

钍地半导体
Tudi Semiconductor

Product Specification

TUDI-AT24C16D

I²C-Compatible (2-Wire) Serial EEPROM 16-Kbit

网址 www.sztdbdt.com

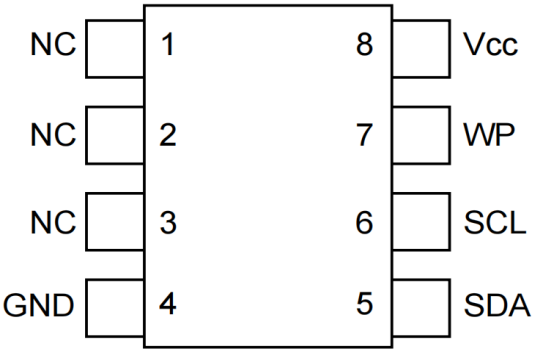
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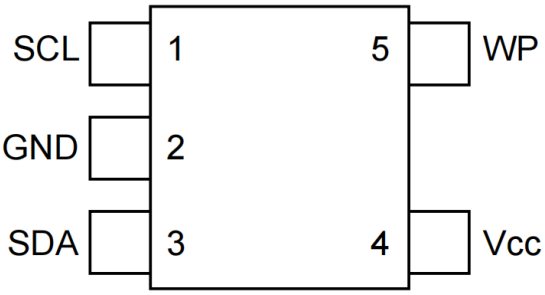
- Design
- research and development
- production
- and sales

Features

- Low-Voltage Operation:
  - Vcc = 1.7V to 3.6V
- Internally Organized as 2,048 x 8 (16K)
- I^2C-Compatible (2-Wire) Serial Interface:
  - 100 kHz Standard mode, 1.7V to 3.6V
  - 400 kHz Fast mode, 1.7V to 3.6V
  - 1 MHz Fast Mode Plus (FM+), 2.5V to 3.6V
- Schmitt Triggers, Filtered Inputs for Noise Suppression
- Bidirectional Data Transfer Protocol
- Write-Protect Pin for Full Array Hardware Data Protection (except WLCSP)
- Ultra Low Active Current (1 mA maximum) and Standby Current (0.8 µA maximum)
- 16-Byte Page Write Mode:
  - Partial page writes allowed
- Random and Sequential Read Modes
- Self-Timed Write Cycle within 5 ms Maximum
- ESD Protection > 4,000V
- High Reliability:
  - Endurance: 1,000,000 write cycles
  - Data retention: 100 years
- Green Package Options (Lead-free/Halide-free/RoHS compliant)
- Die Sale Options: Wafer Form and Tape and Reel Available



SOP8/DIP8/TSSOP8



SOT23-5

Description

The AT24C16D provides 16,384 bits of Serial Electrically Erasable and Programmable Read-Only Memory (EEPROM) organized as 2,048 words of 8 bits each. This device is optimized for use in many industrial and commercial applications where low-power and low-voltage operations are essential. The device is available in space-saving 8-lead SOIC, 8-lead TSSOP, 8-lead PDIP,5-lead SOT23 packages. The entire family of packages operates from 1.7V to 3.6V.

Pin Descriptions

The descriptions of the pins are listed in Table 1

Table 1.Pin Function Table

Name	8-lead PDIP	8-lead SOIC	8-lead TSSOP	5-lead SOT23	Function
NC	1	1	1	—	No Connect
NC	2	2	2	—	No Connect
NC	3	3	3	—	No Connect
GND	4	4	4	2	Ground
SDA	5	5	5	3	Serial Data
SCL	6	6	6	1	Serial Clock
WP(2)	7	7	7	5	Write-Protect
V_{CC}	8	8	8	4	DevicePower Supply

Note:
1. The exposed pad on the UDFN package can be connected to GND or left floating.
2. If the WP pin is not driven, it is internally pulled down to GND. In order to operate in a wide variety of application environments, the pull-down mechanism is intentionally designed to be somewhat strong. Once these pins are biased above the CMOS input buffer ' s trip point (~0.5 x V_{CC}), the pull -down mechanism disengages. TUDI recommends connecting these pins to a known state whenever possible.

Ground：The ground reference for the power supply. GND should be connected to the system ground.

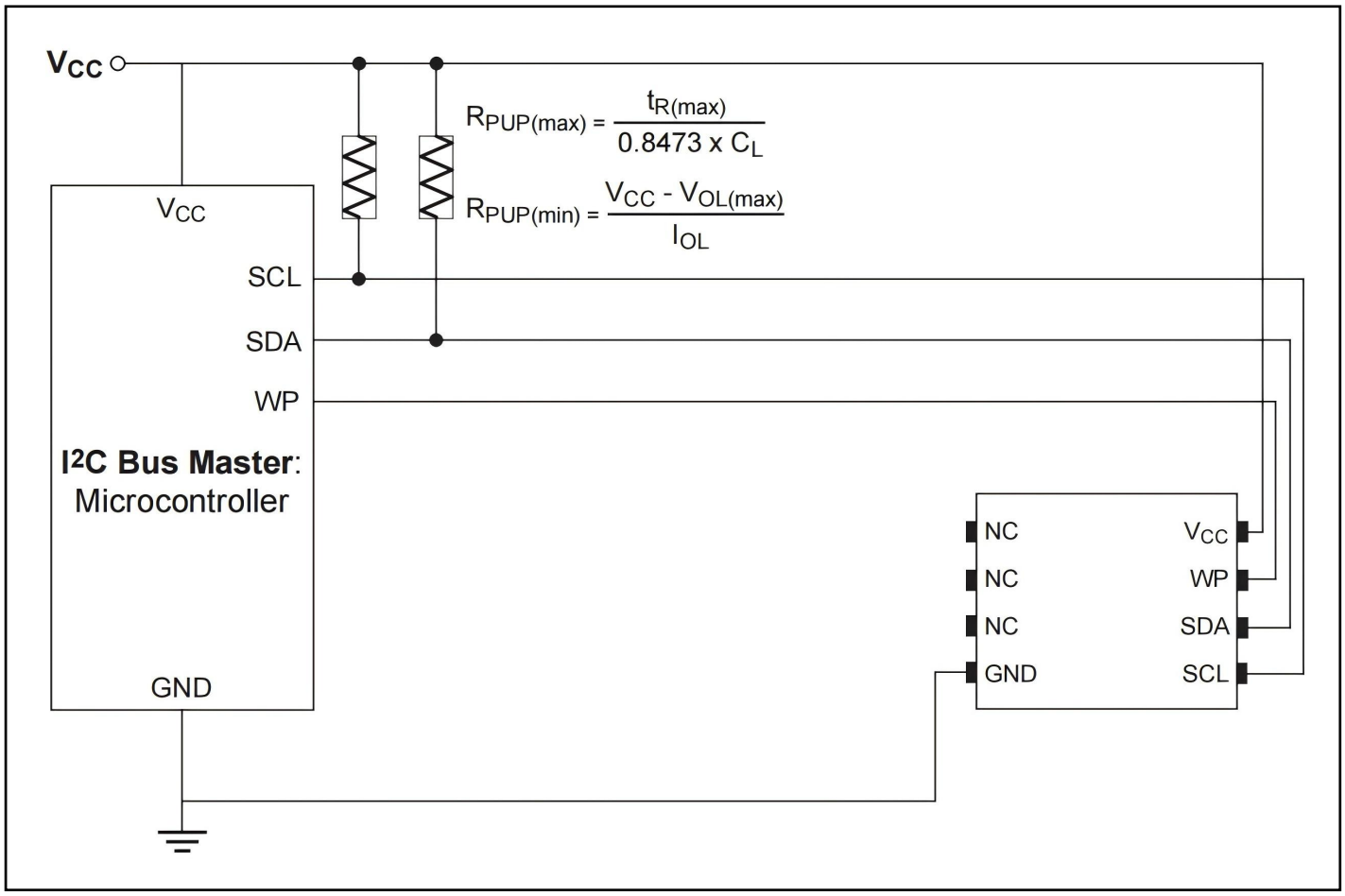
Serial Data (SDA)：The SDA pin is an open-drain bidirectional input/output pin used to serially transfer data to and from the device. The SDA pin must be pulled-high using an external pull-up resistor (not to exceed 10 kΩ in value) and may be wire-ORed with any number of other open-drain or open-collector pins from other devices on the same bus.

Serial Clock (SCL)：The SCL pin is used to provide a clock to the device and to control the flow of data to and from the device. Command and input data present on the SDA pin is always latched in on the rising edge of SCL, while output data on the SDA pin is clocked out on the falling edge of SCL. The SCL pin must either be forced high when the serial bus is idle or pulled high using an external pull-up resistor.

Write-Protect: Connecting the WP pin to GND will ensure normal write operations. When the WP pin is connected to Vcc, all write operations to the memory are inhibited. Refer to Note 2 for the behavior of the pin when not connected.

Device Power Supply: The Vcc pin is used to supply the source voltage to the device. Operations at invalid Vcc voltages may produce spurious results and should not be attempted

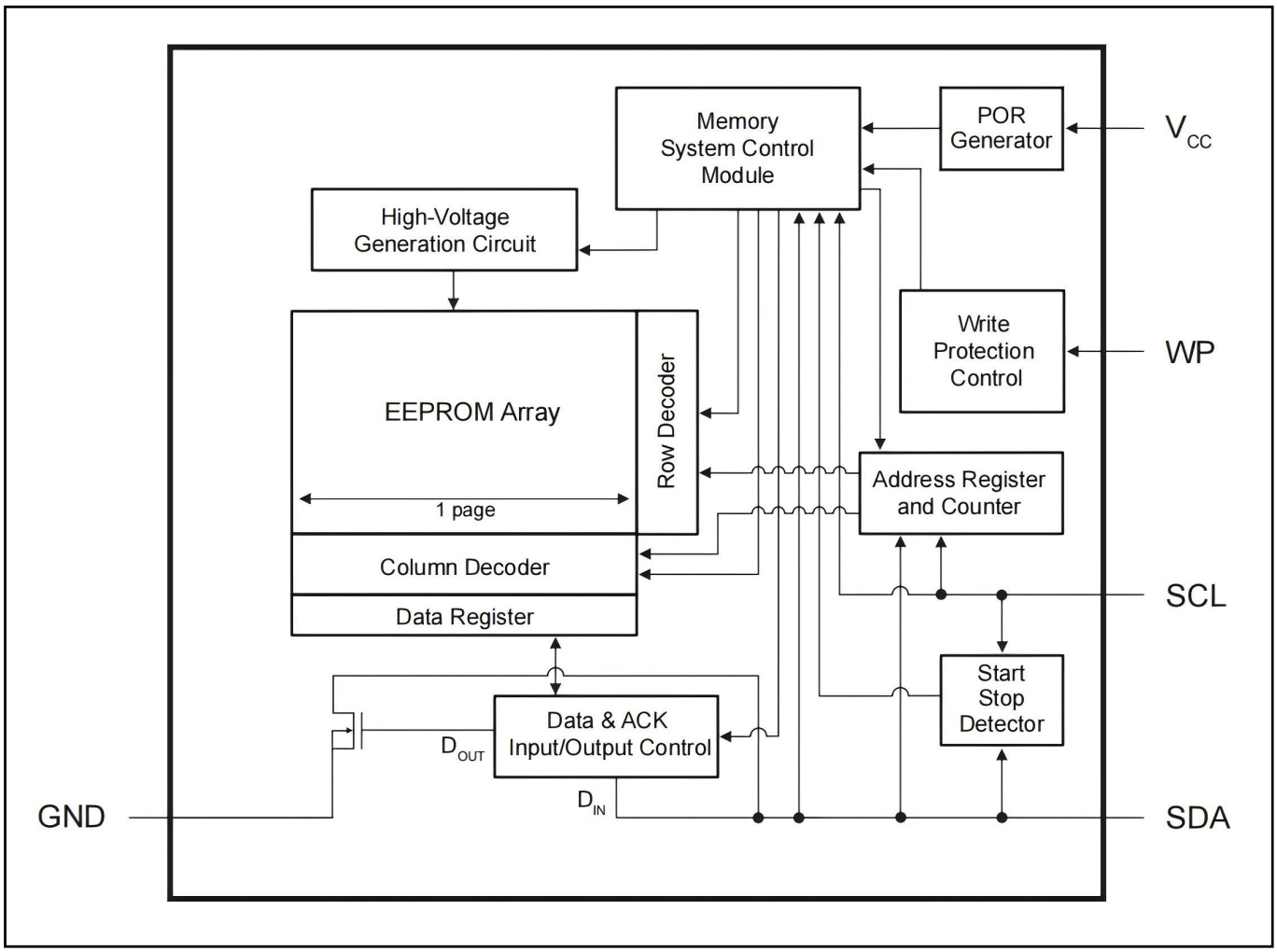
System Configuration Using 2-Wire Serial EEPROMs



Device Default Condition from TUDI

The AT24C16D is delivered with the EEPROM array set to logic ’1’, resulting in FFh data in all locations.

Block Diagram



Electrical Characteristics

Absolute Maximum Ratings

Temperature under bias	-55°C to +125°C
Storage temperature	-65°C to +150°C
Supply voltage with respect to ground	-0.5V to +4.10V
Voltage on any pin with respect to ground	-0.6V to V_{cc} + 0.5V
DC output current	5.0 mA
ESD protection	>4 kV

Note: Stresses above those listed under “ Absolute Maximum Ratings ” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure above maximum rating conditions for extended periods may affect device reliability

DC and AC Operating Range

AT24C16D		
Operating Temperature(Case)	Industrial Temperature Range	-40℃ to +85℃
V_{CC} Power Supply	Low Voltage Grade	1.7V to 3.6V

DC Characteristics

Parameter	Symbol	Minimum	Typical(1)	Maximum	Units	Test Conditions
Supply Voltage	V_{CC}	1.7	—	3.6	V	
Supply Current, Read	I_{CC1}	—	0.08	0.3	mA	V_{CC}=1.8V(2),Read at 400 kHz
		—	0.15	0.5	mA	V_{CC}=3.6V,Read at 1 MHz
Supply Current, Write	I_{CC2}	—	0.20	1.0	mA	V_{CC}=3.6V,Write at 1 MHz
Standby Current	I_{SB}	—	0.08	0.4	μA	V_{CC}=1.8V(2),V_{IN}=Vcc or GND
		—	0.10	0.8	μA	V_{CC}=3.6V,V_{IN}=V_{CC} or GND
Input Leakage Current	I_{LI}	—	0.10	3.0	μA	V_{IN}=V_{CC} or GND
Ouput Leakage Current	I_{LO}	—	0.05	3.0	μA	V_{OUT}=V_{CC} or GND
Input Low Level	V_{IL}	-0.6	—	V_{CC}×0.3	V	Note 2
Input High Level	V_{IH}	V_{CC}×0.7	—	V_{CC}+0.5	V	Note 2
Output Low Level	V_{OL1}	—	—	0.2	V	V_{CC}=1.8V,I_{OL}=0.15 mA
Output Low Level	V_{OL2}	—	—	0.4	V	V_{CC}=3.0V,I_{OL}=2.1 mA

Note:
1. Typical values characterized at T_A = +25°C unless otherwise noted.
2. This parameter is characterized but is not 100% tested in production.

AC Characteristics

Parameter	Symbol	Standard Mode		Fast Mode		Fast Mode Plus		Units
		V_{CC}=1.7V to 3.6V		V_{CC}=1.7V to 3.6V		V_{CC}=2.5V to 3.6V		
		Min.	Max.	Min.	Max.	Min.	Max.	
Clock Frequency,SCL	$f_{SU,STA}$	—	100	—	400	—	1000	kHz
Clock Pulse Width Low	t_{LOW}	4,700	—	1,300	—	500	—	ns
Clock Pulse Width High	t_{HIGH}	4,000	—	600	—	400	—	ns
Input Filter Spike Suppression (SCL,SDA)(1)	t_I	—	100	—	100	—	100	ns
Clock Low to Data Out Valid	t_{AA}	—	4,500	—	900	—	450	ns
Bus Free Time between Stop and Start(1)	t_{BUF}	4,700	—	1,300	—	500	—	ns
Start Hold Time	$t_{HD.STA}$	4,000	—	600	—	250	—	ns
Start Set-up Time	$t_{SU.STA}$	4,700	—	600	—	250	—	ns
Data In Hold Time	$t_{HD.DAT}$	0	—	0	—	0	—	ns
Data In Set-up Time	$t_{SU.DAT}$	200	—	100	—	100	—	ns
Inputs Rise Time(1)	t_R	—	1,000	—	300	—	100	ns
Inputs Fall Time(1)	t_F	—	300	—	300	—	100	ns
Stop Set-up Time	$t_{SU.STO}$	4,700	—	600	—	250	—	ns
Write-Protect Setup Time	$t_{SU.WP}$	4,000	—	600	—	100	—	ns

AC Characteristics(Continue)

Parameter	Symbol	Standard Mode		Fast Mode		Fast Mode Plus		Units
		V_{CC}=1.7V to 3.6V		V_{CC}=1.7V to 3.6V		V_{CC}=2.5V to 3.6V		
		Min.	Max.	Min.	Max.	Min.	Max.	
Write-Protect Hold Time	$t_{HD.WP}$	4,000	—	600	—	400	—	ns
Data Out Hold Time	t_{DH}	100	—	50	—	50	—	ns
Write Cycle Time	t_{WR}	—	5	—	5	—	5	ms

Note:
1. These parameters are determined through product characterization and are not 100% tested in production.
2. AC measurement conditions:
- CL: 100 pF
- RPUP (SDA bus line pull-up resistor to V_{CC}): 1.3 kΩ (1000 kHz), 4 kΩ (400 kHz), 10 kΩ (100 kHz)
- Input pulse voltages: 0.3 x V_{CC} to 0.7 x V_{CC}
- Input rise and fall times: ≤50 ns
- Input and output timing reference voltages: 0.5 x V_{CC}

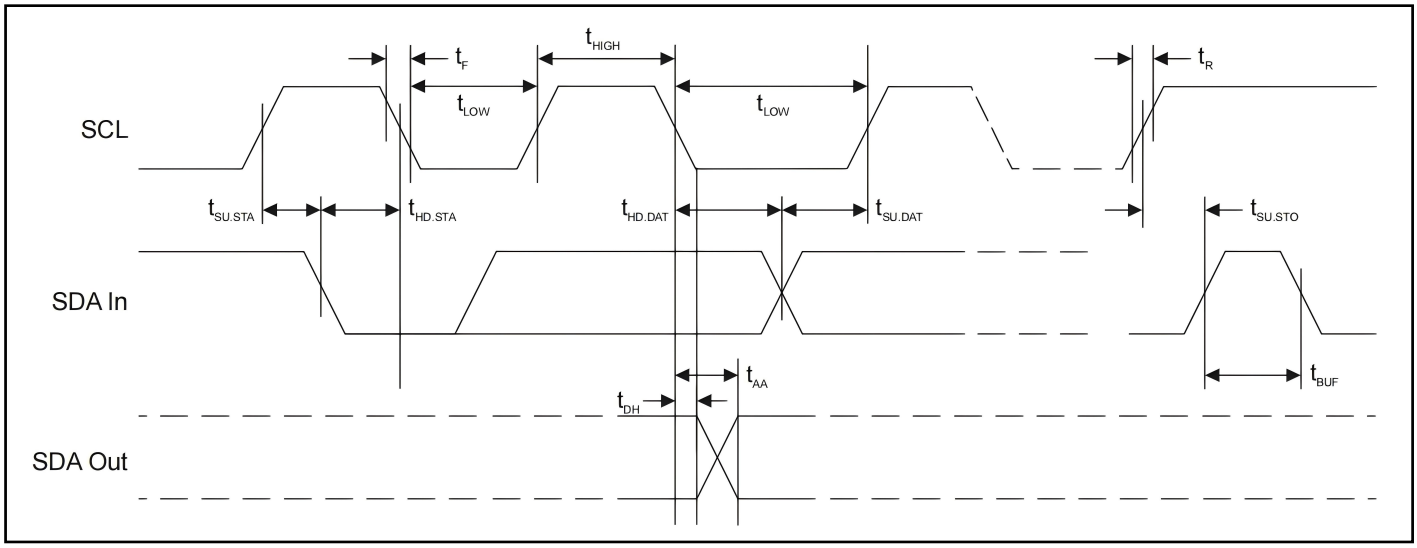


Figure 1.Bus Timing

Electrical Specifications

Power-Up Requirements and Reset Behavior: During a power-up sequence, the V_{CC} supplied to the AT24C16D should monotonically rise from GND to the minimum V_{CC} level as specified in Pin Capacitance with a slew rate no faster than 0.1 V/µs.

Device Reset: To prevent inadvertent write operations or any other spurious events from occurring during a power-up sequence, the AT24C16D includes a Power-on Reset (POR) circuit. Upon power-up, the device will not respond to any commands until the V_{CC} level crosses the internal voltage threshold (V_{POR}) that brings the device out of Reset and into Standby mode. The system designer must ensure the instructions are not sent to the device until the V_{CC} supply has reached a stable value greater than or equal to the minimum V_{CC} level. Additionally, once the V_{CC} is greater than or equal to the minimum V_{CC} level, the bus master must wait at least t_{PUP} before sending the first command to the device. See Table 2 for the values associated with these power-up parameters.

Power-up Conditions (1)

Symbol	Parameter	Min.	Max.	Units
t_{PUP}	Time required after V_{cc} is stable before the device can accept commands	100	—	µs
V_{POR}	Power-on Reset Threshold Voltage.	—	1.5	V
t_{POFF}	Minimum time at V_{cc}=0V between power cycles.	1	—	ms

Note:
1. These parameters are characterized but they are not 100% tested in production.

If an event occurs in the system where the V_{CC} level supplied to the AT24C16D drops below the maximum V_{POR} level specified, it is recommended that a full power cycle sequence be performed by first driving the V_{CC} pin to GND, waiting at least the minimum t_{POFF} time, and then performing a new power-up sequence in compliance with the requirements defined in this section.

Pin Capacitance(1)

Symbol	Test Condition	Max.	Units	Conditions
$C_{I/O}$	Input/Output Capacitance(SDA)	8	pF	$V_{I/O}$=0V
C_{IN}	Input Capacitance(SCL)	6	pF	V_{IN}=0V

Note:
1. This parameter is characterized but is not 100% tested in production.

EEPROM Cell Performance Characteristics

Operation	Test Condition	Min.	Max.	Units
Write Endurance(1)	T_A=25°C,V_{CC}(min.)<V_{CC}<V_{CC}(max.)	1,000,000	—	Write Cycles
	Byte or Page Write mode			
Data Retention(2)	T_A = 55°C, V_{CC}(min.) < V_{CC}< V_{CC} (max.)	100	—	Years

Note:
1. Write endurance performance is determined through characterization and the qualification process.
2. The data retention capability is determined through qualification and is checked on each device in production.

Device Operation and Communication

The AT24C16D operates as a slave device and utilizes a simple I^2C-compatible 2-wire digital serial interface to communicate with a host controller, commonly referred to as the bus master. The master initiates and controls all read and write operations to the slave devices on the serial bus, and both the master and the slave devices can transmit and receive data on the bus.
The serial interface is comprised of just two signal lines: Serial Clock (SCL) and Serial Data (SDA). The SCL pin is used to receive the clock signal from the master, while the bidirectional SDA pin is used to receive command and data information from the master as well as to send data back to the master. Data is always latched into the AT24C16D on the rising edge of SCL and always output from the device on the falling edge of SCL. Both the SCL and SDA pin incorporate integrated spike suppression filters and Schmitt Triggers to minimize the effects of input spikes and bus noise.
All command and data information is transferred with the Most Significant bit (MSb) first.
During bus communication, one data bit is transmitted every clock cycle, and after eight bits (one byte) of data have been transferred, the receiving device must respond with either an Acknowledge (ACK) or a No-acknowledge (NACK) response bit during a ninth clock cycle (ACK/NACK clock cycle) generated by the master. Therefore, nine clock cycles are required for every one byte of data transferred. There are no unused clock cycles during any read or write operation, so there must not be any interruptions or breaks in the data stream during each data byte transfer and ACK or NACK clock cycle.
During data transfers, data on the SDA pin must only change while SCL is low, and the data must remain stable while SCL is high. If data on the SDA pin changes while SCL is high, then either a Start or a Stop condition will occur. Start and Stop conditions are used to initiate and end all serial bus communication between the master and the slave devices. The number of data bytes transferred between a Start and a Stop condition is not limited and is determined by the master. In order for the serial bus to be idle, both the SCL and SDA pins must be in the logic-high state at the same time.

Clock and Data Transition Requirements

The SDA pin is an open-drain terminal and therefore must be pulled high with an external pull-up resistor. SCL is an input pin which can either be driven high or pulled high using an external pull-up resistor. Data on the SDA pin may change only during SCL low time periods. Data changes during SCL high periods will indicate a Start or Stop condition as defined below. The relationship of the AC timing parameters with respect to SCL and SDA for the AT24C16D are shown in the timing waveform in Figure 1. The AC timing characteristics and specifications are outlined in AC Characteristics.

Start and Stop Conditions

Start Condition:A Start condition occurs when there is a high-to-low transition on the SDA pin while the SCL pin is at a stable logic ‘1’ state and will bring the device out of Standby mode. The master uses a Start condition to initiate any data transfer sequence; therefore, every command must begin with a Start condition. The device will continuously monitor the SDA and SCL pins for a Start condition but will not respond unless one is detected. Refer to Figure 2 for more details.

Stop Condition:A Stop condition occurs when there is a low-to-high transition on the SDA pin while the SCL pin is stable in the logic ‘1’ state.
The master can use the Stop condition to end a data transfer sequence with the AT24C16D which will subsequently return to Standby mode. The master can also utilize a repeated Start condition instead of a Stop condition to end the current data transfer if the master will perform another operation. Refer to Figure 2 for more details

Acknowledge and No-Acknowledge

After every byte of data is received, the receiving device must confirm to the master that it has successfully received the data byte by responding with what is known as an Acknowledge (ACK). An ACK is accomplished by the transmitting device first releasing the SDA line at the falling edge of the eighth clock cycle followed by the receiving device responding with a logic ‘0’ during the entire high period of the ninth clock cycle.
When the AT24C16D is transmitting data to the master, the master can indicate that it is done receiving data and wants to end the operation by sending a logic ‘1’ response to the AT24C16D instead of an ACK response during the ninth clock cycle. This is known as a No-Acknowledge (NACK) and is accomplished by the master sending a logic ‘1’ during the ninth clock cycle, at which point the AT24C16D will release the SDA line so the master can then generate a Stop condition.
The transmitting device, which can be the bus master or the Serial EEPROM, must release the SDA line at the falling edge of the eighth clock cycle to allow the receiving device to drive the SDA line to a logic ‘0’ to ACK the previous 8-bit word. The receiving device must release the SDA line at the end of the ninth clock cycle to allow the transmitter to continue sending new data. A timing diagram has been provided in Figure 2 to better illustrate these requirements.

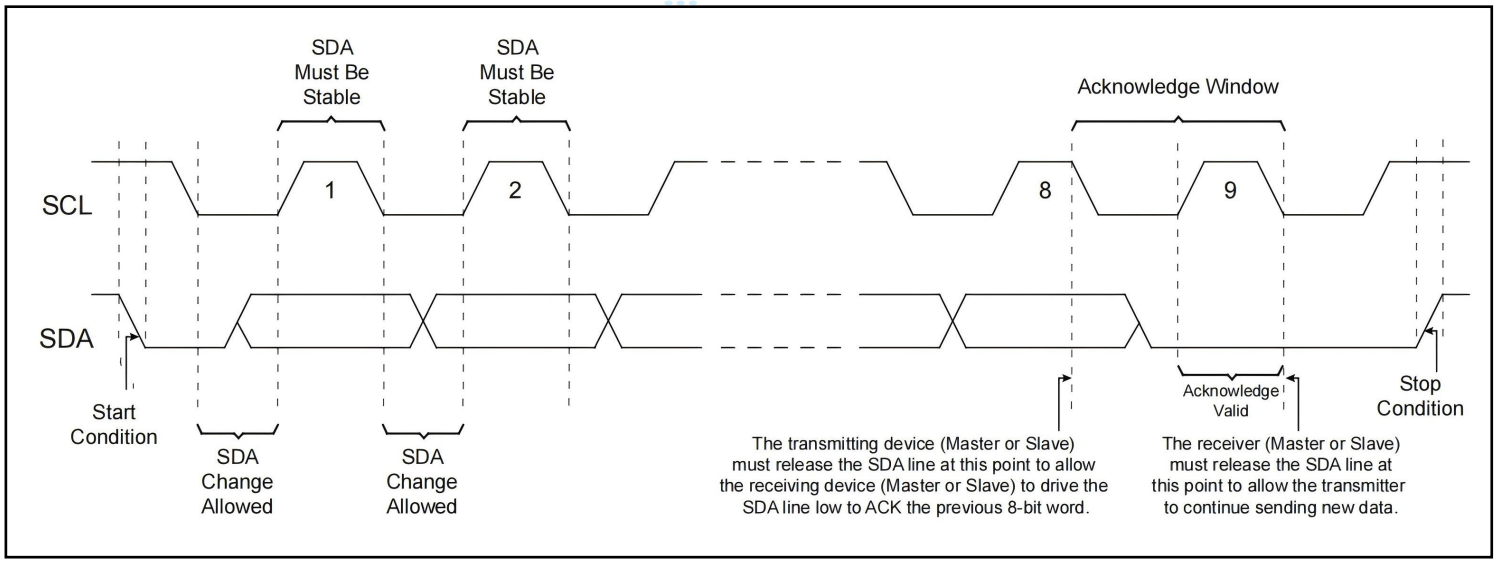


Figure 2.Start Condition, Data Transitions, Stop Condition, and Acknowledge

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Standby Mode

The AT24C16D features a low-power Standby mode which is enabled when any one of the following occurs:

● A valid power-up sequence is performed (see Power-Up Requirements and Reset Behavior).

● A Stop condition is received by the device unless it initiates an internal write cycle (see Write Operations).

● At the completion of an internal write cycle (see Write Operations).

● An unsuccessful match of the device type identifier or hardware address in the device address byte occurs (see Device Addressing).

● The bus master does not ACK the receipt of data read out from the device; instead it sends a NACK response. (see Read Operations)

Software Reset

After an interruption in protocol, power loss, or system Reset, any 2-wire device can be protocol reset by clocking SCL until SDA is released by the EEPROM and goes high. The number of clock cycles until SDA is released by the EEPROM will vary. The software Reset sequence should not take more than nine dummy clock cycles. Once the software Reset sequence is complete, new protocol can be sent to the device by sending a Start condition followed by the protocol. Refer to Figure 3 for an illustration.

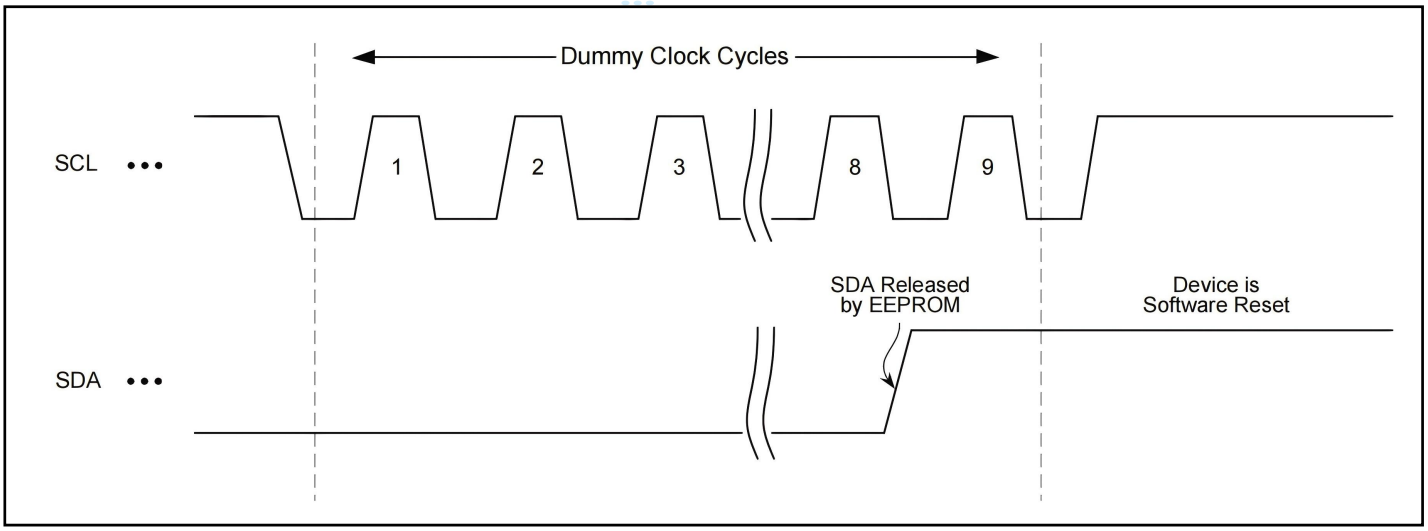


Figure 3.Software Reset

In the event that the device is still non-responsive or remains active on the SDA bus, a power cycle must be used to reset the device (see Power-Up Requirements and Reset Behavior)

Memory Organization

The AT24C16D is internally organized as 128 pages of 16 bytes each.

Device Addressing

Accessing the device requires an 8-bit device address word following a Start condition to enable the device for a read or write operation. Since multiple slave devices can reside on the serial bus, each slave device must have its own unique address so the master can access each device independently.

The Most Significant four bits of the device address word is referred to as the device type identifier. The device type identifier ‘ 1010 ’ (Ah) is required in bits 7 through 4 of the device address byte (see Device Address Byte).

Following the 4-bit device type identifier in the bit 3, bit 2, and bit 1 position of the device address byte are bits A10, A9 and A8 which are the three Most Significant bits of the memory array word address. The eighth bit (bit 0) of the device address byte is the read/write operation select bit. A read operation is initiated if this bit is high, and a write operation is initiated if this bit is low. Refer to Device Address Byte these bit positions.

Upon the successful comparison of the device address byte, the EEPROM will return an ACK. If a valid comparison is not made, the device will NACK and return to a standby state.

Device Address Byte

Package	Device Type Identifier				Most Significant Bits of the Word Address			Read/Write
	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
All Package Types	1	0	1	0	A10	A9	A8	RN

For all operations except the Current Address Read, a word address byte must be transmitted to the device immediately following the device address byte. The word address byte consists of the remaining eight bits of the 11-bit memory array word address, and is used to specify which byte location in the EEPROM to start reading or writing. Refer to Word Address Byte to review these bit positions.

Word Address Byte

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
A7	A6	A5	A4	A3	A2	A1	A0

Write Operations

All write operations for the AT24C16D begin with the master sending a Start condition, followed by a device address byte with the R/W bit set to ‘ 0 ’, and then by the word address byte. The data value(s) to be written to the device immediately follow the word address byte.

Byte Write

The AT24C16D supports the writing of a single 8-bit byte. Selecting a data word in the AT24C16D requires an 11-bit word address.
Upon receipt of the proper device address and word address bytes, the EEPROM will send an Acknowledge. The device will then be ready to receive the first 8-bit data word. Following receipt of the 8-bit data word, the EEPROM will respond with an ACK. The addressing device, such as a bus master, must then terminate the write operation with a Stop condition. At that time, the EEPROM will enter an internally self-timed write cycle which will be completed within t_{WR} while the data word is being programmed into the nonvolatile EEPROM. All inputs are disabled during this write cycle, and the EEPROM will not respond until the write is complete.

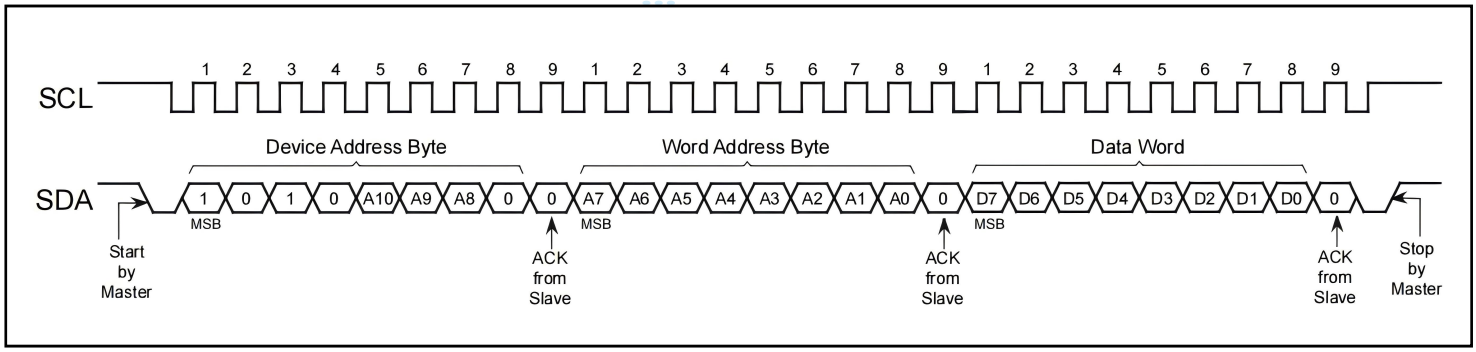


Figure 4.Byte Write

Page Write

A page write operation allows up to 16 bytes to be written in the same write cycle, provided all bytes are in the same row of the memory array (where address bits A10 through A4 are the same). Partial page writes of less than 16 bytes are also allowed.
A page write is initiated the same way as a byte write, but the bus master does not send a Stop condition after the first data word is clocked in. Instead, after the EEPROM acknowledges receipt of the first data word, the bus master can transmit up to fifteen additional data words. The EEPROM will respond with an ACK after each data word is received. Once all data to be written has been sent to the device, the bus master must issue a Stop condition (see Figure 5) at which time the internally self-timed write cycle will begin.
The lower four bits of the word address are internally incremented following the receipt of each data word. The higher order address bits are not incremented and retain the memory page row location. Page write operations are limited to writing bytes within a single physical page, regardless of the number of bytes actually being written. When the incremented word address reaches the page boundary, the address counter will roll-over to the beginning of the same page. Nevertheless, creating a roll-over event should be avoided as previously loaded data in the page could become unintentionally altered.

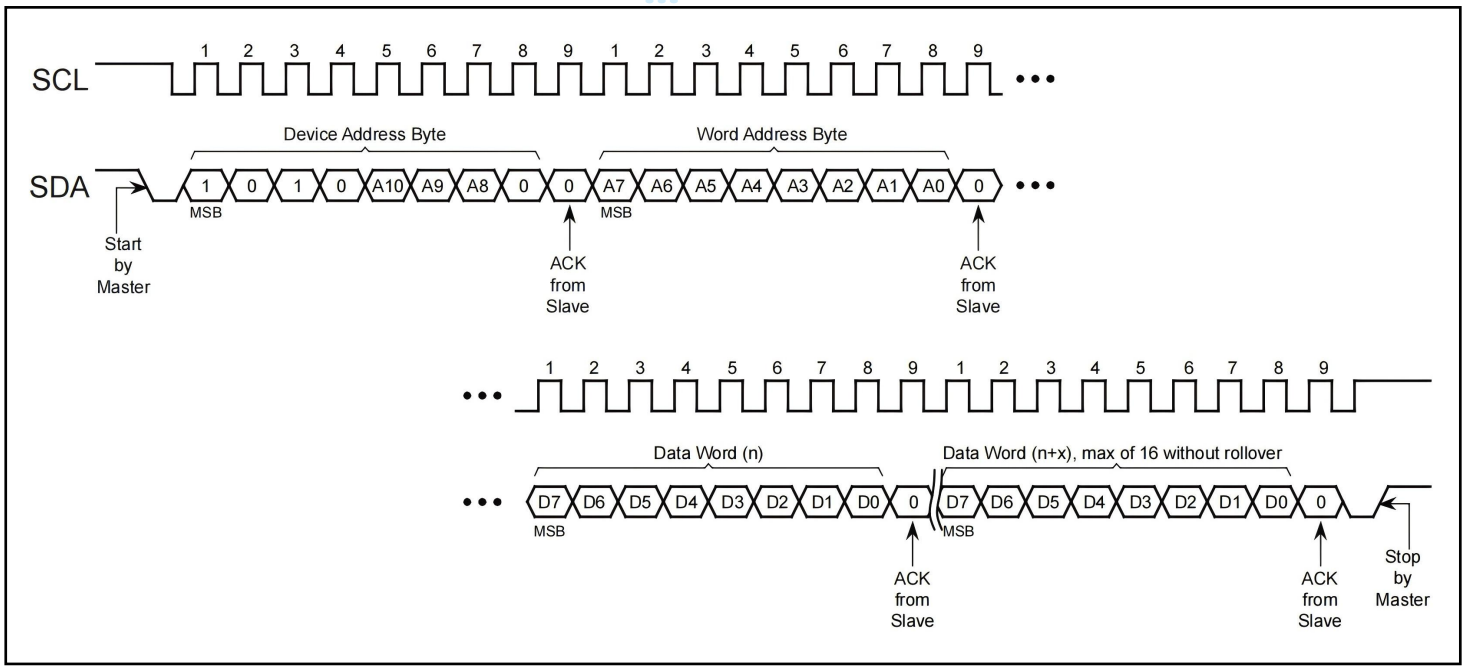


Figure 5. Page Write

Acknowledge Polling

An Acknowledge Polling routine can be implemented to optimize time-sensitive applications that would prefer not to wait the fixed maximum write cycle time (tWR). This method allows the application to know immediately when the Serial EEPROM write cycle has completed, so a subsequent operation can be started.

Once the internally self-timed write cycle has started, an Acknowledge Polling routine can be initiated. This involves repeatedly sending a Start condition followed by a valid device address byte with the R/W bit set set at logic ‘ 0 ’. The device will not respond with an ACK while the write cycle is ongoing. Once the internal write cycle has completed, the EEPROM will respond with an ACK, allowing a new read or write operation to be immediately initiated. A flowchart has been included below in Figure 6 to better illustrate this technique.

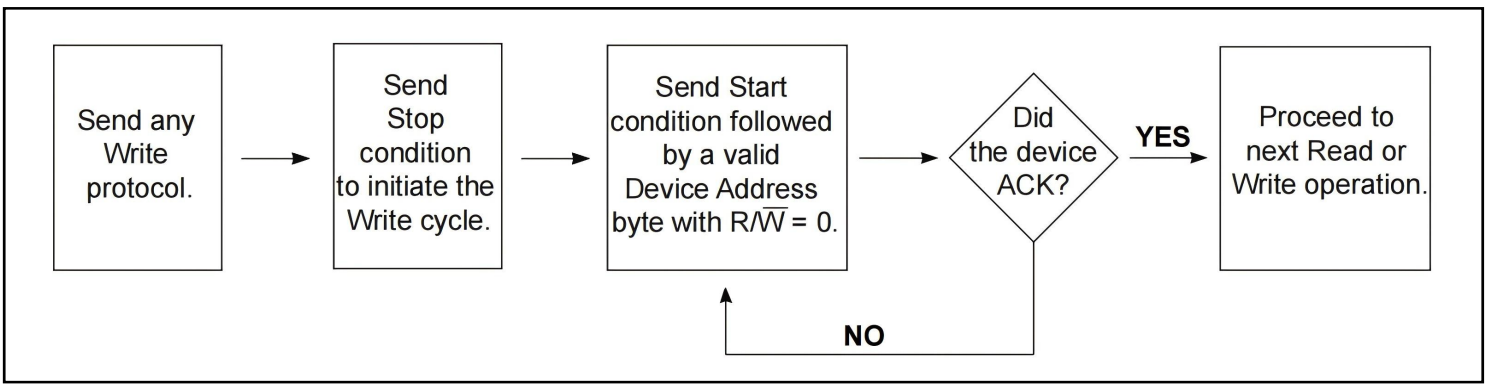


Figure 6.Acknowledge Polling Flow Chart

Write Cycle Timing

The length of the self-timed write cycle (t_{WR}) is defined as the amount of time from the Stop condition that begins the internal write operation to the Start condition of the first device address byte sent to the AT24C16D that it subsequently responds to with an ACK. Figure 7 has been included to show this measurement. During the internally self-timed write cycle, any attempts to read from or write to the memory array will not be processed.

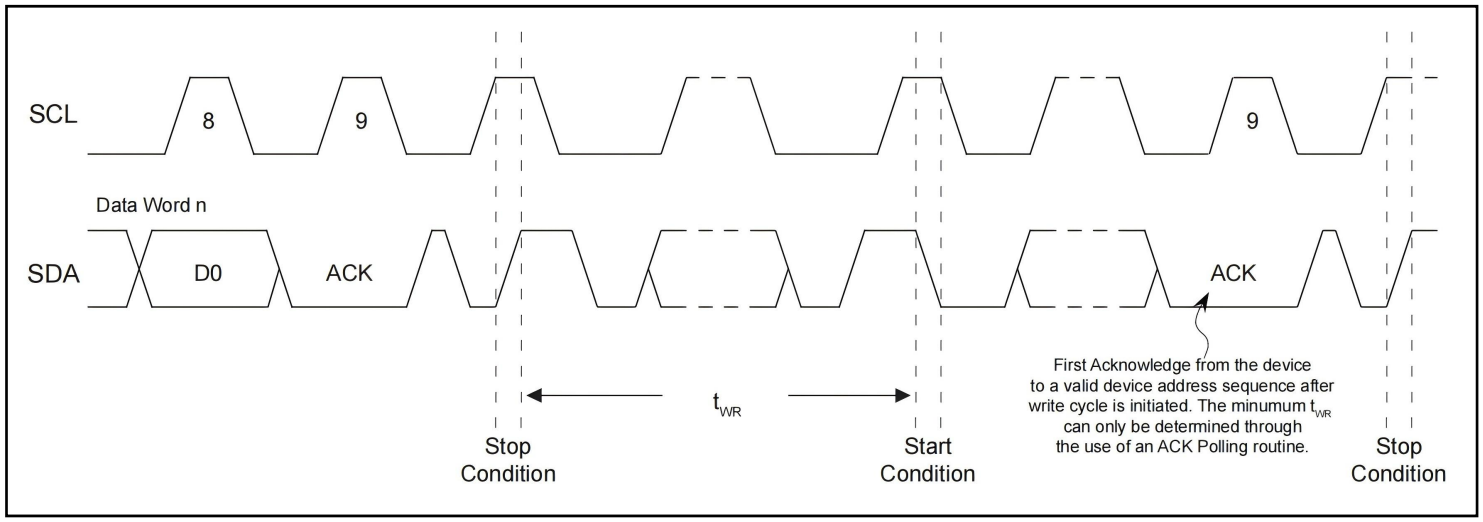


Figure 7.Write Cycle Timing

Write Protection

The AT24C16D utilizes a hardware data protection scheme that allows the user to write-protect the entire memory contents when the WP pin is at V_{CC} (or a valid V_{IH}). No write protection will be set if the WP pin is at GND or left floating.

AT24C16D Write-Protect Behavior

WP Pin Voltage	Part of the Array Protected
V_{CC}	Full Array
GND	None-Write Protection Not Enabled

The status of the WP pin is sampled at the Stop condition for every Byte Write or Page Write command prior to the start of an internally self-timed write operation. Changing the WP pin state after the Stop condition has been sent will not alter or interrupt the execution of the write cycle. The WP pin state must be valid with respect to the associated setup ($t_{SU:WP}$) and hold ($t_{HD:WP}$) timing as shown in Figure 8 below. The WP setup time is the amount of time that the WP state must be stable before the Stop condition is issued. The WP hold time is the amount of time after the Stop condition that the WP must remain stable.
If an attempt is made to write to the device while the WP pin has been asserted, the device will acknowledge the device address, word address, and data bytes but no write cycle will occur when the Stop condition is issued, and the device will immediately be ready to accept a new Read or Write command.

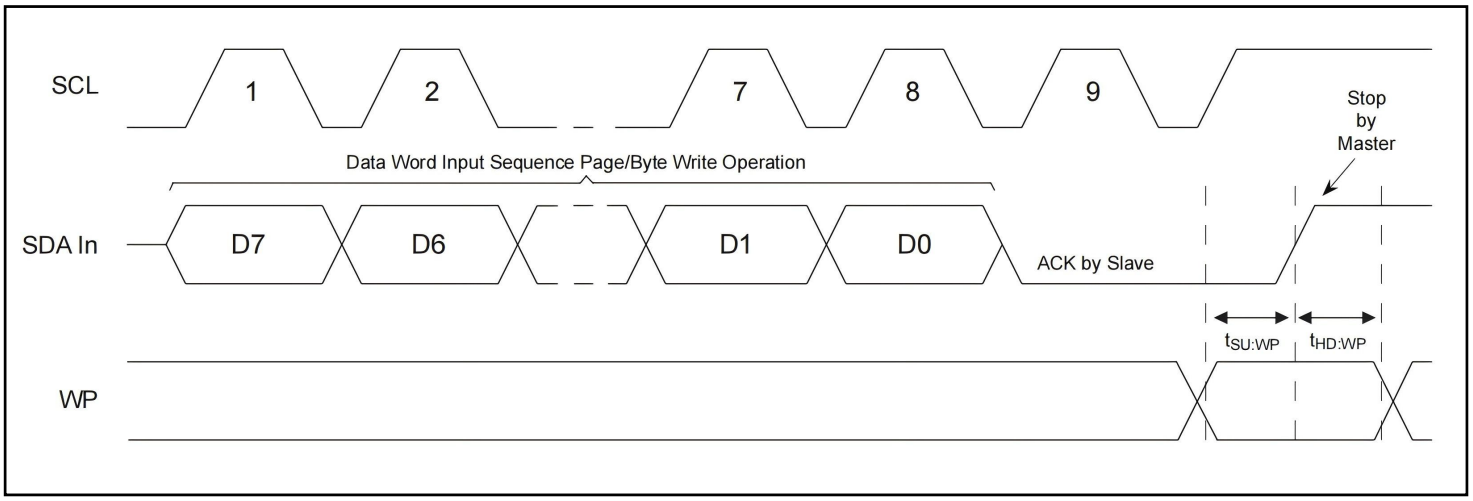


Figure 8.Write-Protect Setup and Hold Timing

Read Operations

Read operations are initiated the same way as write operations with the exception that the Read/ Write Select bit in the device address word must be a logic ‘ 1 ’. There are three read operations:

- Current Address Read
- Random Address Read
- Sequential Read

Current Address Read

The internal data word address counter maintains the last address accessed during the last read or write operation, incremented by one. This address stays valid between operations as long as the V_{CC} is maintained to the part. The address roll-over during read is from the last byte of the last page to the first byte of the first page of the memory.

A Current Address Read operation will output data according to the location of the internal data word address counter. This is initiated with a Start condition, followed by a valid device address byte with the R/W bit set to logic ’1’. The device will ACK this sequence and the current address data word is serially clocked out on the SDA line. All types of read operations will be terminated if the bus master does not respond with an ACK (it NACKs) during the ninth clock cycle, which will force the device into Standby mode. After the NACK response, the master may send a Stop condition to complete the protocol, or it can send a Start condition to begin the next sequence.

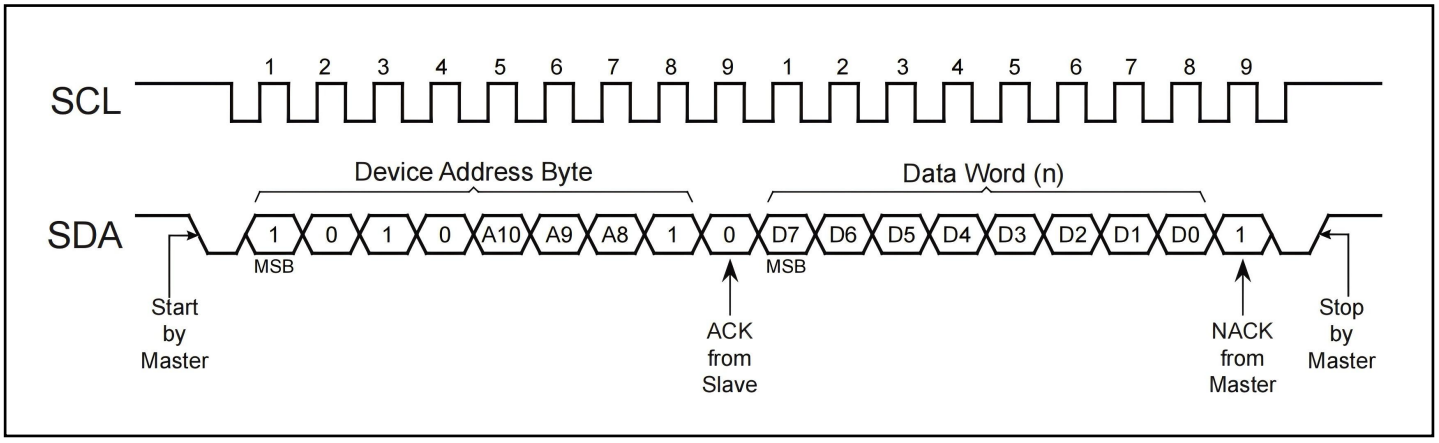


Figure 9.Current Address Read

Random Read

A Random Read begins in the same way as a byte write operation does to load in a new data word address. This is known as a “ dummy write ” sequence; however, the data byte and the Stop condition of the byte write must be omitted to prevent the part from entering an internal write cycle. Once the device address and word address are clocked in and acknowledged by the EEPROM, the bus master must generate another Start condition. The bus master now initiates a Current Address Read by sending a Start condition, followed by a valid device address byte with the R/W bit set to logic ’1’. In this second device address byte, the bit positions usually reserved for the Most Significant bits of the word address (bit 3, 2, and 1) are "don’t care" bits since the address that will be read from is determined only by what was sent in the dummy write portion of the sequence. The EEPROM will ACK the device address and serially clock out the data word on the SDA line. All types of read operations will be terminated if the bus master does not respond with an ACK (it NACKs) during the ninth clock cycle, which will force the device into Standby mode. After the NACK response, the master may send a Stop condition to complete the protocol, or it can send a Start condition to begin the next sequence.

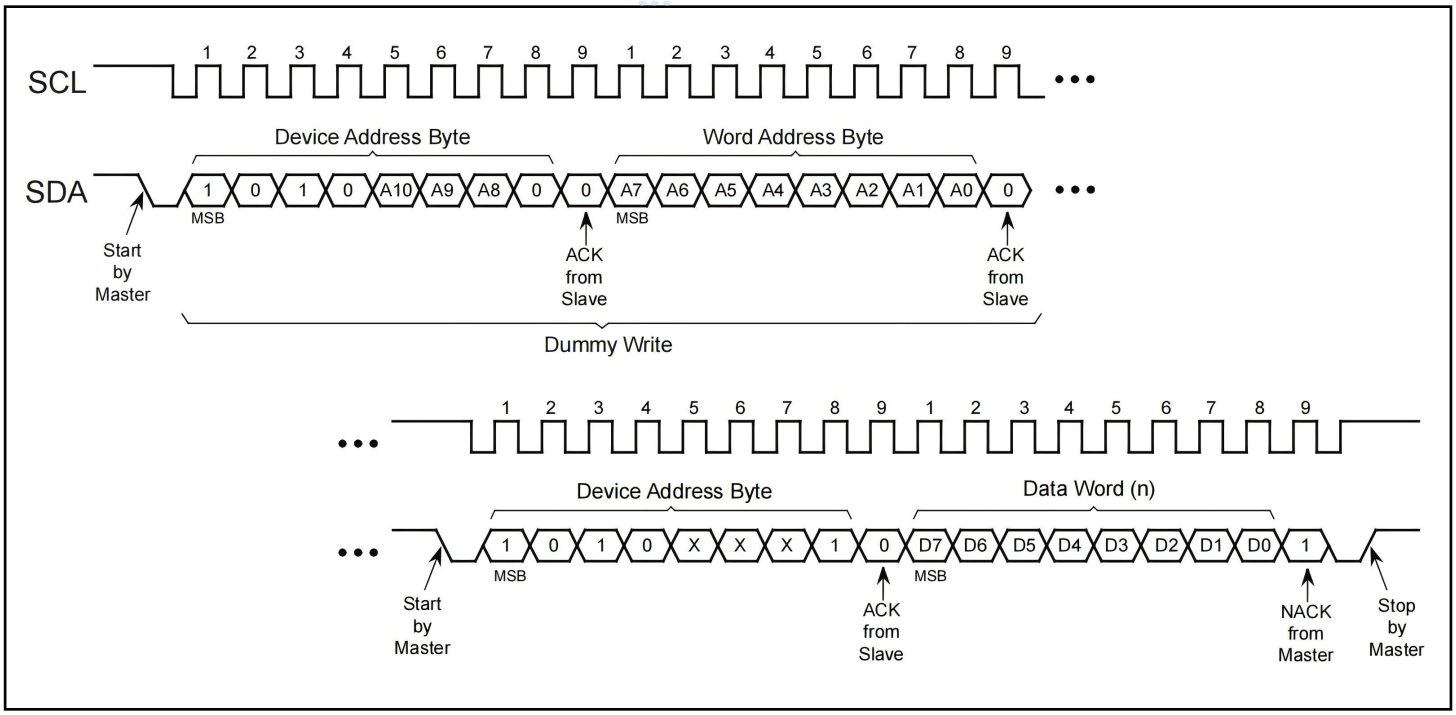


Figure 10.Random Read

Sequential Read

Sequential Reads are initiated by either a Current Address Read or a Random Read. After the bus master receives a data word, it responds with an acknowledge. As long as the EEPROM receives an ACK, it will continue to increment the word address and serially clock out sequential data words. When the maximum memory address is reached, the data word address will roll-over and the sequential read will continue from the beginning of the memory array. All types of read operations will be terminated if the bus master does not respond with an ACK (it NACKs) during the ninth clock cycle, which will force the device into Standby mode. After the NACK response, the master may send a Stop condition to complete the protocol, or it can send a Start condition to begin the next sequence.

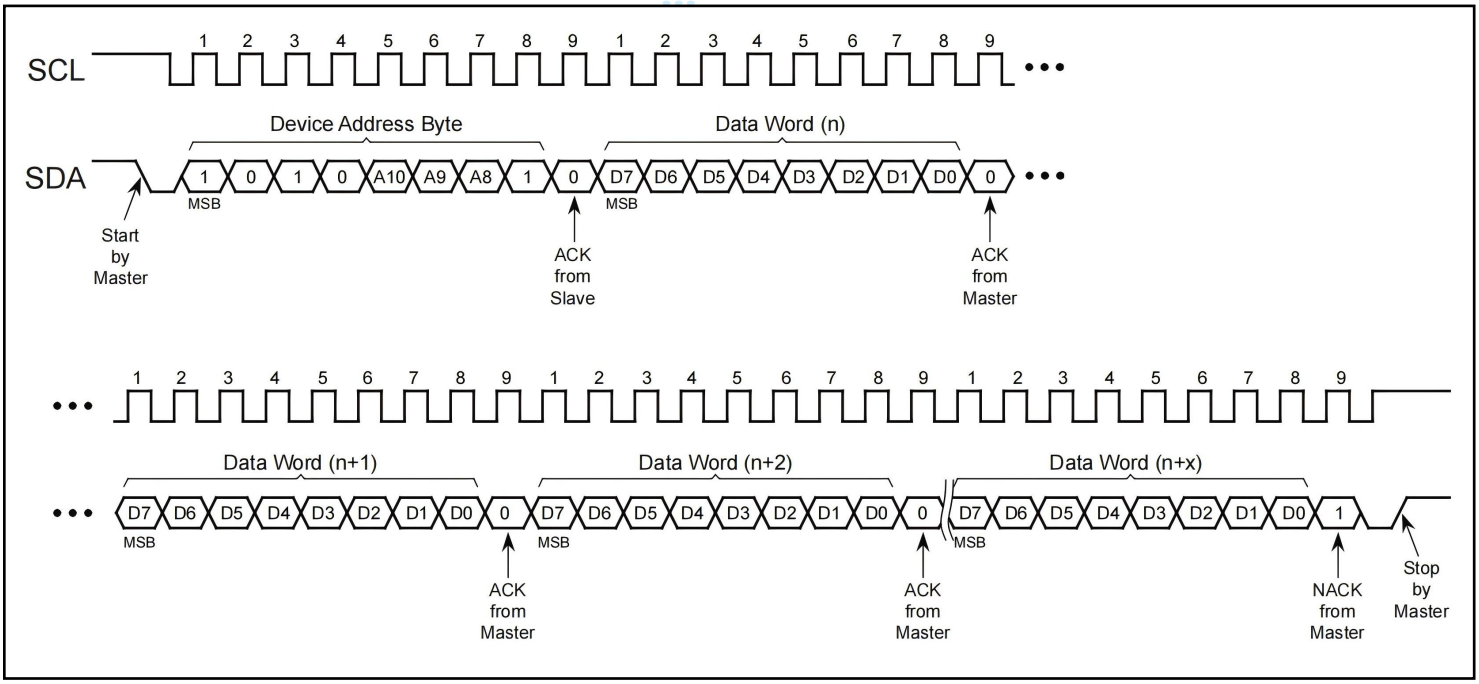


Figure 11.Sequential Read

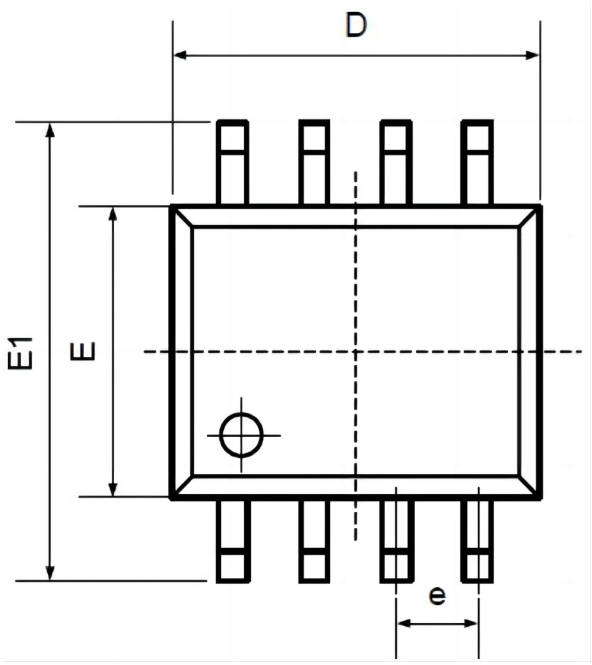
Order information

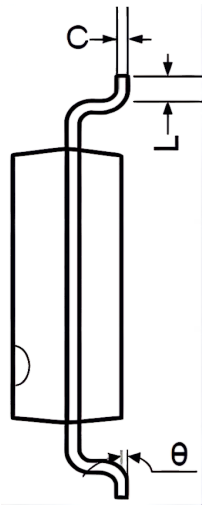
Order Number	Package	Package Quantity	Marking On The park	Temperature
AT24C16D-SSHM-T-TUDI	SOP8	Tape,Reel,4000	16DM	-40℃ to 85℃
AT24C16D-XHM-T-TUDI	TSSOP8	Tape,Reel,4000	24C16D	
			16DM	
AT24C16D-PUM-TUDI	DIP8	Tube,50,A box of 2000	24C16D	
			16DM	
AT24C16D-STUM-T-TUDI	SOT23	Tape,Reel,3000	24C16D	
			ADMU	

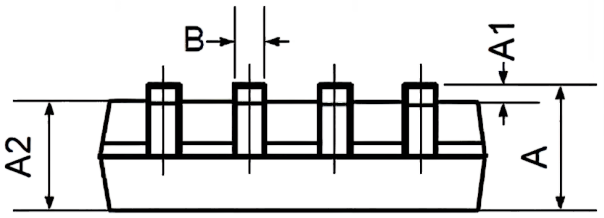
Revision history

	Date	Revision	Page
V1.0	2022/6	New	1-18
V1.1	2025/3	Update model and PDF template	1-27

Package SOP8

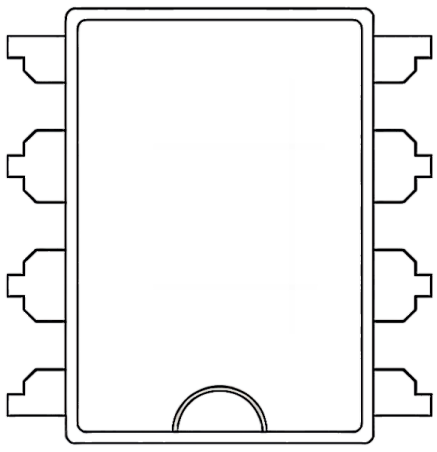


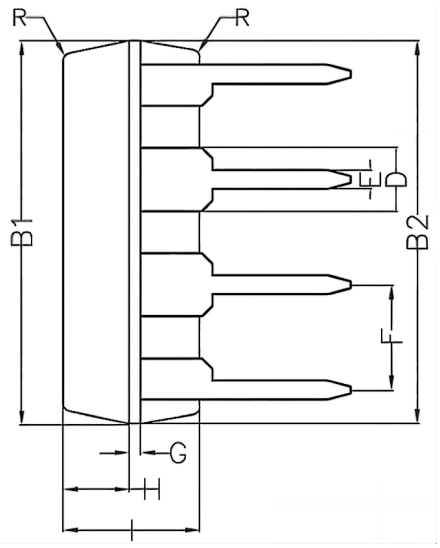


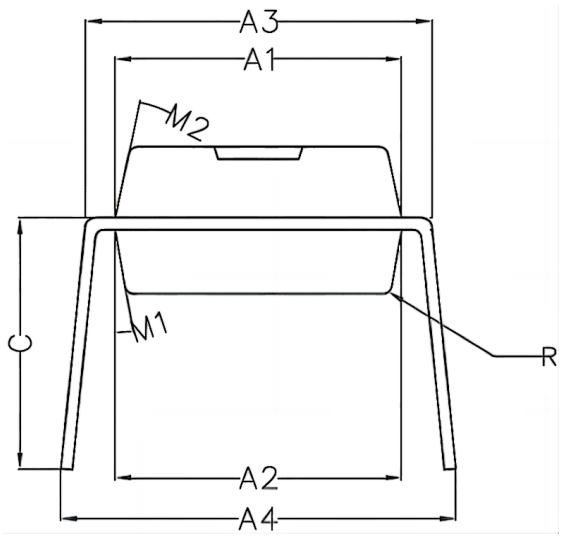


Symbol	Dimensions In Millimeters		Dimensions In Inches	
	Min	Max	Min	Max
A	1.350	1.750	0.053	0.069
A1	0.100	0.250	0.004	0.010
A2	1.350	1.550	0.053	0.061
B	0.330	0.510	0.013	0.020
C	0.190	0.250	0.007	0.010
D	4.780	5.000	0.188	0.197
E	3.800	4.000	0.150	0.157
E1	5.800	6.300	0.228	0.248
e	1.270TYP		0.050TYP	
L	0.400	1.270	0.016	0.050
θ	0°	8°	0°	8°

Package DIP8

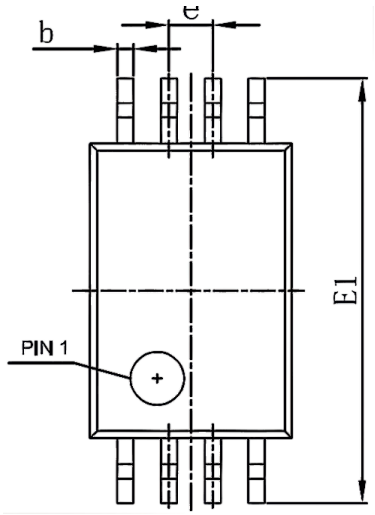


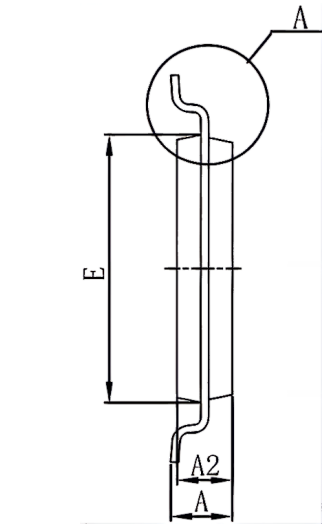


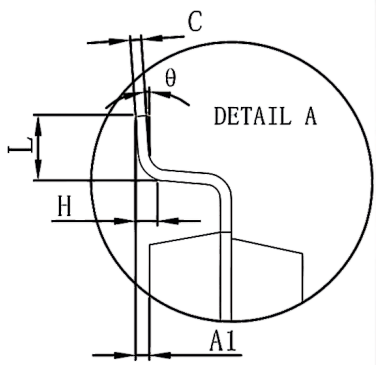


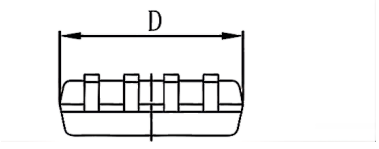
Symbol	Min	Non	Max
A1	6.28	6.33	6.38
A2	6.33	6.38	6.43
A3	7.52	7.62	7.72
A4	7.80	8.40	9.00
B1	9.15	9.20	9.25
B2	9.20	9.25	9.30
C		5.57	
D		1.52	
E	0.43	0.45	0.47
F		2.54	
G		0.25	
H	1.54	1.59	1.64
工	3.22	3.27	3.32
R		0.20	
M1	9°	10°	11°
M2	11°	12°	13°

Package TSSOP8



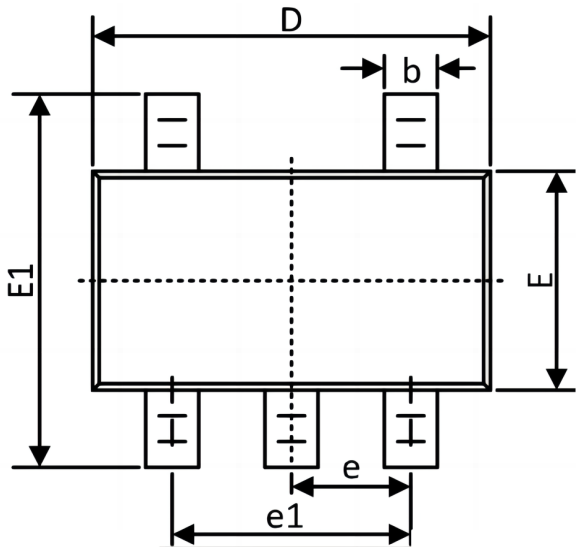


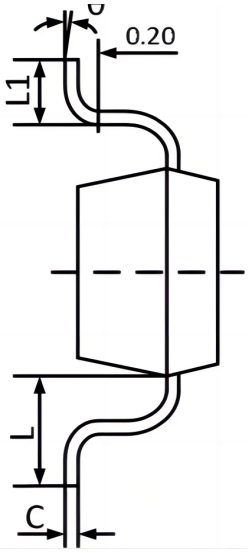


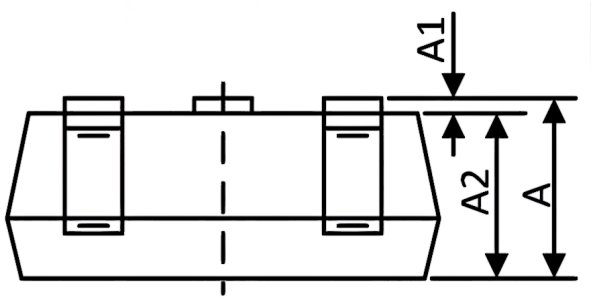


Symbol	Dimensions In Millimeters		Dimensions In Inches	
	Min	Max	Min	Max
D	2.900	3.100	0.114	0.122
E	4.300	4.500	0.169	0.177
b	0.190	0.300	0.007	0.012
C	0.090	0.200	0.004	0.008
E1	6.250	6.550	0.246	0.258
A		1.200		0.047
A2	0.800	1.000	0.031	0.039
A1	0.050	0.150	0.002	0.006
e	0.65(BSC)		0.026(BSC)	
L	0.500	0.700	0.020	0.028
H	0.25(TYP)		0.01(TYP)	
θ	1°		1°	

Package SOT23-5







Symbol	Dimensions In Millimeters		Dimensions In Inches	
	MIN	MAX	MIN	MAX
A	1.050	1.250	0.041	0.049
A1	0.000	0.100	0.000	0.004
A2	1.050	1.150	0.041	0.045
b	0.300	0.400	0.012	0.016
C	0.100	0.200	0.004	0.008
D	2.820	3.020	0.111	0.119
E	1.500	1.700	0.059	0.067
E1	2.650	2.950	0.104	0.116
e	0.950TYP		0.037TYP	
e1	1.800	2.000	0.071	0.079
L	0.700REF		0.028REF	
L1	0.300	0.600	0.012	0.024
θ	0°	8°	0°	8°

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