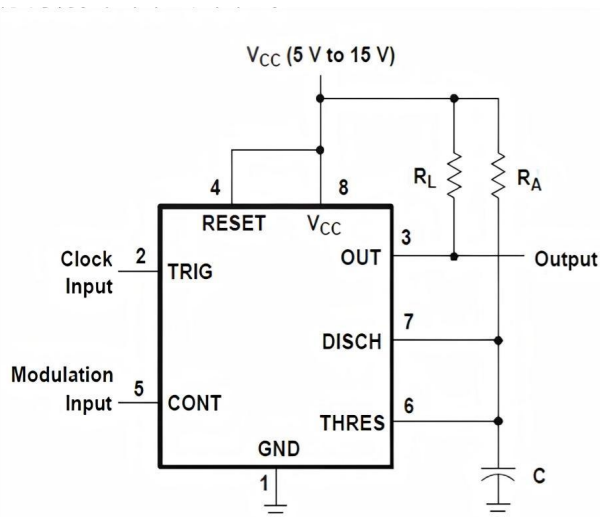


Figure 7, Pulse Width Modulation Circuit

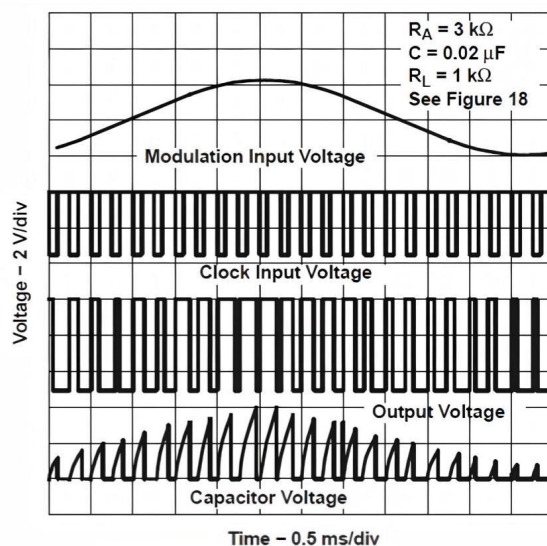


Figure 8, waveform diagram of pulse width modulation circuit

Pulse position modulation:

When the timer is connected in the manner shown in Figure 9, the output pulse position can be modulated by the signal applied to pin 5. Refer to Figures 9 and 10.

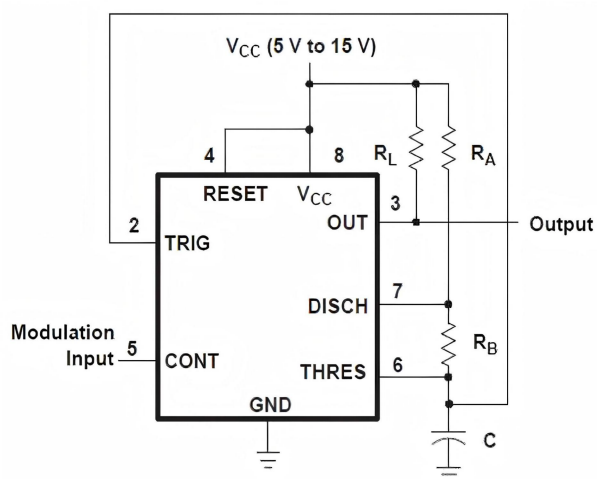


Figure 9, Pulse Width Position Modulation Circuit

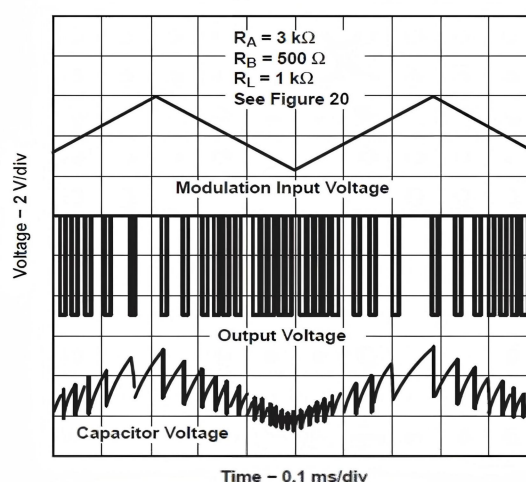
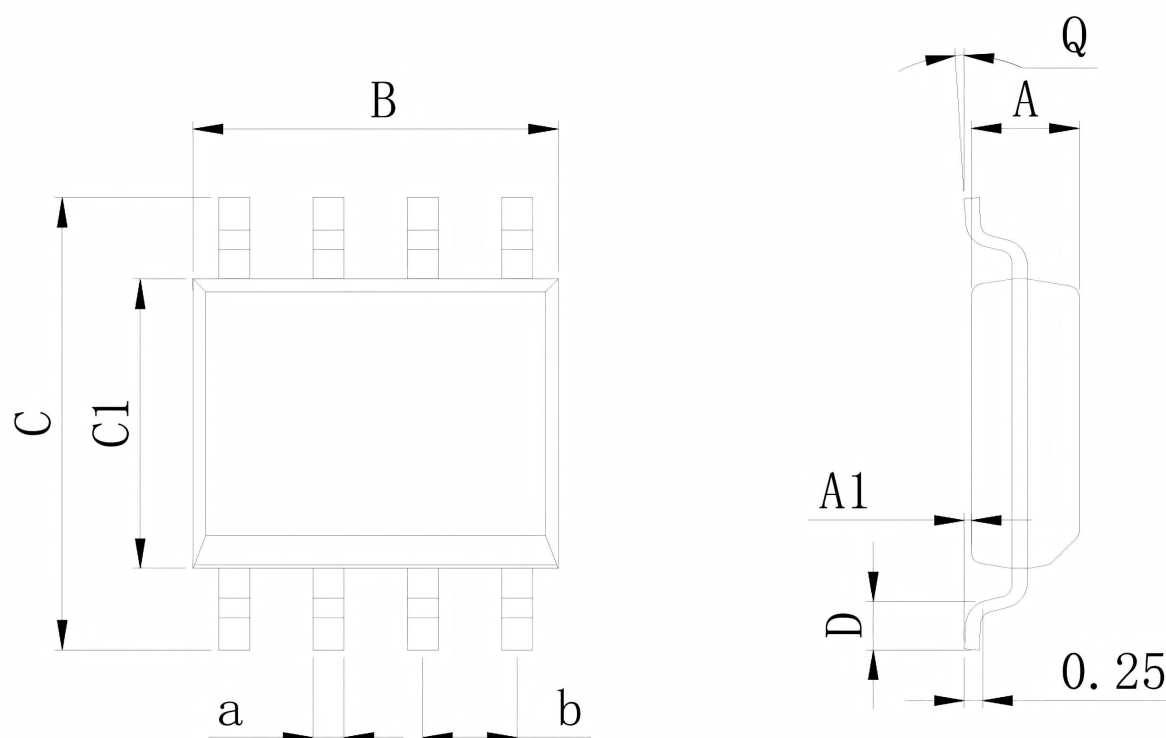


Figure 10, waveform diagram of pulse width position modulation circuit

◆ **Package size diagram**

SOP8(150mil)



Dimensions In Millimeters(SOP-8)									
Symnol:	A	A1	B	C	C1	D	Q	a	b
Min:	1.35	0.05	4.90	5.80	3.80	0.40	0°	0.35	1.27 BSC
Max:	1.55	0.20	5.10	6.20	4.00	0.80	8°	0.45	

◆ Attention

- AOTE implements dynamic technical updates. Specifications are subject to change. Refer to the official website for the latest version.
- Users must strictly adhere to specified conditions. Failures caused by misuse (overload, high temperature, incompatible circuits) are excluded from warranty.
- Contact technical support for customized validation in critical applications (medical devices, industrial control).
- This document is valid until December 31, 2026. Updates will be notified on the official website.
- For further clarification on technical specifications or application solutions, please contact us through official channels: