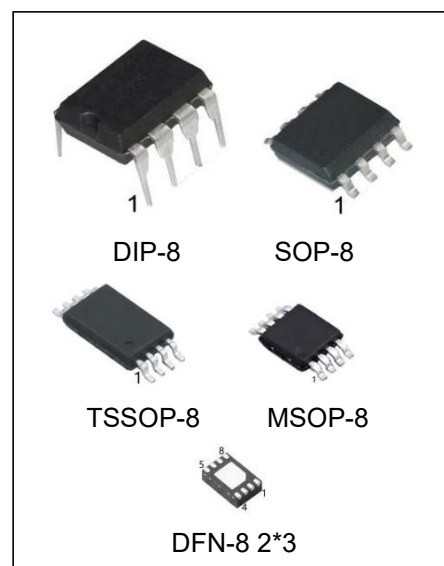


## 512-Kbit I<sup>2</sup>C-compatible Serial EEPROM

### Features

- Supply Voltage Range: 1.7V to 5.5V
- 2-wire Serial Interface I<sup>2</sup>C Compatible
  - 400 kHz and High Speed 1MHz Transfer Rate Compatibility
- Byte and Page (up to 128 Bytes) Write Mode
  - Partial Page Write Allowed
- Self-timed Write Cycle (3ms Maximum)
- Hardware Write Protection on the Whole Memory Array
- Additional 128-byte Write Lockable Page and 128-bit Unique ID
- Schmitt Trigger, Filtered Inputs for Noise Suppression
- Low Operating Current
  - Write Current: 1mA (Maximum)
  - Read Current: 0.5mA (Maximum)
  - Standby Current: 1μA (Maximum)
- High Reliability
  - Endurance: 2,000,000 Write Cycles
  - Data Retention: 200 Years
  - ESD Protection (Human Body Model): 6000V
- Operating Temperature Range: -40°C to +105°C
- Green Packaging Options (RoHS Compliant, Pb/Halogen-free)
  - SOP, TSSOP, DFN, MSOP, DIP.



### Ordering Information

| DEVICE          | Package Type | MARKING  | Packing | Packing Qty  |
|-----------------|--------------|----------|---------|--------------|
| AT24LC512CN     | DIP-8        | 24LC512C | TUBE    | 2000pcs/box  |
| AT24LC512CM/TR  | SOP-8        | 24LC512C | REEL    | 2500pcs/reel |
| AT24LC512CMM/TR | MSOP-8       | LC512C   | REEL    | 3000pcs/reel |
| AT24LC512CMT/TR | TSSOP-8      | LC512C   | REEL    | 5000pcs/reel |
| AT24LC512CDQ/TR | DFN-8 2*3    | LC512C   | REEL    | 4000pcs/reel |

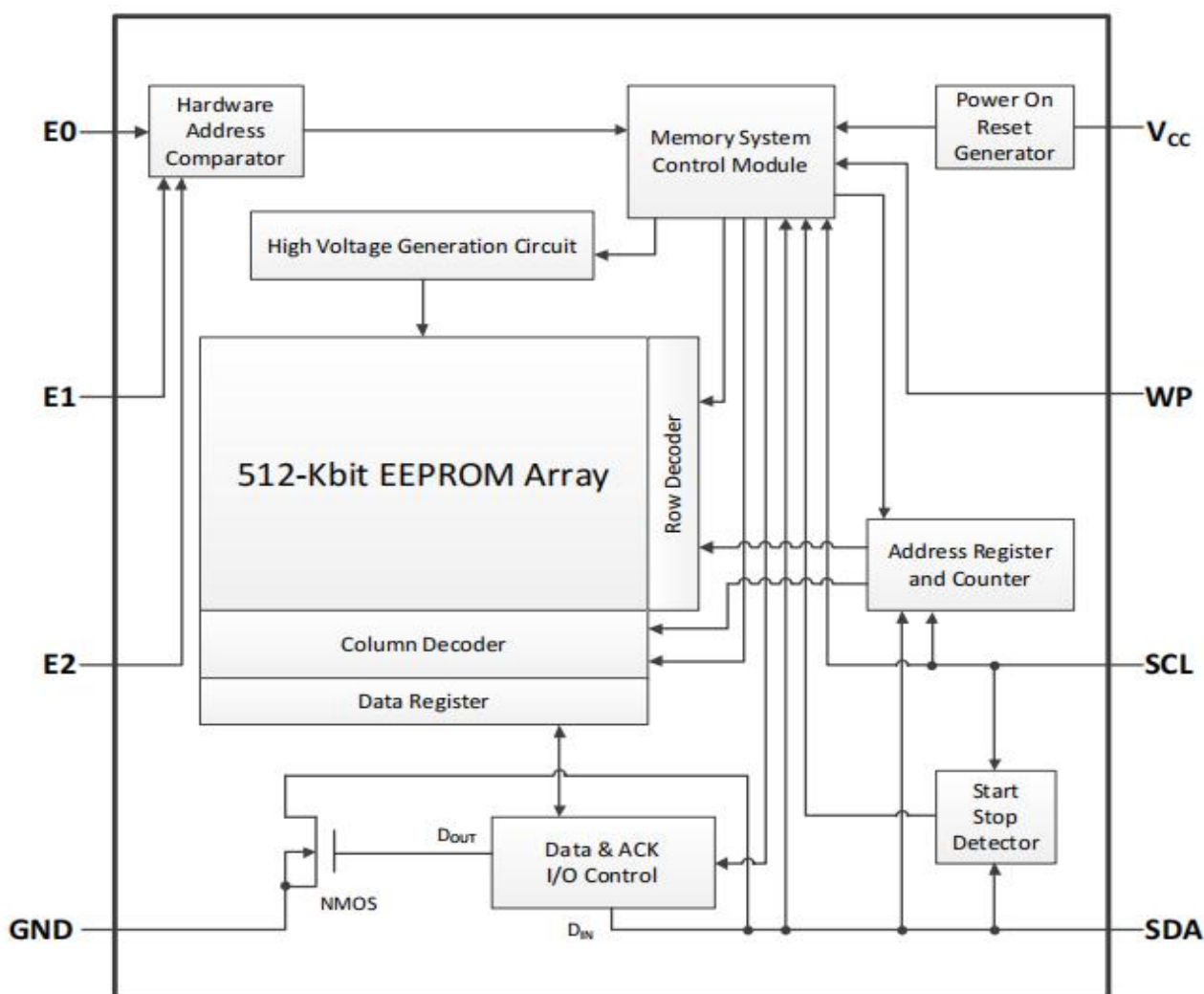
## Description

The AT24LC512C is a 512-Kbit I<sup>2</sup>C-compatible Serial EEPROM (Electrically Erasable Programmable Memory) device. The device is designed to operate in a supply voltage range of 1.7V to 5.5V, with a maximum of 1MHz transfer rate. The operating temperature range is from -40°C to +105°C. The device incorporates a Write Protection pin used for hardware Write Protection on the whole memory array.

The Serial EEPROM memory is organized as 512 pages of 128 bytes each, totaling 65536\*8 bits. The device offers an additional 128-byte Identification Page for users to store sensitive application parameters. This page can be permanently locked in Read-only mode after the application data is written into the Identification Page. The AT24LC512C also offers a separate memory block containing a factory programmed 128-bit Unique ID. This block is in Read-only mode and can be accessed to by sending a specific Read command.

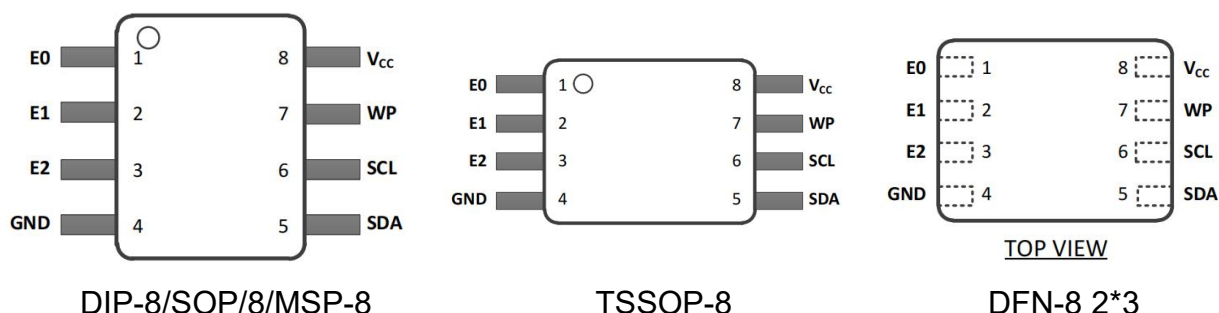
The AT24LC512C is delivered in Lead-free green packages: SOP, TSSOP , DIP ,MSOP and DFN

## Functional Block Diagram



## Pin Descriptions and Pin Configuration

### Pin Configuration



### Pin Descriptions

| Symbol                              | Type         | Name and Function                                                                                                                                                                                                                                                                                                                                                                                                                                                     |
|-------------------------------------|--------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>E0</b><br><b>E1</b><br><b>E2</b> | Input        | <b>Device Address Inputs:</b> The E0, E1, and E2 pins are device address inputs for compatibility with other 2-wire Serial EEPROM devices. These pins can be directly connected to V <sub>CC</sub> or GND in any combination, allowing up to eight devices on a single bus system.<br>If these pins are left floating, the E0, E1, and E2 pins will be internally pulled down to GND.                                                                                 |
| <b>SDA</b>                          | Input/Output | <b>Serial Data:</b> The SDA pin is an open-drain bidirectional input/output pin used to serially transfer data to and from the device.                                                                                                                                                                                                                                                                                                                                |
| <b>SCL</b>                          | Input        | <b>Serial Clock:</b> The SCL pin is used to provide a clock to the device and is used to control the flow of data to and from the device. Command and input data present on the SDA pin is always latched in on the rising edge of SCL, while output data on the SDA pin is always clocked out on the falling edge of SCL.                                                                                                                                            |
| <b>V<sub>CC</sub></b>               | Power        | <b>Device Power Supply:</b> The V <sub>CC</sub> pin is used to supply the source voltage to the device. Operations at invalid V <sub>CC</sub> voltages may produce spurious results and should not be attempted.                                                                                                                                                                                                                                                      |
| <b>GND</b>                          | Power        | <b>Ground:</b> The ground reference for the power supply. GND should be connected to the system ground.                                                                                                                                                                                                                                                                                                                                                               |
| <b>WP</b>                           | Input        | <b>Write Protection:</b> The WP pin is used to write protect the entire contents of the memory. When the WP pin is connected to Power Supply, the entire memory array becomes Write-protected, that is, the device becomes Read-only. When the WP pin is connected to Ground or left floating, Write operations are enabled.<br>When the WP pin is driven high, the device address byte and the word address bytes are acknowledged, data bytes are not acknowledged. |

## Device Communication

The AT24LC512C operates as a slave device and utilizes a 2-wire serial interface to communicate with the Master. The Master initiates and controls all Read and Write operations to the slave devices on the serial bus, and both the Master and the slave devices can transmit and receive data on the bus.

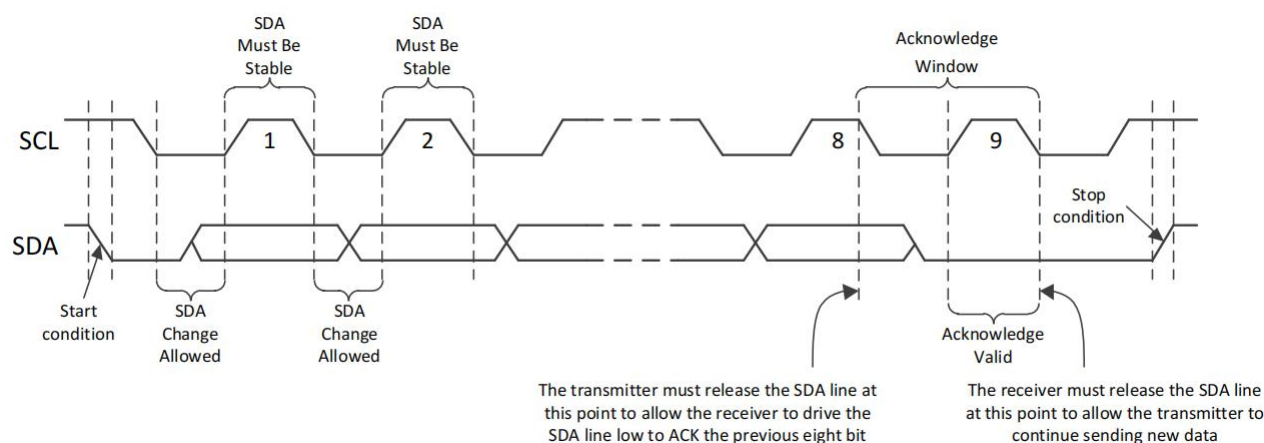
The serial interface is comprised of just two signal lines: the Serial Clock (SCL) and the Serial Data (SDA). Data is always latched into the AT24LC512C on the rising edge of SCL and is always output from the device on the falling edge of SCL. Both the SCL pin and SDA pin incorporate integrated spike suppression filters and Schmitt Triggers to minimize the effects of input spikes and bus noise.

All command and data information is transferred with the Most Significant Bit (MSB) first. During the bus communication, one data bit is transmitted every clock cycle, and after eight bits of data has been transferred, the receiving device must respond with an acknowledge or a no-acknowledge response bit during a ninth clock cycle generated by the Master. Therefore, nine clock cycles are required for every one byte of data transferred. There is no unused clock cycle during any Read or Write operation, so there must not be any interruptions or breaks during the data stream.

During data transfers, data on the SDA pin must only change while SCL is low, and the data must remain stable while SCL is high. If data on the SDA pin changes while SCL is high, then either a Start or a Stop condition will occur. The number of data bytes transferred between a Start and a Stop condition is not limited and is determined by the Master.

### Start Condition

A Start condition occurs when there is a high-to-low transition on the SDA pin while the SCL pin is stable in Logic 1 state. The Start condition must precede any command as the Master uses a Start condition to initiate any data transfer sequence (see Figure 1). The AT24LC512C will continuously monitor the SDA and SCL pins for a Start condition, and the device will not respond unless one is given.



**Figure 1 Start, Stop, and ACK**

### Stop Condition

A Stop condition occurs when there is a low-to-high transition on the SDA pin while the SCL pin is stable in Logic 1 state (see Figure 1). A stop condition terminates communication between the AT24LC512C and the Master. A Stop condition at the end of a Write command triggers the EEPROM internal write cycle. Otherwise, the AT24LC512C subsequently returns to Standby mode after receiving a Stop condition.

## Acknowledge (ACK)

After each byte of data is received, the AT24LC512C should acknowledge to the Master that it has received the data byte successfully. This is accomplished by the Master first releasing the SDA line and providing the ACK/NACK clock cycle (a ninth clock cycle for every byte). During the ACK/NACK clock cycle, the AT24LC512C must output Logic 0 as ACK for the entire clock cycle so that the SDA line must be stable in Logic 0 state during the entire high period of the clock cycle (see Figure 1).

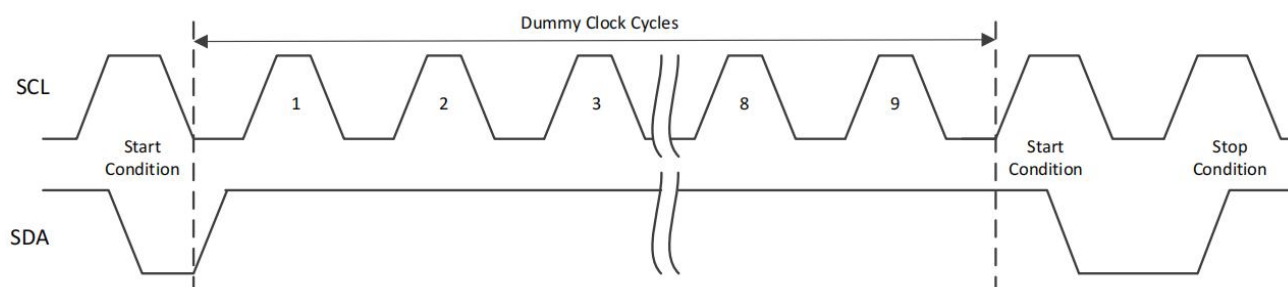
## Standby Mode

The features a low-power Standby mode which is enabled:

- (1) Upon power-up;
- (2) After the receipt of a Stop condition in Read operation;
- (3) The completion of any internal operations.

## Software Reset

After an interruption in protocol, power loss, or system reset, any 2-wire part can be reset by following these steps: (1) Create a Start condition; (2) Clock nine cycles; (3) Create another Start condition followed by a Stop condition (see Figure 2).



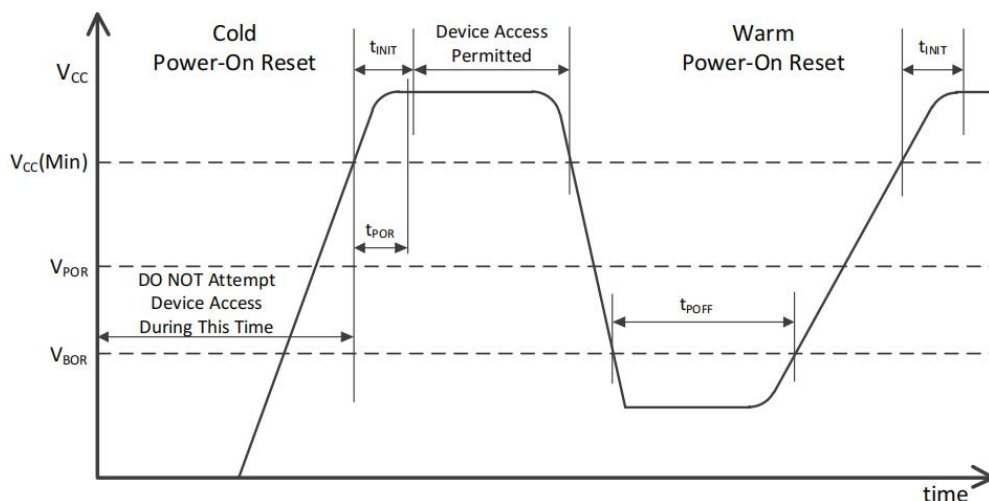
**Figure 2 2-wire Software Reset**

## Device Reset and Initialization

The AT24LC512C incorporates a Power-On Reset (POR) circuit to prevent inadvertent operations during power-up. On a cold power-up, the device does not respond to any instructions until the supply voltage reaches the internal power-on reset threshold voltage ( $V_{POR}$ ). The supply voltage must rise continuously between  $V_{POR}$  and  $V_{CC}(\text{Min})$  without any ring back to ensure a proper power-up. Once the supply voltage passes  $V_{POR}$ , the device is reset and enters Standby mode. However, no protocol should be issued to the device until a valid and stable supply voltage is applied for the time specified by the  $t_{INIT}$  parameter. The supply voltage must remain stable and valid until the end of the protocol transmission, and for a Write instruction, until the end of the internal write cycle (see Figure 3).

This POR behavior is bi-directional. It protects the AT24LC512C against brown-out failure caused by a temporary loss of power. In a similar way, as soon as the supply voltage drops below the internal brown-out reset threshold voltage ( $V_{BOR}$ ), the device is reset and stops responding to any instructions (see Figure 3). The  $V_{BOR}$  level is set below the  $V_{POR}$  level.

Parameters related to power-up and power-down conditions are listed in Table 1.



**Figure 3 Power-up and Power-down Timing**

**Table 1 Power-up and Power-down Conditions**

| Symbol     | Parameter                           | Min  | Max  | Unit |
|------------|-------------------------------------|------|------|------|
| $t_{POR}$  | Power-On Reset Time                 | -    | 10.0 | ms   |
| $V_{POR}$  | Power-On Reset Voltage              | -    | 1.5  | V    |
| $V_{BOR}$  | Brown-out Reset Voltage             | 0.8  | -    | V    |
| $t_{INIT}$ | Time from Power-On to First Command | 10.0 | -    | ms   |
| $t_{POFF}$ | Warm Power Cycle Off Time           | 1.0  | -    | ms   |

## Data Security

The AT24LC512C incorporates a hardware data protection feature that allows the user to write protect the whole memory array (and Identification Page) when the WP pin is connected directly to  $V_{CC}$ .

## Device Addressing

The AT24LC512C requires a 7-bit device address and a Read/Write select bit following a Start condition from the Master to initiate communication with the Serial EEPROM. The device address byte is comprised of a 4-bit device type identifier followed by three device address bits (E2, E1, and E0) and a R/W select bit and is clocked by the Master on the SDA pin with the most significant bit (bit 7) first.

The AT24LC512C will respond to two unique device type identifiers. The device type identifier of '1010' is necessary to select the device memory for normal Read or Write operation. The device type identifier of '1011' is used to select the Identification Page for Read or Write/Lock operation. The device type identifier of '1011' is also used for Read Unique ID operation (see Table 2 ).

The software device address bits (E2, E1 and E0) must match their corresponding hard-wired device address inputs (E2, E1 and E0), allowing up to eight devices on the bus at the same time. The eighth bit of the address byte is the R/W operation selection bit. A Read operation is selected if this bit is Logic 1, and a Write operation is selected if this bit is Logic 0. Upon a compare of the device address byte, the AT24LC512C outputs an ACK or a NACK during the ninth clock cycle if the compare is true or not true, respectively. The device will return to the low-power Standby mode after a NACK.

Once the AT24LC512C has acknowledged the device address byte, the device waits for the Master to send two word address bytes (first word address byte sent first, followed by the second word address byte) for a certain Read or Write instruction according to Table 3 . The AT24LC512C responds to each address byte with an ACK.

**Table 2 AT24LC512C Device Address Byte**

| Function                                        | Device Type Identifier |       |       |       | Device Address |       |       | Read/Write |
|-------------------------------------------------|------------------------|-------|-------|-------|----------------|-------|-------|------------|
|                                                 | bit 7                  | bit 6 | bit 5 | bit 4 | bit 3          | bit 2 | bit 1 | bit 0      |
| When accessing the 512-Kbit memory array        | 1                      | 0     | 1     | 0     | E2             | E1    | E0    | R/W        |
| When accessing the Identification Page          | 1                      | 0     | 1     | 1     | E2             | E1    | E0    | R/W        |
| When accessing the Lock Identification Page bit | 1                      | 0     | 1     | 1     | E2             | E1    | E0    | 0          |
| When accessing the Unique ID                    | 1                      | 0     | 1     | 1     | E2             | E1    | E0    | 1          |

**Table 3 AT24LC512C Word Address Bits**

| Function                  | First Word Address Byte |        |        |        |        |        |       |       | Second Word Address Byte |       |       |       |       |       |       |       |
|---------------------------|-------------------------|--------|--------|--------|--------|--------|-------|-------|--------------------------|-------|-------|-------|-------|-------|-------|-------|
|                           | bit 15                  | bit 14 | bit 13 | bit 12 | bit 11 | bit 10 | bit 9 | bit 8 | bit 7                    | bit 6 | bit 5 | bit 4 | bit 3 | bit 2 | bit 1 | bit 0 |
| Random Read               | A15 <sup>[1]</sup>      | A14    | A13    | A12    | A11    | A10    | A9    | A8    | A7                       | A6    | A5    | A4    | A3    | A2    | A1    | A0    |
| Byte/Page Write           | A15                     | A14    | A13    | A12    | A11    | A10    | A9    | A8    | A7                       | A6    | A5    | A4    | A3    | A2    | A1    | A0    |
| Read Identification Page  | X <sup>[2]</sup>        | X      | X      | X      | 0      | 0      | 0     | X     | X                        | A6    | A5    | A4    | A3    | A2    | A1    | A0    |
| Write Identification Page | X                       | X      | X      | X      | 0      | 0      | 0     | X     | X                        | A6    | A5    | A4    | A3    | A2    | A1    | A0    |
| Lock Identification Page  | X                       | X      | X      | X      | 0      | 1      | 0     | X     | X                        | X     | X     | X     | X     | X     | X     | X     |
| Read Lock Status          | X                       | X      | X      | X      | 0      | 0      | 0     | X     | X                        | X     | X     | X     | X     | X     | X     | X     |
| Read Unique ID            | X                       | X      | X      | X      | 0      | 0      | 1     | X     | X                        | X     | X     | X     | A3    | A2    | A1    | A0    |

Notes: <sup>[1]</sup> A = Significant address bit.

<sup>[2]</sup> X = Bit is Don't Care.

## Read and Write Operations

### Write Operations

#### Byte Write

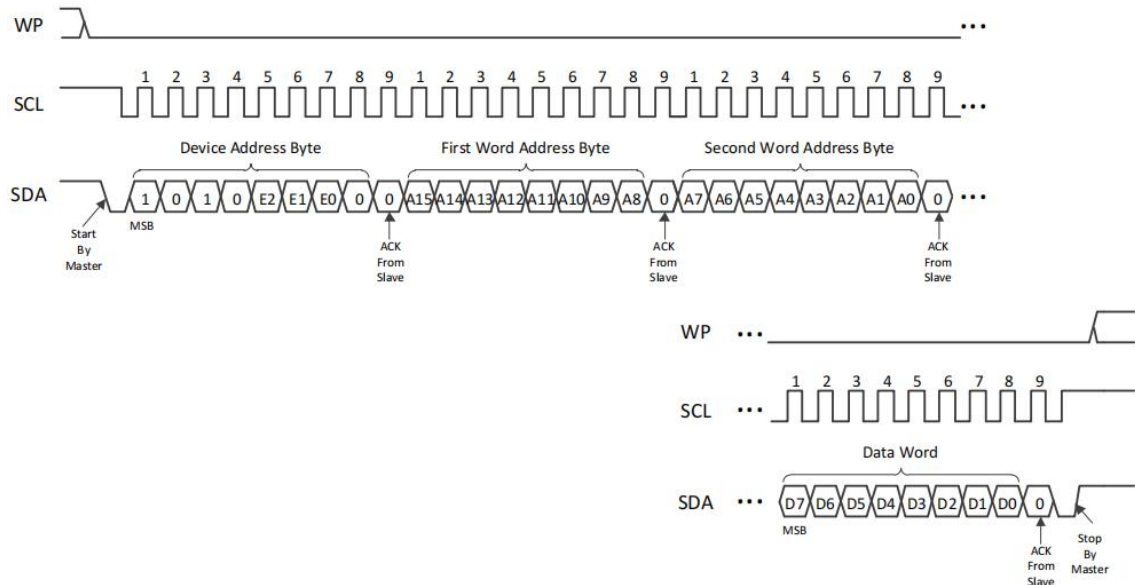
For a Byte Write operation, the Master sends a Start condition followed by the device type identifier of '1010', the device address bits and the R/ $\bar{W}$  select bit set to Logic 0. The AT24LC512C responds with an ACK during the ninth clock cycle and waits for the Master to send two word address bytes (first word address byte and second word address byte). Then the device responds to each word address byte with an ACK. After receiving ACKs from the AT24LC512C, the Master transmits one data byte. If the addressed location has been Write-protected, by WP pin connected to  $V_{CC}$ , the device responds with a NACK, and the location is not modified. If the addressed location is not Write-protected, by WP pin set to GND, the device will respond with an ACK (see Figure 4 and Figure 5 ). The Master ends the Byte Write sequence with a Stop condition during the 10th clock cycle to initiate the internally self-timed write cycle. A Stop condition issued during any other clock cycle during the Write operation will not trigger the internal write cycle.

Once the write cycle begins, the preloaded data word will be programmed in the amount of time not to exceed the  $t_{WR}$  specification (see Figure 8 ). During the time, the Master should wait a fixed time by the  $t_{WR}$  specification, or for time sensitive applications, an ACK polling routine can be implemented. All inputs are ignored by the device during the write cycle and the device will not respond until the write cycle is completed. The Serial EEPROM will increment its internal address counter each time a byte is written.

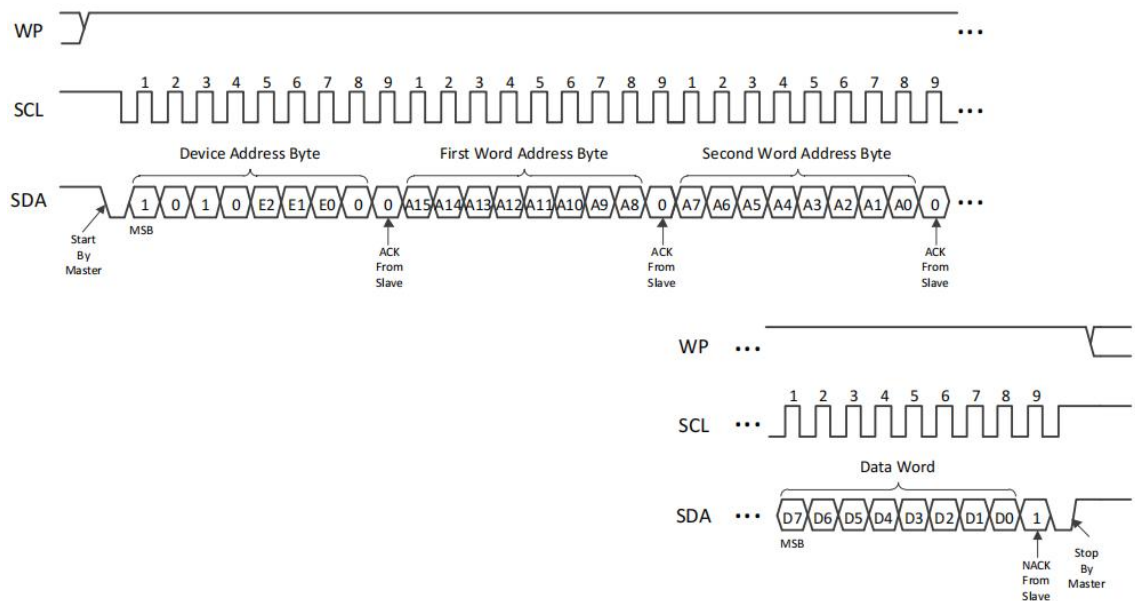
#### Page Write

The 512-Kbit Serial EEPROM is capable of writing up to 128 data bytes at a time by executing the Page Write protocol sequence. A partial or full Page Write operation is initiated the same as a Byte Write operation except that the Master does not send a Stop condition after the first data word is clocked in. Instead, after the device has acknowledged to the first data word, the Master can transmit up to 127 more data words. The device responds with an ACK after each data word is received if the WP pin is set to GND while the device is not acknowledged to each data word and the addressed locations are not modified if the WP pin is connected to  $V_{CC}$  (see Figure 6 and Figure 7 ). After the device acknowledges to the last data word, the Master should terminate the Page Write sequence with a Stop condition to start the internal write cycle. A Stop condition issued at any other clock cycle will not initiate the internally self-timed write cycle and the Write sequence will have to be repeated again. Once the write cycle begins, the data words should be programmed in the amount of time not exceeding the  $t_{WR}$  specification (see Figure 8 ). During this time, the Master should wait a fixed time by the specified  $t_{WR}$  parameter, or for time sensitive applications, an ACK polling routine can be implemented.

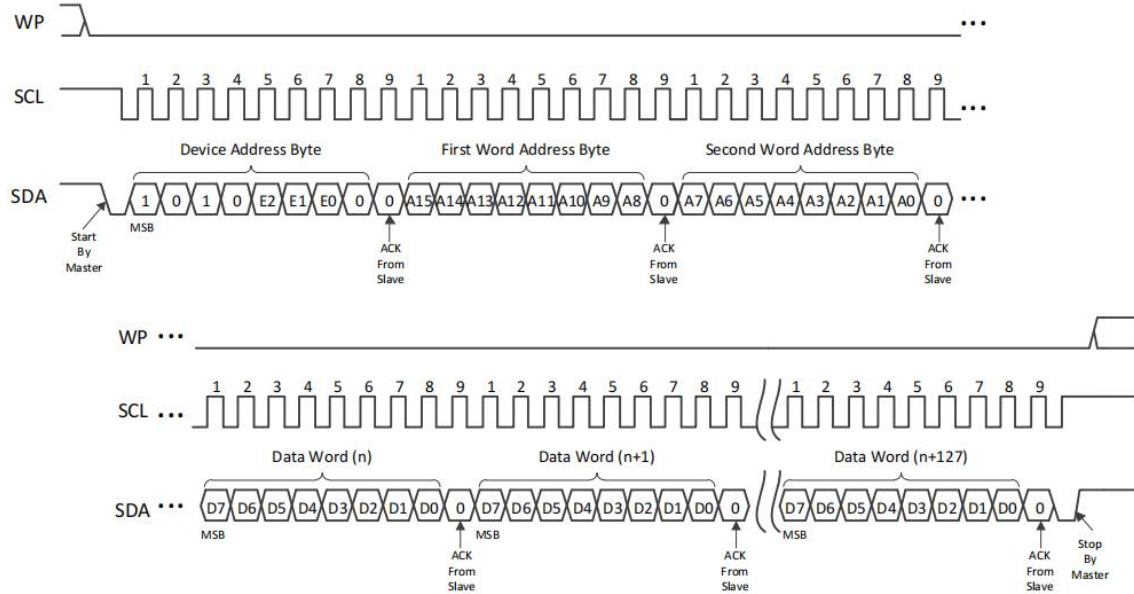
The lower seven bits of the word address are internally incremented following the receipt of each data word. The higher word address bits are not incremented, retaining the memory page row location. When the internally generated word address reaches the page boundary, then the following data word is placed at the beginning of the same page. If more than 128 data words are transmitted to the device, the data word address will roll over and the previous data will be overwritten. The address roll-over during a Write sequence is from the last byte of the current page to the first byte of the same page.



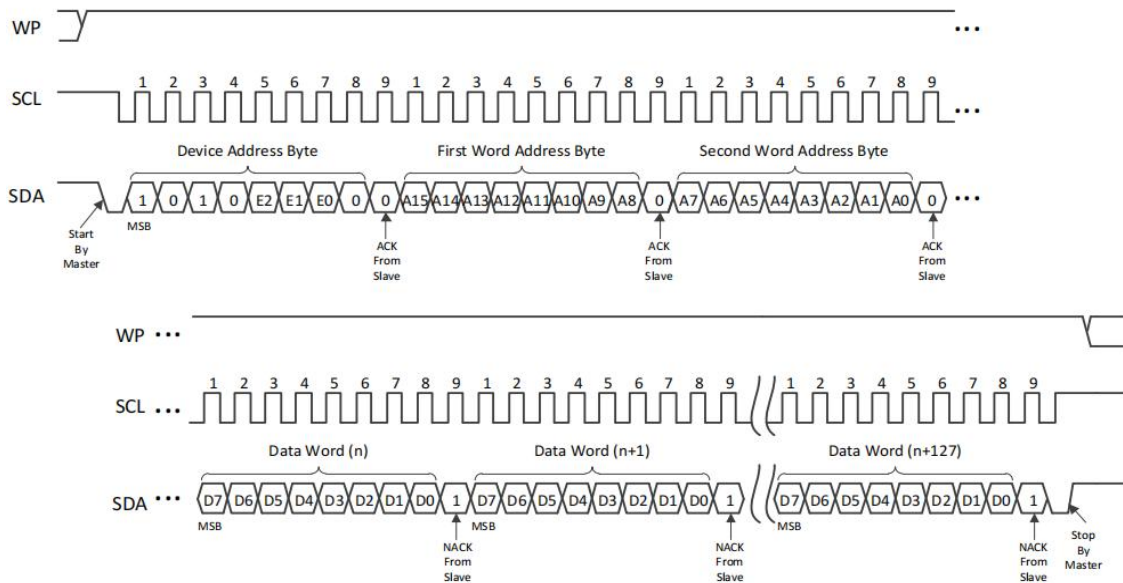
**Figure 4 Byte Write Operation with Write Protection Pin Set to Low**



**Figure 5 Byte Write Operation with Write Protection Pin Set to High**



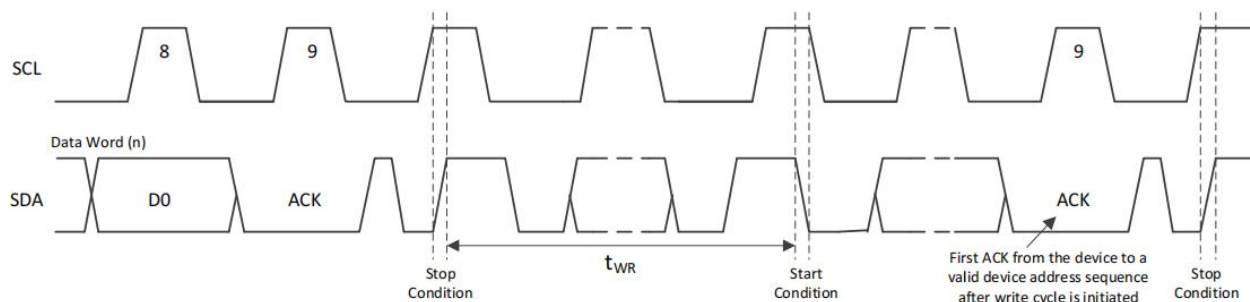
**Figure 6 Page Write Operation with Write Protection Pin Set to Low**



**Figure 7 Page Write Operation with Write Protection Pin Set to High**

### Write Cycle Timing

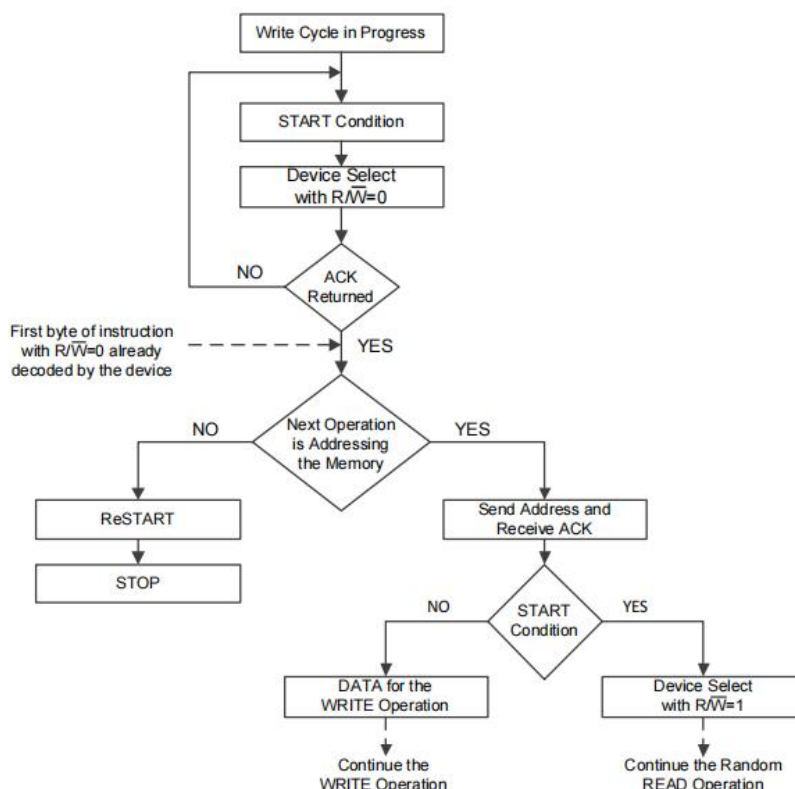
The length of the self-timed write cycle, or  $t_{WR}$ , is defined as the amount of time from a valid Stop condition that begins the internal write sequence to the Start condition of the first device address byte sent to the AT24LC512C that it subsequently responds to with an ACK (see Figure 8).



**Figure 8 Write Cycle Timing**

### Acknowledge (ACK) Polling

An ACK polling routine can be implemented to optimize time sensitive applications that would not prefer to wait the fixed maximum write cycle time but would prefer to know immediately when the Serial EEPROM write cycle has completed to start a subsequent operation. Once the internally self-timed write cycle has started, the device inputs are disabled and ACK polling can be initiated. An ACK polling routine involves sending a valid Start condition followed by the device address byte. While the write cycle is in progress, the device will not respond with an ACK, indicating the device is busy writing data. Once completed, the device returns an ACK and the next device operation can be started (see Figure 9 ).



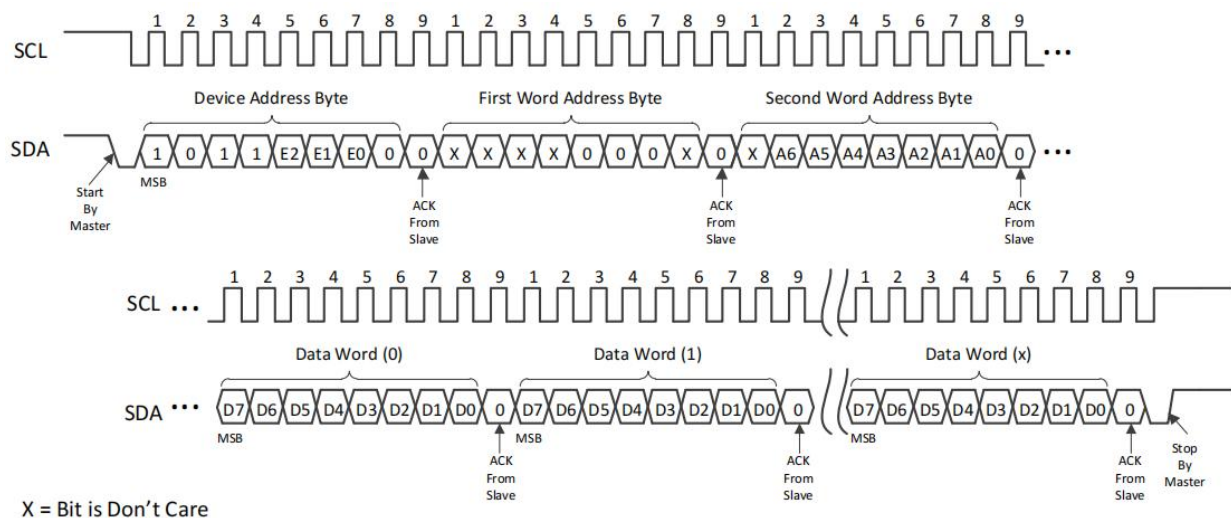
**Figure 9 Acknowledge Polling Flow Chart**

### Write Identification Page

The AT24LC512C offers a 128-byte Identification Page (ID Page) in addition to the 512-Kbit memory array for storage of specific application data. This Identification Page can be written and permanently locked in Read-only mode after the data is written into this Page. The Identification Page is written by issuing the Write Identification Page instruction (see Figure 10 ), which is similar to Page Write, except that:

- The device type identifier is defined as '1011';
- The word address bits A11:A9 must be '000', bits A15:A12 and A8:A7 are Don't Care;
- The word address bits A6:A0 define the byte locations inside the ID Page (see Table 3 ).

If the Identification Page has been locked, the data bytes transferred during the Write Identification Page instruction will not be acknowledged.



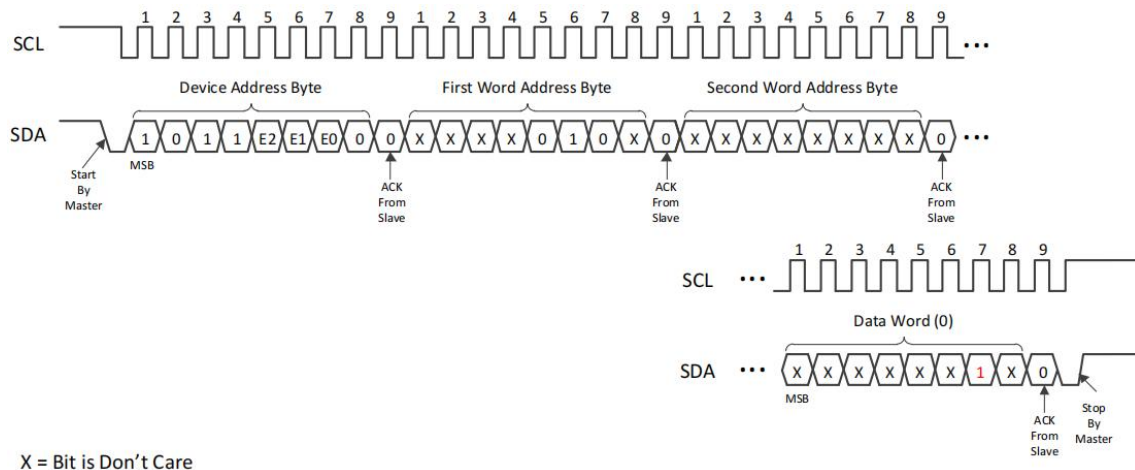
**Figure 10 Write Identification Page**

### Lock Identification Page

The Lock Identification Page (Lock ID) instruction permanently locks the Identification Page in Read-only mode. The Lock ID instruction is similar to Byte Write, except the following specific conditions:

- The device type identifier is defined as '1011';
- The word address bits A11:A9 must be '010' and other word address bits are Don't Care;
- The data byte must be equal to the binary value xxxx\_xx1x, where x is Don't Care (see Figure 11 ).

Once a valid Lock ID instruction has been executed, if another Lock ID instruction is issued, the device will respond with a NACK to the data byte.



**Figure 11 Lock Identification Page**

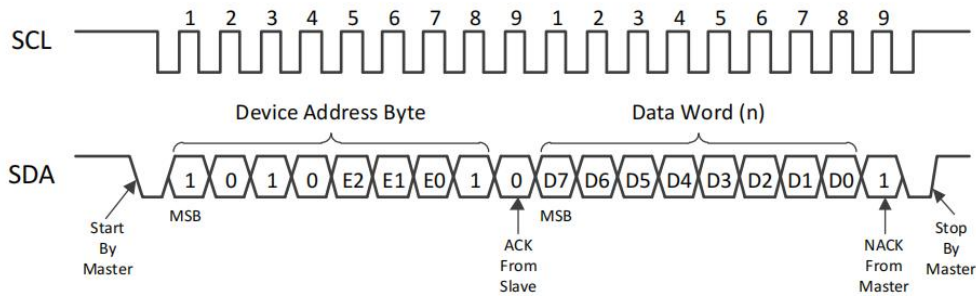
## Read Operations

All Read operations are initiated by the Master transmitting a Start condition, a device type identifier of '1010' or '1011', three software device address bits (E2, E1, E0) that match corresponding hard-wired address pins (E2, E1, E0), and the R/ $\bar{W}$  select bit with Logic 1 state. In the following clock cycle, the AT24LC512C should respond with an ACK. The subsequent protocol depends on the type of Read operation desired. There are three Read operations for memory array: Current Address Read, Random Address Read, and Sequential Read with the device type identifier of '1010'; three Read operations for Identification Page and Unique ID: Read Identification Page, Read the Lock Status, and Read Unique ID with the device type identifier of '1011'. Read operations are performed independently of the state of the WP pin connection.

### Current Address Read

For a Current Address Read operation, the Master sends a Start condition followed by transmitting the device address byte with the R/ $\bar{W}$  bit set to Logic 1 (see Figure 12). The AT24LC512C should respond with an ACK and then serially transmits the data word addressed by the internal address counter. This address maintained by the internal address counter is the last address accessed during the last Read or Write operation. The counter is then incremented by one and the address will stay valid between operations as long as power to the device is supplied. The address roll-over during a Read operation is from the last byte of the last page to the first byte of the first page. To end the command, the Master responds with a NACK followed by a Stop condition.

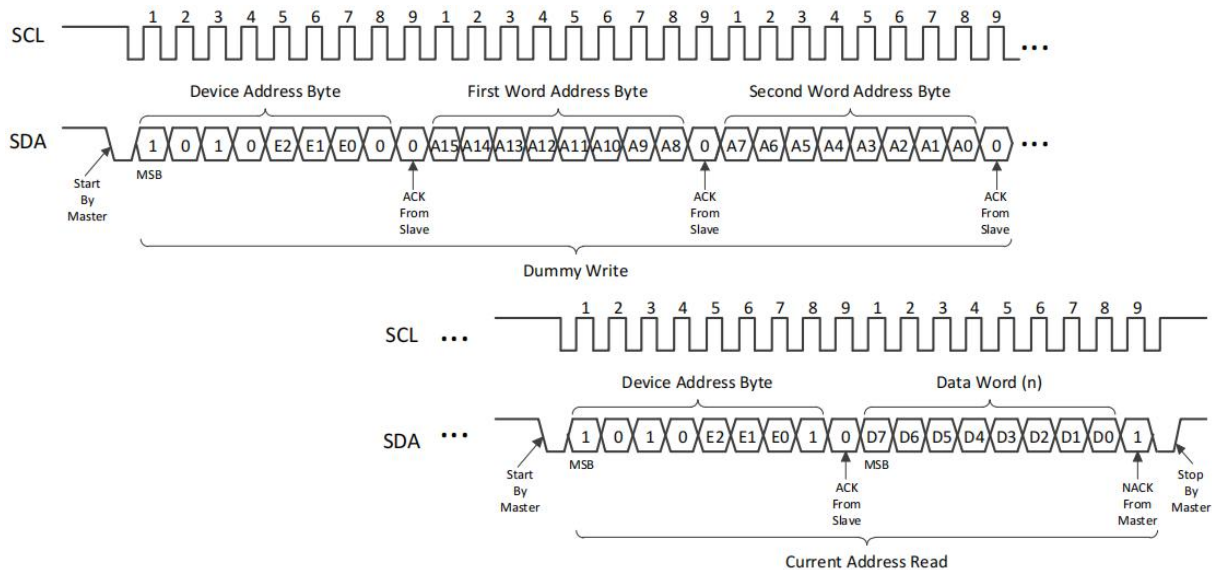
Note that the internal address counter value is defined by instructions accessing the 512-Kbit memory or the Identification Page or the Unique ID. For example, when accessing the ID Page, the counter value is loaded with the byte location in the ID Page. Therefore the next Current Address Read in the memory uses this new address counter value. When accessing the memory, it is recommended to always use the Random Read instruction instead of the Current Address Read instruction.



**Figure 12 Current Address Read**

### Random Read

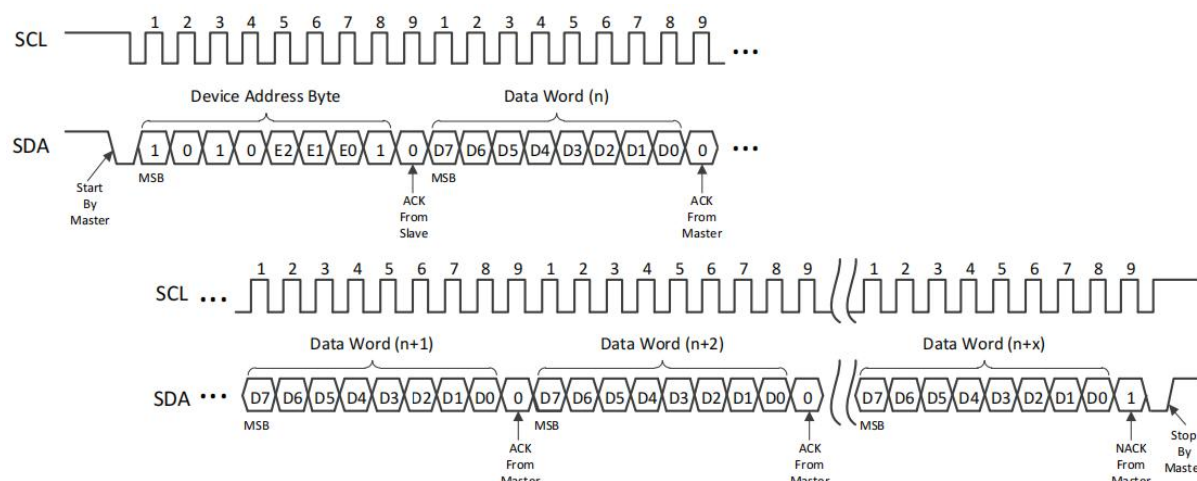
A Random Read operation allows the Master to access any memory location in a random manner and requires a dummy write sequence to preload the starting data word address. To perform a Random Read, the device address byte and the word address bytes are transmitted to the AT24LC512C as part of the dummy write sequence (see Figure 13 ). Once the device address byte and word address bytes are clocked in and acknowledged by the AT24LC512C, the Master must generate another Start condition. The Master initiates a Current Address Read by sending another device address byte with the  $R/\bar{W}$  bit set to Logic 1. The AT24LC512C responds with an ACK to the device address byte and serially clocks out the first data word and increments its internal address counter. The device will continue to transmit sequential data words as long as the Master continues to acknowledge each data word. To end the sequence, the Master responds with a NACK followed by a Stop condition.



**Figure 13 Random Read**

## Sequential Read

A Sequential Read operation is initiated in the same way as either a Current Address Read or a Random Read, except that after the AT24LC512C transmitting the first data word, the Master responds with an ACK instead of a NACK. As long as the AT24LC512C receives an ACK, it will continue to increment the data word address and serially clock out the sequential data words (see Figure 14 ). When the internal address counter is at the last byte of the last page, the word address will roll over to the beginning of the memory array and the Sequential Read operation will continue. The Sequential Read operation is terminated by the Master responding with a NACK followed by a Stop condition.



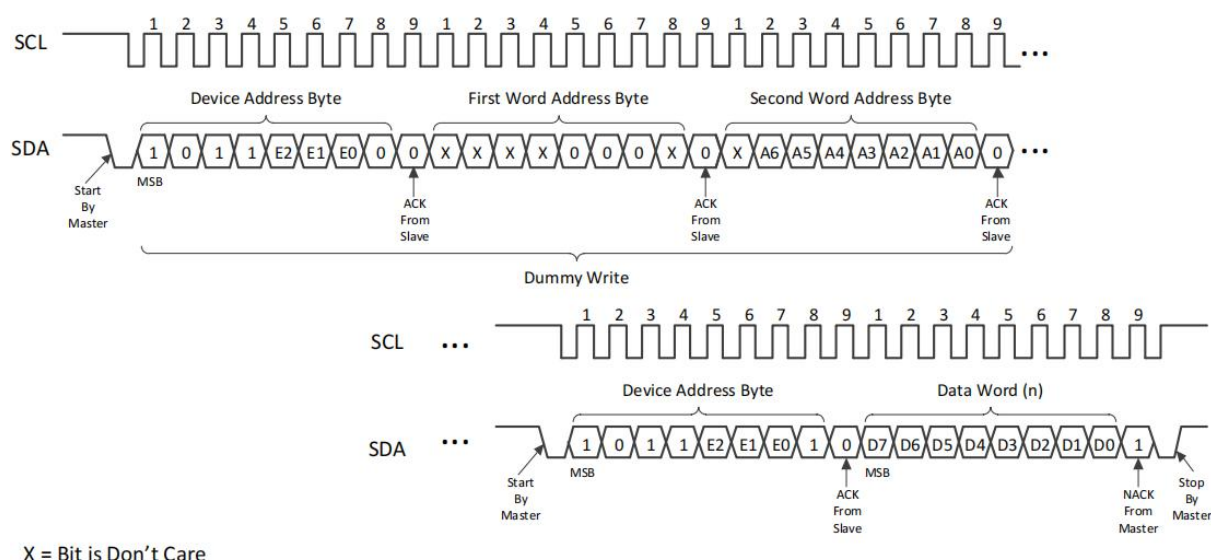
**Figure 14 Sequential Read**

## Read Identification Page

The Identification Page can be read by issuing a Read Identification Page instruction. This instruction uses the same protocol and format as Random Read, except that:

- The device type identifier is defined as '1011';
- The word address bits A11:A9 must be '000', bits A15:A12 and A8:A7 are Don't Care;
- The word address bits A6:A0 define the byte locations inside the ID Page (see Table 3 ).

When the end of Identification Page is reached, the word address will roll over to the beginning of the Identification Page. The Read Identification Page operation is terminated by the Master responding with a NACK followed by a Stop condition (see Figure 15 ).



**Figure 15 Read Identification Page**

### Read Lock Status

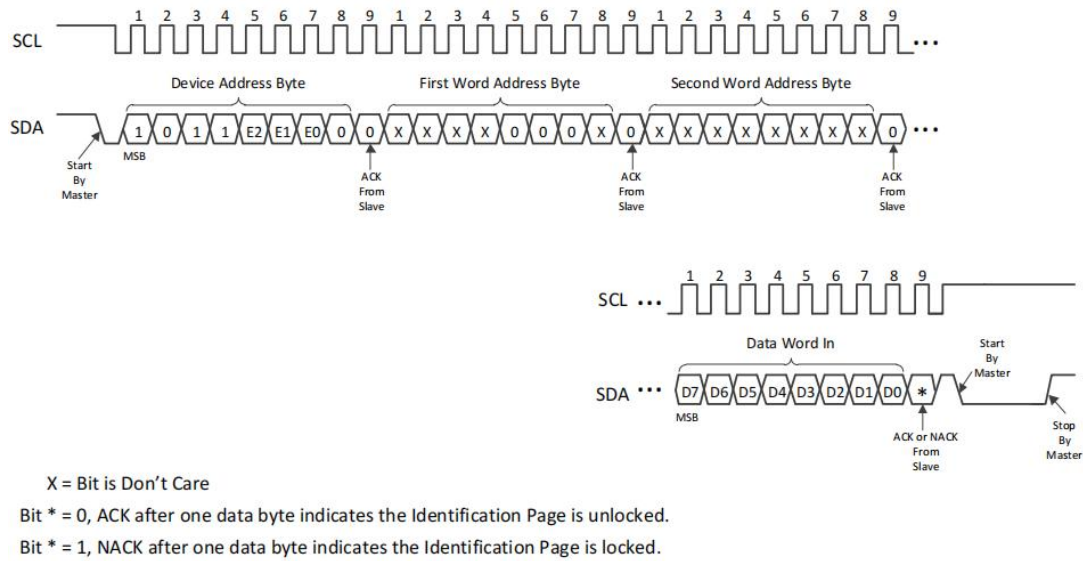
The locked/unlocked status of the Identification Page can be checked by transmitting a specific truncated command, Write Identification Page instruction and one data byte to the device. The device responds with an ACK to the data byte if the Identification Page is unlocked, or responds with a NACK if the Identification Page has been locked. Right after this, it is recommended to transmit a Start condition to the device followed by a Stop condition (see Figure 16 ), so that the truncated Write command will not be executed because the Start condition resets the device internal logic, and the device is then set back into Standby mode by the Stop condition.

### Read Unique ID

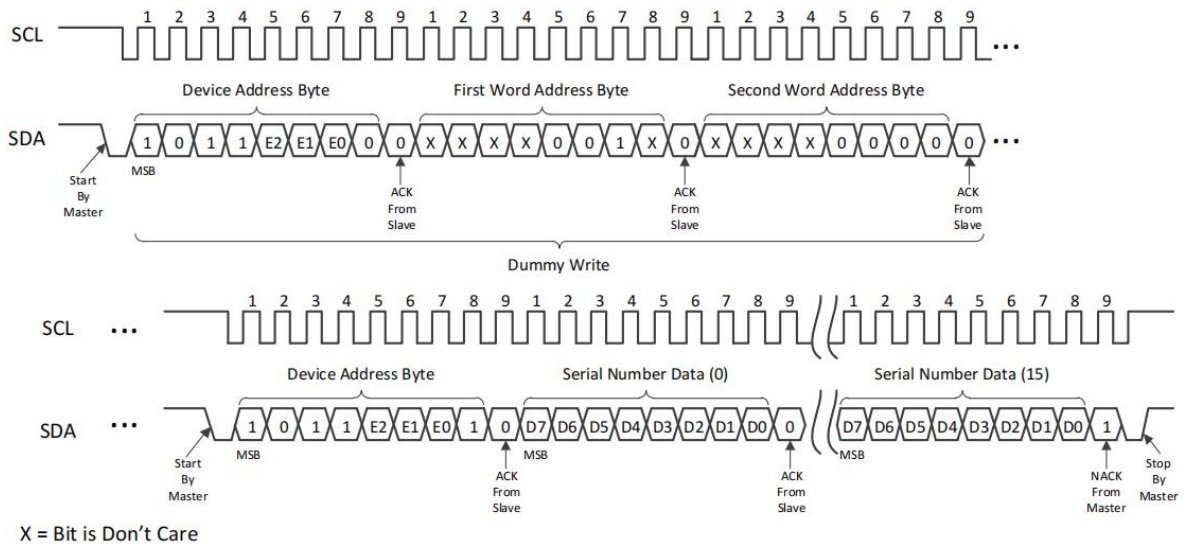
The AT24LC512C offers a separate memory block containing a factory programmed 128-bit Unique ID (UID), or Serial Number. Reading the Serial Number is similar to Sequential Read, except that:

- The device type identifier is defined as '1011';
- The word address bits A11:A9 must be '001', bits A15:A12 and A8:A4 are Don't Care;
- The word address bits A3:A0 define the byte locations inside the Unique ID (see Table 3 ).

In order to guarantee a unique number, the entire 128-bit value must be read from the starting address of the Serial Number block. Reading from a location other than the first address of the block will not result in a unique Serial Number. To read the first byte of the Serial Number, the word address bits A3:A0 need to be '0000'. Writing or altering the 128-bit Unique ID is not allowed. When the end of the 128-bit UID block is reached (16 bytes of data), the word address will roll over to the beginning of the 128-bit UID block. The Read Unique ID operation is terminated when the Master responds with a NACK to the data byte followed by a Stop condition (see Figure 17 ).



**Figure 16 Read Lock Status**



**Figure 17 Read Unique ID**

## Electrical Specifications

### Absolute Maximum Ratings

| Symbol           | Parameter                                | Value        | Unit |
|------------------|------------------------------------------|--------------|------|
|                  | Ambient temperature with power applied   | -55 to +130  | °C   |
| T <sub>STG</sub> | Storage temperature                      | -65 to +150  | °C   |
| V <sub>CC</sub>  | Supply voltage                           | -0.5 to +6.5 | V    |
| V <sub>IN</sub>  | Voltage on input Pins                    | -0.5 to +6.5 | V    |
| V <sub>ESD</sub> | Electrostatic pulse (human body model)   | 6000         | V    |
| T <sub>L</sub>   | Lead Temperature (Soldering, 10 seconds) | 260          | °C   |

**Note:** Stresses beyond those listed under 'Absolute Maximum Ratings' may cause permanent damage to the device. Functional operation of the device at these ratings or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability

### DC Characteristics

Operating range: T<sub>A</sub> = -40°C to +105°C, V<sub>CC</sub> = 1.7V to 5.5V (unless otherwise noted).

| Symbol           | Parameter                           | Test Condition                                                   | Min                 | Max                  | Unit |
|------------------|-------------------------------------|------------------------------------------------------------------|---------------------|----------------------|------|
| V <sub>CC</sub>  | Supply Voltage                      |                                                                  | 1.7                 | 5.5                  | V    |
| I <sub>CC1</sub> | Supply Current (Read)               | V <sub>CC</sub> = 1.7V, Read at 1MHz                             | -                   | 0.15                 | mA   |
|                  |                                     | V <sub>CC</sub> = 5.5V, Read at 400 kHz                          | -                   | 0.4                  | mA   |
|                  |                                     | V <sub>CC</sub> = 5.5V, Read at 1MHz                             | -                   | 0.5                  | mA   |
| I <sub>CC2</sub> | Supply Current (Write)              | V <sub>CC</sub> = 1.7V, Write at 400 kHz                         | -                   | 0.5                  | mA   |
|                  |                                     | V <sub>CC</sub> = 5.5V, Write at 400 kHz                         | -                   | 1.0                  | mA   |
| I <sub>SB</sub>  | Standby Current                     | V <sub>CC</sub> = 1.7V, V <sub>IN</sub> = V <sub>CC</sub> or GND | -                   | 0.5                  | μA   |
|                  |                                     | V <sub>CC</sub> = 5.5V, V <sub>IN</sub> = V <sub>CC</sub> or GND | -                   | 1.0                  | μA   |
| I <sub>LI</sub>  | Input Leakage Current               | V <sub>IN</sub> = V <sub>CC</sub> or GND                         | -                   | 1.0                  | μA   |
| I <sub>LO</sub>  | Output Leakage Current              | V <sub>OUT</sub> = V <sub>CC</sub> or GND                        | -                   | 1.0                  | μA   |
| V <sub>IL</sub>  | Input Low-Level Voltage (SDA, SCL)  |                                                                  | -0.5                | 0.3*V <sub>CC</sub>  | V    |
| V <sub>IH</sub>  | Input High-Level Voltage (SDA, SCL) |                                                                  | 0.7*V <sub>CC</sub> | V <sub>CC</sub> +0.5 | V    |
| V <sub>OL1</sub> | Low-Level Output Voltage            | V <sub>CC</sub> > 2V, I <sub>OL</sub> = 3mA                      | -                   | 0.4                  | V    |
| V <sub>OL2</sub> | Low-Level Output Voltage            | V <sub>CC</sub> ≤2V, I <sub>OL</sub> = 2mA                       | -                   | 0.2                  | V    |

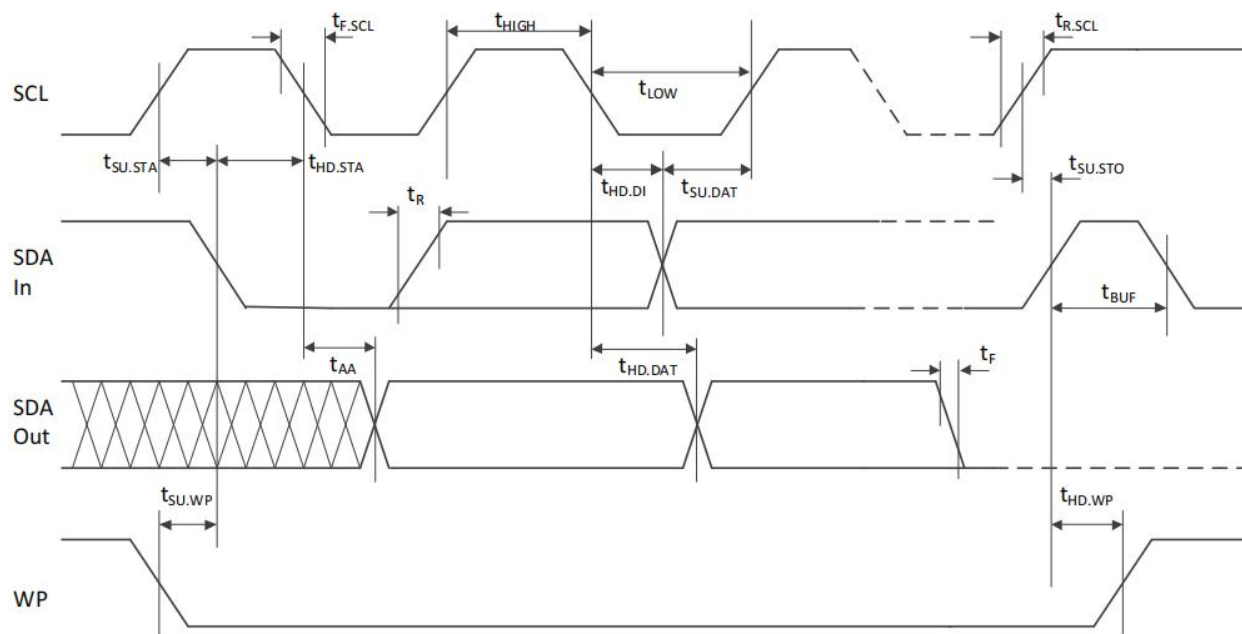
## AC Characteristics

Operating range:  $T_A = -40^{\circ}\text{C}$  to  $+105^{\circ}\text{C}$ ,  $V_{CC} = 1.7\text{V}$  to  $5.5\text{V}$ ,  $C_L = 100\text{pF}$  (unless otherwise noted).

Measurement conditions: Input rise and fall time  $\leq 50\text{ns}$  Input pulse voltages:  $0.2 \cdot V_{CC}$  to  $0.8 \cdot V_{CC}$  Input and output timing reference voltages:  $0.3 \cdot V_{CC}$  to  $0.7 \cdot V_{CC}$

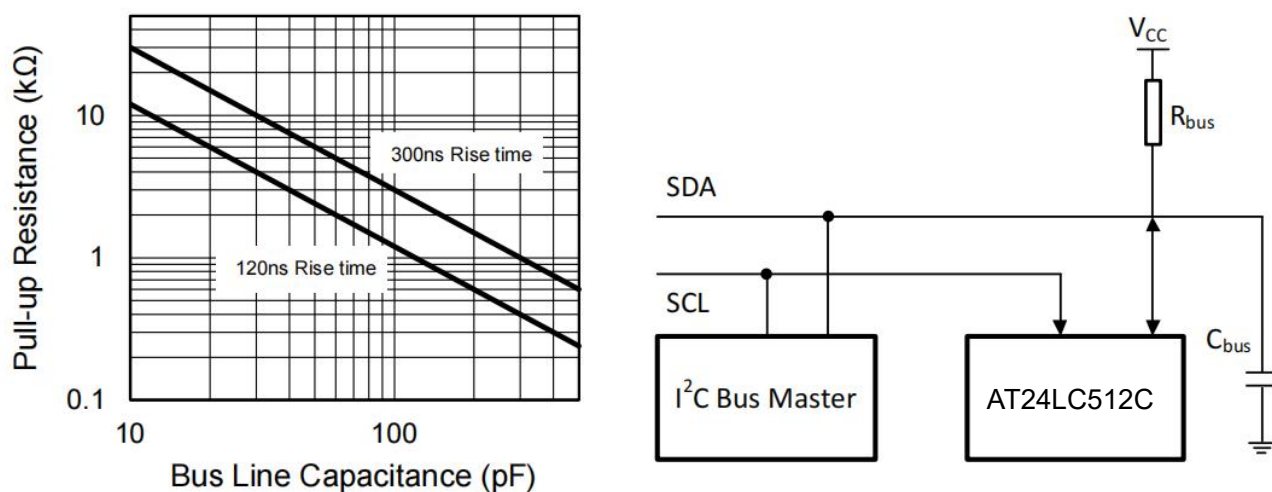
| Symbol       | Parameter                                 | Fast<br>$V_{CC} = 1.7\text{V}$ to $5.5\text{V}$ |     | High Speed<br>$V_{CC} = 1.7\text{V}$ to $5.5\text{V}$ |      | Unit |
|--------------|-------------------------------------------|-------------------------------------------------|-----|-------------------------------------------------------|------|------|
|              |                                           | Min                                             | Max | Min                                                   | Max  |      |
| $f_{SCL}$    | Clock Frequency, SCL                      | -                                               | 400 | -                                                     | 1000 | kHz  |
| $t_{LOW}$    | Clock Pulse Width Low                     | 1300                                            | -   | 600                                                   | -    | ns   |
| $t_{HIGH}$   | Clock Pulse Width High                    | 600                                             | -   | 260                                                   | -    | ns   |
| $t_R^{[1]}$  | SDA Rise Time                             | -                                               | 300 | -                                                     | 300  | ns   |
| $t_F^{[1]}$  | SDA(Out) Fall Time                        | -                                               | 300 | -                                                     | 100  | ns   |
| $t_{HD.STA}$ | Start Hold Time                           | 600                                             | -   | 250                                                   | -    | ns   |
| $t_{SU.STA}$ | Start Setup Time                          | 600                                             | -   | 250                                                   | -    | ns   |
| $t_{SU.STO}$ | Stop Setup Time                           | 600                                             | -   | 250                                                   | -    | ns   |
| $t_{BUF}$    | Bus Free Time between Stop and Next Start | 1300                                            | -   | 500                                                   | -    | ns   |
| $t_{HD.DI}$  | Data In Hold Time                         | 0.0                                             | -   | 0.0                                                   | -    | ns   |
| $t_{SU.DAT}$ | Data In Setup Time                        | 100                                             | -   | 50                                                    | -    | ns   |
| $t_{HD.DAT}$ | Data Out Hold Time                        | 50                                              | -   | 50                                                    | -    | ns   |
| $t_{AA}$     | SCL Low to Data Out Valid                 | 100                                             | 900 | 50                                                    | 500  | ns   |
| $t_{SU.WP}$  | WP Pin Setup Time                         | 1200                                            | -   | 600                                                   | -    | ns   |
| $t_{HD.WP}$  | WP Pin Hold Time                          | 1200                                            | -   | 600                                                   | -    | ns   |
| $t_{WR}$     | Write Cycle Time                          | -                                               | 5   | -                                                     | 5    | ms   |
| $t_i$        | Noise Suppression Time                    | -                                               | 50  | -                                                     | 50   | ns   |

**Notes:** <sup>[1]</sup> This parameter is ensured by characterization only.



The timing sequence of the model is slightly longer than that of the 24CXX series.

**Figure 6–1 Bus Timing**



**Figure 6–2 Maximum Pull-up Resistance vs. Bus Parasitic Capacitance**

## Pin Capacitance

Operating range for pin capacitance:  $T_A = +25^{\circ}\text{C}$ ,  $f_C = 1\text{MHz}$ ,  $V_{CC} = 1.7\text{V}$  to  $5.5\text{V}$ .

| Symbol    | Parameter <sup>[1]</sup>       | Max | Unit | Test Condition        |
|-----------|--------------------------------|-----|------|-----------------------|
| $C_{I/O}$ | Input/output Capacitance (SDA) | 8   | pF   | $V_{I/O} = 0\text{V}$ |
| $C_{IN}$  | Input Capacitance (other Pins) | 6   | pF   | $V_{IN} = 0\text{V}$  |

**Note:** <sup>[1]</sup> These parameters are ensured by characterization only.

## Reliability Characteristics

| Symbol | Parameter             | Min             | Unit  | Test Condition                          |
|--------|-----------------------|-----------------|-------|-----------------------------------------|
| $N_W$  | Write Cycle Endurance | $2 \times 10^6$ | cycle | $T_A = +25^{\circ}\text{C}$ , Page Mode |
| $D_R$  | Data Retention        | 200             | year  | $T_A = +25^{\circ}\text{C}$             |

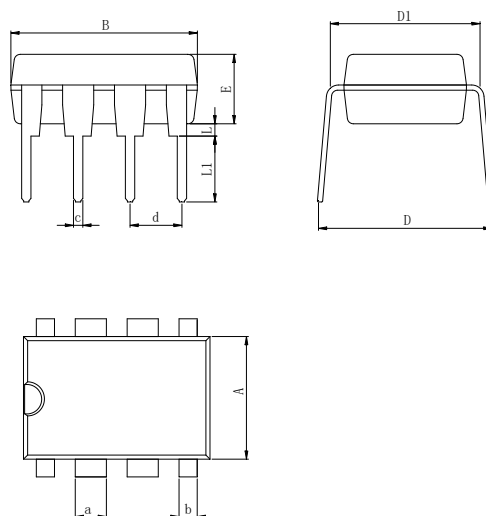
## Initial Delivery State

The AT24LC512C Serial EEPROM is delivered as follows:

- All bits in the memory array are set to '1' (each byte contains FFh).
- All bits in the Identification Page are set to '1' (each byte contains FFh).

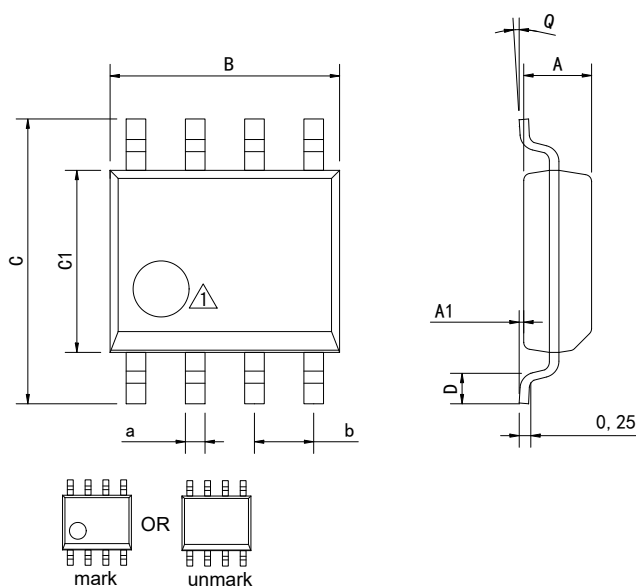
## Physical Dimensions

### DIP-8



| Dimensions In Millimeters(DIP-8) |      |      |      |      |      |      |      |      |      |      |          |
|----------------------------------|------|------|------|------|------|------|------|------|------|------|----------|
| Symbol:                          | A    | B    | D    | D1   | E    | L    | L1   | a    | b    | c    | d        |
| Min:                             | 6.10 | 9.00 | 8.10 | 7.42 | 3.10 | 0.50 | 3.00 | 1.50 | 0.85 | 0.40 | 2.54 BSC |
| Max:                             | 6.68 | 9.50 | 10.9 | 7.82 | 3.55 | 0.70 | 3.60 | 1.55 | 0.90 | 0.50 |          |

### SOP-8

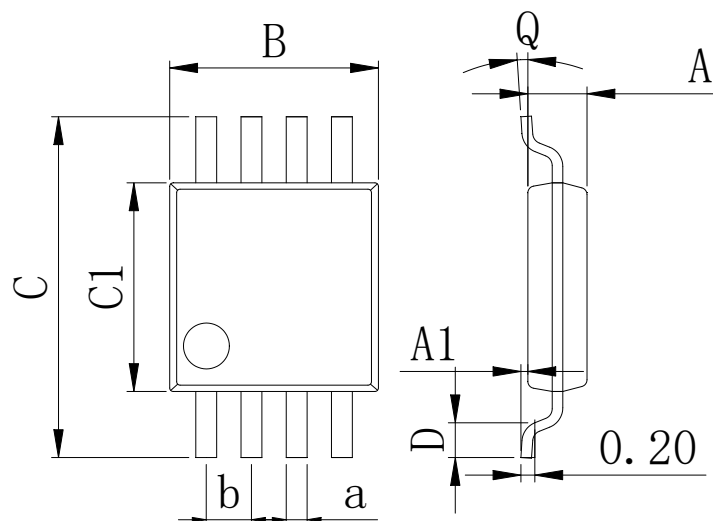


⚠ Package top mark may be in lower left corner or unmark

| Dimensions In Millimeters(SOP-8) |      |      |      |      |      |      |    |      |          |
|----------------------------------|------|------|------|------|------|------|----|------|----------|
| Symbol:                          | A    | A1   | B    | C    | C1   | D    | Q  | a    | b        |
| Min:                             | 1.35 | 0.05 | 4.90 | 5.80 | 3.80 | 0.40 | 0° | 0.35 | 1.27 BSC |
| Max:                             | 1.55 | 0.20 | 5.10 | 6.20 | 4.00 | 0.80 | 8° | 0.45 |          |

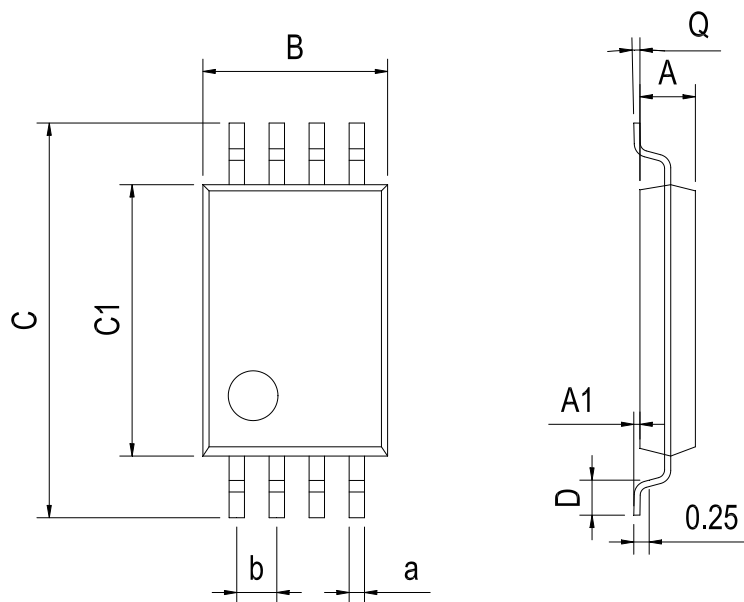
## Physical Dimensions

### MSOP-8



| Dimensions In Millimeters(MSOP-8) |      |      |      |      |      |      |    |      |          |
|-----------------------------------|------|------|------|------|------|------|----|------|----------|
| Symbol:                           | A    | A1   | B    | C    | C1   | D    | Q  | a    | b        |
| Min:                              | 0.80 | 0.05 | 2.90 | 4.75 | 2.90 | 0.35 | 0° | 0.25 | 0.65 BSC |
| Max:                              | 0.90 | 0.20 | 3.10 | 5.05 | 3.10 | 0.75 | 8° | 0.35 |          |

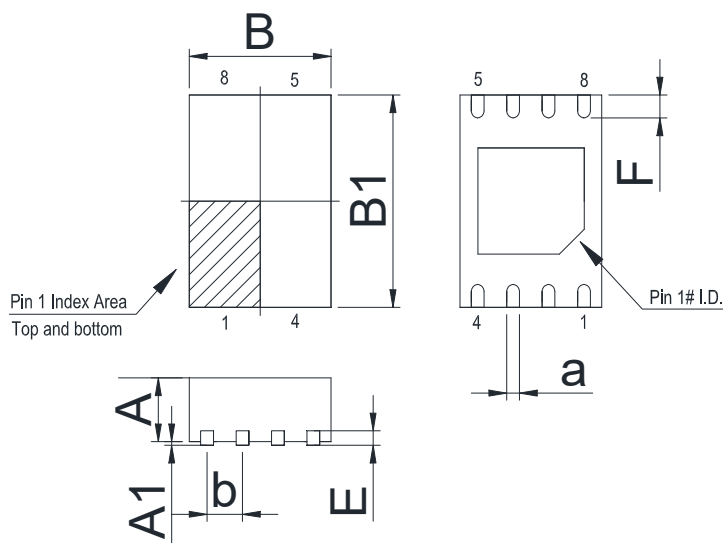
### TSSOP-8 (4.4\*3.0)



| Dimensions In Millimeters(TSSOP-8) |      |      |      |      |      |      |    |      |          |
|------------------------------------|------|------|------|------|------|------|----|------|----------|
| Symbol:                            | A    | A1   | B    | C    | C1   | D    | Q  | a    | b        |
| Min:                               | 0.85 | 0.05 | 2.90 | 6.20 | 4.30 | 0.40 | 0° | 0.20 | 0.65 BSC |
| Max:                               | 0.95 | 0.20 | 3.10 | 6.60 | 4.50 | 0.80 | 8° | 0.25 |          |

## Physical Dimensions

DFN-8 2\*3



| Dimensions In Millimeters(DFN-8 2*3) |      |      |      |      |      |      |      |         |
|--------------------------------------|------|------|------|------|------|------|------|---------|
| Symbol:                              | A    | A1   | B    | B1   | E    | F    | a    | b       |
| Min:                                 | 0.85 | 0    | 1.90 | 2.90 | 0.15 | 0.25 | 0.20 | 0.50TYP |
| Max:                                 | 0.95 | 0.05 | 2.10 | 3.10 | 0.25 | 0.35 | 0.30 |         |

## Revision History

| REVISION NUMBER | DATE    | REVISION                                                    | PAGE   |
|-----------------|---------|-------------------------------------------------------------|--------|
| V1.0            | 2015-1  | New                                                         | 1-27   |
| V1.1            | 2021-5  | Add timing sequential annotations                           | 20     |
| V1.2            | 2024-11 | Write Cycle Time 3mS Change 5mS.、 Update Lead Temperature   | 18、 19 |
| V1.3            | 2025-11 | Update important statements、 Update SOP-8 Dimension drawing | 22、 26 |

**IMPORTANT STATEMENT:**

Huaguan Semiconductor reserves the right to change products and services offered without prior notice. Customers should obtain the latest relevant information before placing orders and verify that such information is current and complete. Huaguan Semiconductor assumes no responsibility or liability for altered documents.

Customers are responsible for complying with safety standards and implementing safety measures when using Huaguan Semiconductor products in system design and end-product manufacturing. You assume full responsibility for: selecting the appropriate Huaguan Semiconductor products for your application; designing, validating, and testing your application; and ensuring that your application complies with applicable standards and all other safety, security, or other requirements. This is to prevent potential risks that may lead to personal injury or property damage.

Huaguan Semiconductor products are not approved for use in life support, military, aerospace, or other high-risk applications. Huaguan products are neither intended nor warranted for use in such systems or equipment. Any failure or malfunction may lead to personal injury or severe property damage. Such applications are deemed "Unsafe Use." Unsafe Use includes, but is not limited to: surgical and medical equipment, nuclear energy control equipment, aircraft or spacecraft instruments, control or operation of vehicle power, braking, or safety systems, traffic signal instruments, all types of safety devices, and any other applications intended to support or sustain life. Huaguan Semiconductor shall not be liable for consequences resulting from Unsafe Use in these fields. Users must independently evaluate and assume all risks. Any issues, liabilities, or losses arising from the use of products beyond their approved applications shall be solely borne by the user. Users may not claim any compensation from Huaguan Semiconductor based on these terms. If any third party claims against Huaguan Semiconductor due to such Unsafe Use, the user shall compensate Huaguan Semiconductor for all resulting damages and liabilities.

Huaguan Semiconductor provides technical and reliability data (including datasheets), design resources (including reference designs), application or other design advice, web tools, safety information, and other resources for its semiconductor products. However, no guarantee is made that these resources are free from defects, and no express or implied warranties are provided. The use of testing and other quality control techniques is limited to Huaguan Semiconductor's quality assurance scope. Not all parameters of each device are tested.

Huaguan Semiconductor's documentation authorizes you to use these resources only for developing applications related to the products described herein. You are not granted rights to any other intellectual property of Huaguan Semiconductor or any third party. Any other reproduction or display of these resources is strictly prohibited. You shall fully indemnify Huaguan Semiconductor and its agents against any claims, damages, costs, losses, and liabilities arising from your use of these resources. Huaguan Semiconductor shall not be held responsible.